



Overview

Optimization-Based Data Analysis

http://www.cims.nyu.edu/~cfgranda/pages/OBDA_spring16

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1/25/2016

Sparsity

Denoising

Regression

Inverse problems

Low-rank models

Matrix completion

Low rank + sparse model

Nonnegative matrix factorization

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Denoising

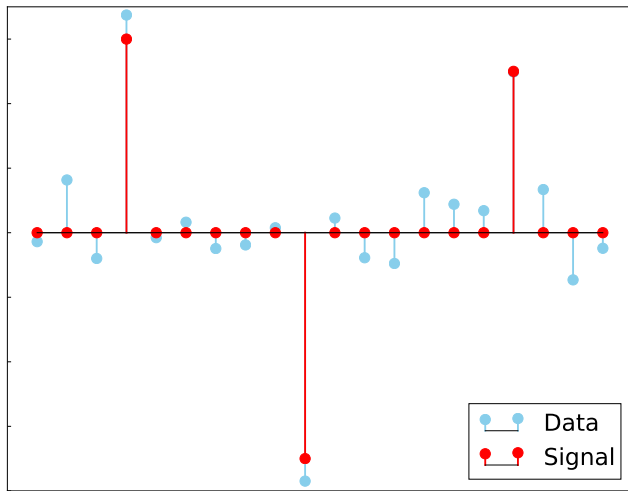
Additive noise model

$$\text{data} = \text{signal} + \text{noise}$$

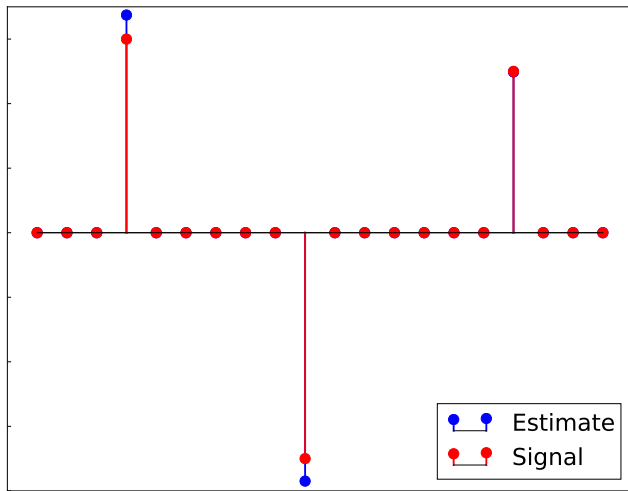
Hard thresholding

$$\mathcal{H}_\eta(x)_i := \begin{cases} x_i & \text{if } |x_i| > \eta, \\ 0 & \text{otherwise} \end{cases}$$

Denoising via thresholding



Denoising via thresholding

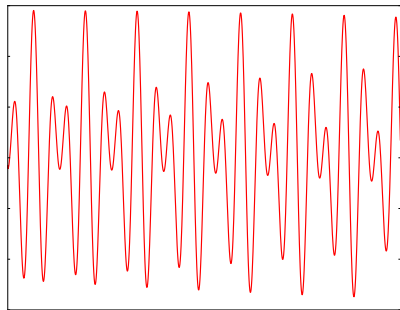


Sparsifying transforms

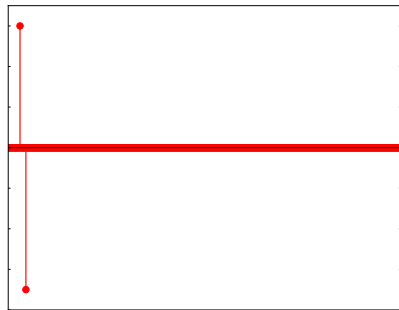
$$x = Dc = \sum_{i=1}^n D_i c_i,$$

Discrete cosine transform

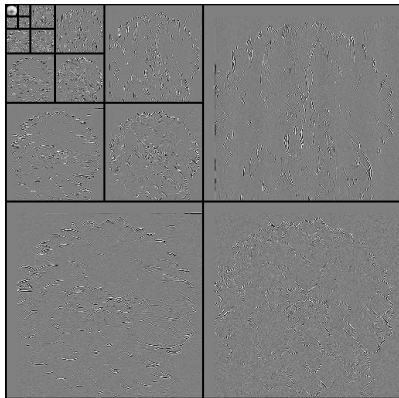
Signal



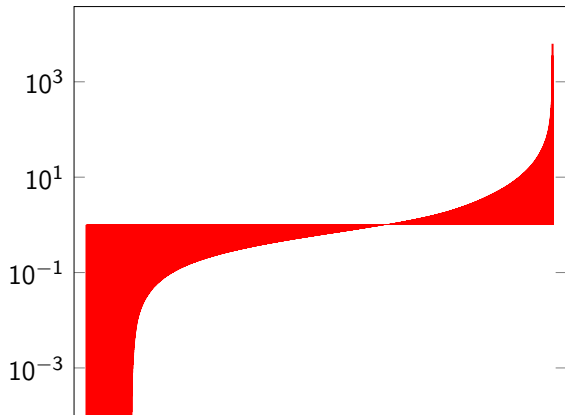
DCT coefficients



Wavelets



Sorted wavelet coefficients



Denoising via thresholding in a basis

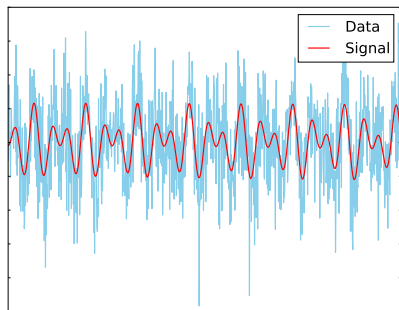
$$x = Bc$$

$$y = Bc + z$$

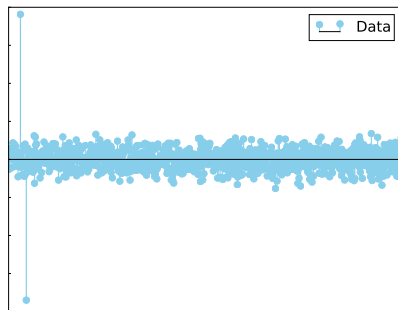
$$\hat{c} = \mathcal{H}_\eta(B^{-1}y)$$

$$\hat{y} = B\hat{c}$$

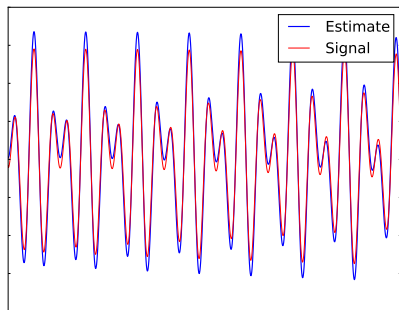
Denosing via thresholding in a DCT basis



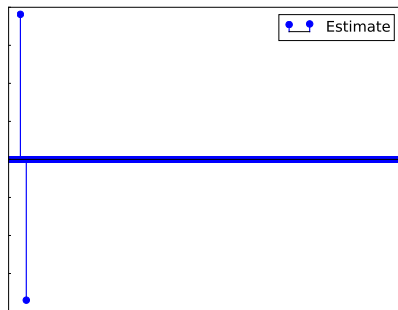
DCT coefficients



Denoising via thresholding in a DCT basis

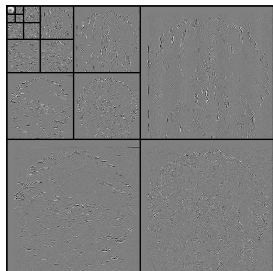


DCT coefficients

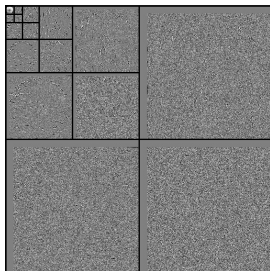


Denoising via thresholding in a wavelet basis

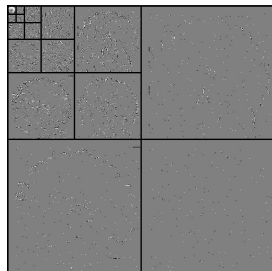
Original



Noisy



Estimate



Denoising via thresholding in a wavelet basis

Original



Noisy



Estimate



Denoising via thresholding in a wavelet basis

Original



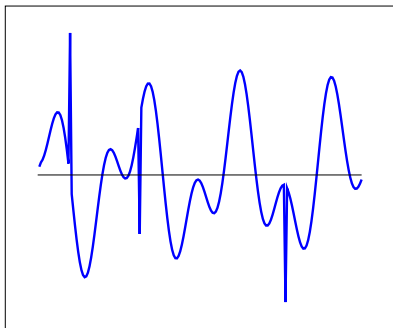
Noisy



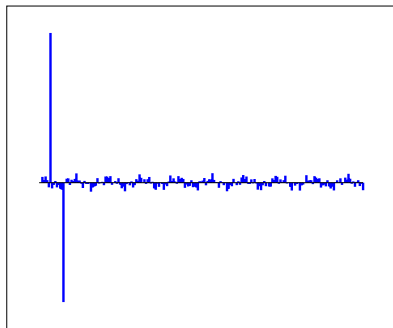
Estimate



Overcomplete dictionary



DCT coefficients



Overcomplete dictionary

$$x = Dc = [A \ B] \begin{bmatrix} a \\ b \end{bmatrix} = Aa + Bb$$

Sparsity estimation

First idea:

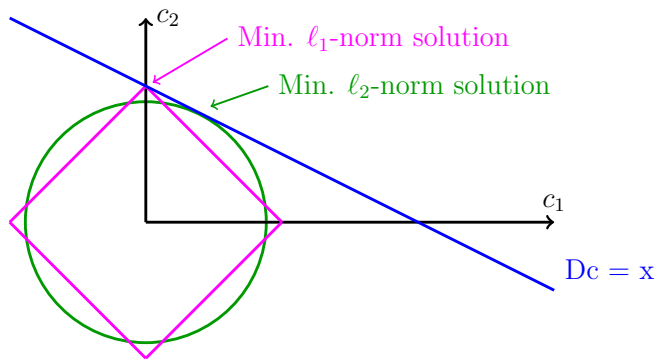
$$\min_{\tilde{c} \in \mathbb{R}^m} \|\tilde{c}\|_0 \quad \text{such that } x = Dc$$

Computationally intractable!

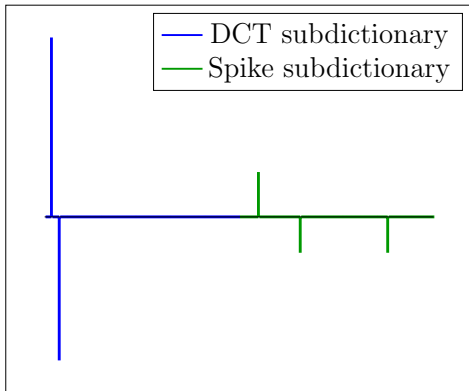
Tractable alternative:

$$\min_{\tilde{c} \in \mathbb{R}^m} \|\tilde{c}\|_1 \quad \text{such that } x = Dc$$

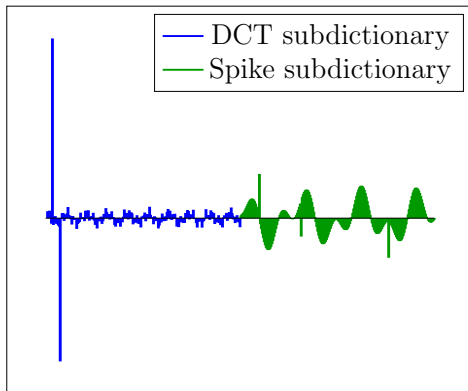
Geometric intuition



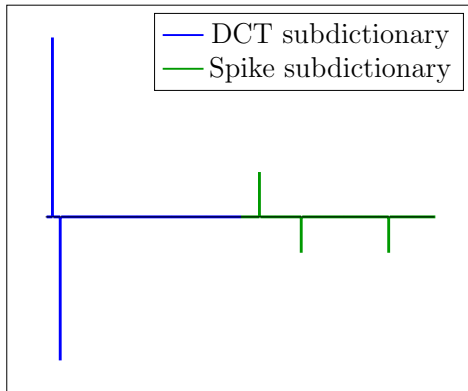
Sparsity estimation



Minimum ℓ_2 -norm coefficients



Minimum ℓ_1 -norm coefficients

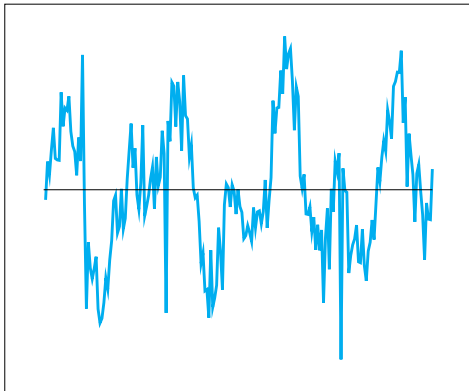


Denoising via ℓ_1 -norm regularized least squares

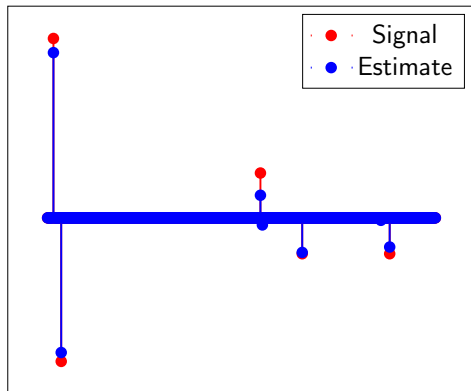
$$\hat{c} = \arg \min_{\tilde{c} \in \mathbb{R}^m} \|x - D\tilde{c}\|_2^2 + \lambda \|\tilde{c}\|_1$$

$$\hat{x} = D\hat{c}$$

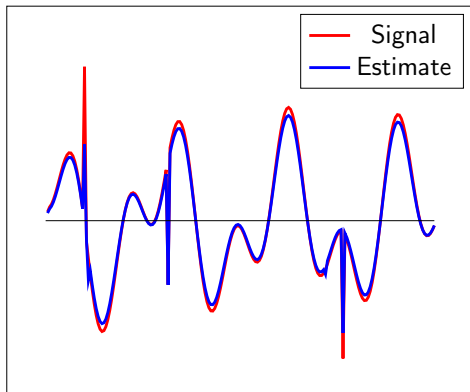
Denoising via ℓ_1 -norm regularized least squares



Denoising via ℓ_1 -norm regularized least squares



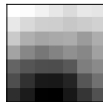
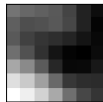
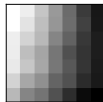
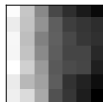
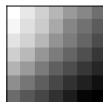
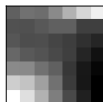
Denoising via ℓ_1 -norm regularized least squares



Learning the dictionary

$$\min_{\tilde{C} \in \mathbb{R}^{m \times k}} \left\| X - \tilde{D}\tilde{C} \right\|_F^2 + \lambda \|\tilde{C}\|_1 \quad \text{such that} \quad \left\| \tilde{D}_i \right\|_2 = 1, \quad 1 \leq i \leq m$$

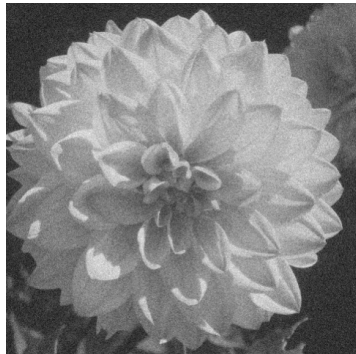
Dictionary learning



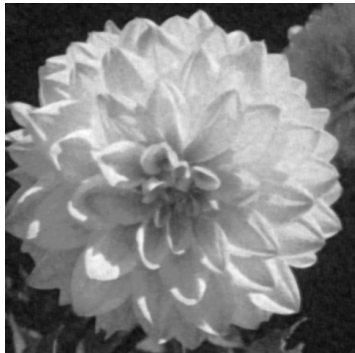
Denoising via dictionary learning



Denoising via dictionary learning



Denoising via dictionary learning



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Low-rank models

Matrix completion

Low rank + sparse model

Nonnegative matrix factorization

Linear regression

$$y_i \approx \sum_{j=1}^p \theta_j X_{ij}, \quad 1 \leq i \leq n$$

$$y \approx X\theta$$

Sparse regression

Least squares

$$\hat{\theta}_{\text{ls}} := \arg \min_{\tilde{\theta} \in \mathbb{R}^n} \left\| y - X\tilde{\theta} \right\|_2$$

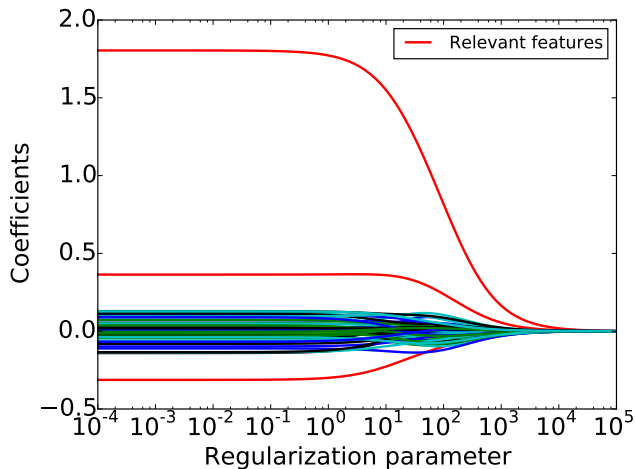
Ridge regression (aka Tikhonov regularization)

$$\hat{\theta}_{\text{ridge}} := \arg \min_{\tilde{\theta} \in \mathbb{R}^n} \left\| y - X\tilde{\theta} \right\|_2^2 + \lambda \left\| \tilde{\theta} \right\|_2^2$$

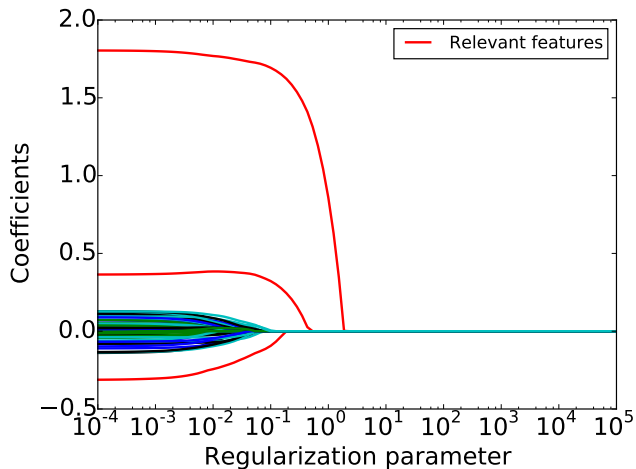
The lasso

$$\hat{\theta}_{\text{lasso}} := \arg \min_{\tilde{\theta} \in \mathbb{R}^n} \left\| y - X\tilde{\theta} \right\|_2^2 + \lambda \left\| \tilde{\theta} \right\|_1$$

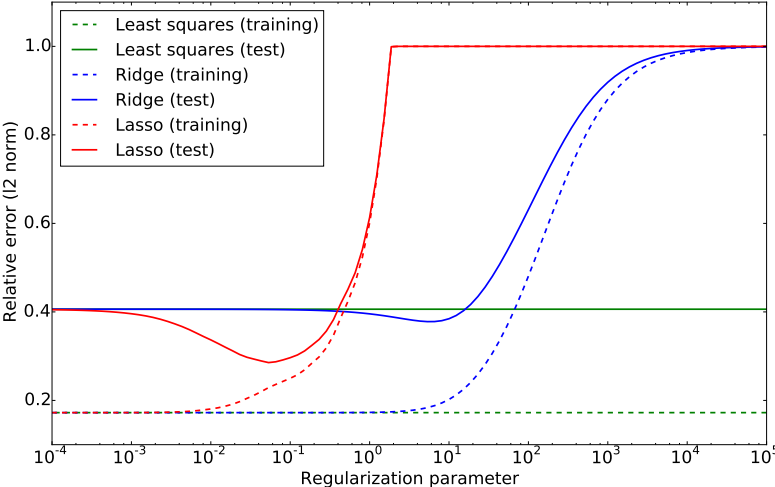
Ridge-regression coefficients



Lasso coefficients



Results



Sparsity

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Low-rank models

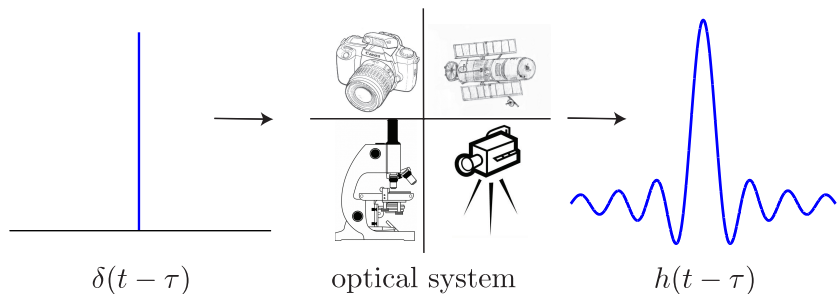
Matrix completion

Low rank + sparse model

Nonnegative matrix factorization

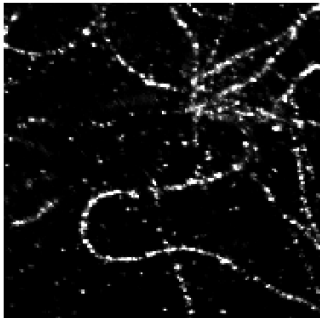
Limits of resolution in imaging

The resolving power of lenses, however perfect, is limited (Lord Rayleigh)



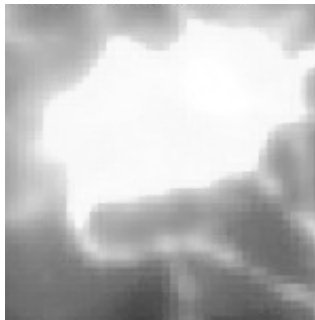
Diffraction imposes a **fundamental limit** on the resolution of optical systems

Fluorescence microscopy



Point sources

Data

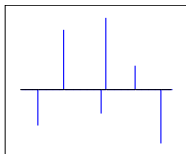


Low-pass blur

(Figures courtesy of V. Morgenshtern)

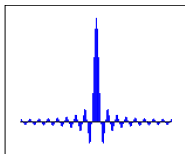
Sensing model for super-resolution

Point sources



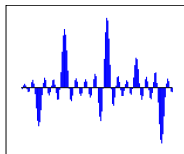
*

Point-spread function

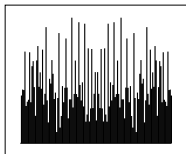


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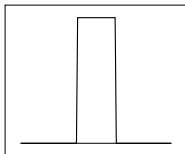
Data



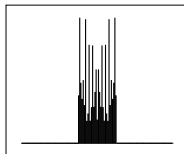
Spectrum



×



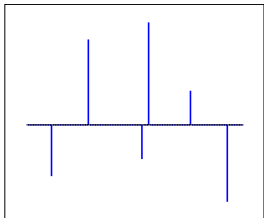
=



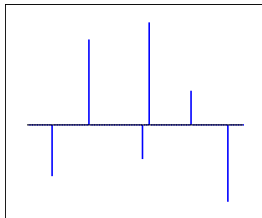
Minimum ℓ_1 -norm estimate

$$\begin{array}{ll} \textit{minimize} & \|\textit{estimate}\|_1 \\ \textit{subject to} & \textit{estimate} * \textit{psf} = \textit{data} \end{array}$$

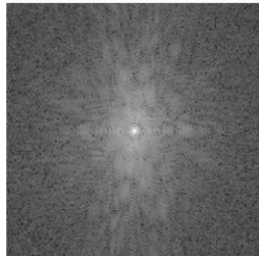
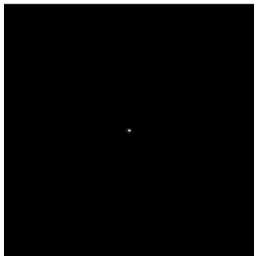
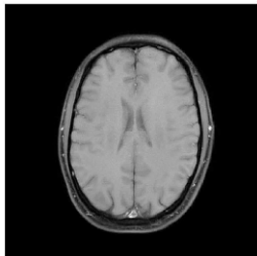
Point sources



Estimate



Magnetic resonance imaging



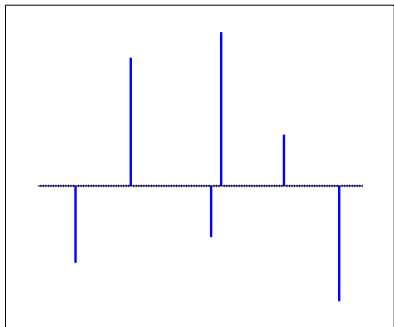
Magnetic resonance imaging

- ▶ **Data**: Samples from spectrum
- ▶ **Problem**: Sampling is time consuming (patients get annoyed, kids move during data acquisition)
- ▶ Images are **compressible** (\approx sparse)
- ▶ Can we recover compressible signals from less data?

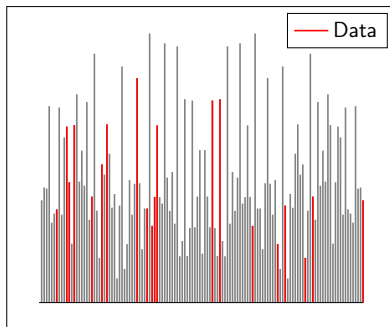
Compressed sensing

1. Undersample the spectrum **randomly**

Signal



Spectrum



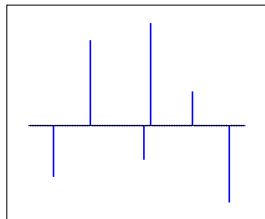
Compressed sensing

2. Solve the optimization problem

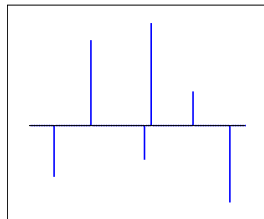
minimize $\|\text{estimate}\|_1$

subject to frequency samples of estimate = data

Signal

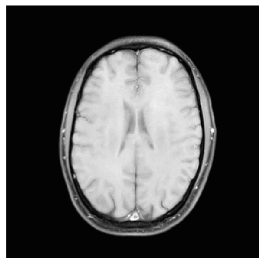


Estimate

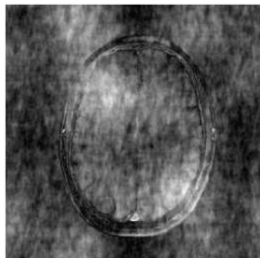


Compressed sensing in MRI

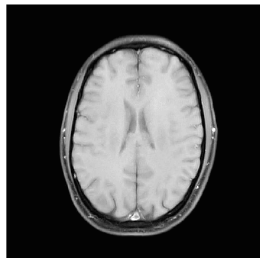
Original



Min. l_2 -norm
estimate



Min. l_1 -norm
estimate



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Netflix Prize



Collaborative filtering

	Bob	Molly	Mary	Larry	
$A :=$	1	1	5	4	The Dark Knight
	2	1	4	5	Spiderman 3
	4	5	2	1	Love Actually
	5	4	2	1	Bridget Jones's Diary
	4	5	1	2	Pretty Woman
	1	2	5	5	Superman 2

Centering

$$\mu := \frac{1}{n} \sum_{i=1}^m \sum_{j=1}^n A_{ij},$$

$$\bar{A} := \begin{bmatrix} \mu & \mu & \cdots & \mu \\ \mu & \mu & \cdots & \mu \\ \cdots & \cdots & \cdots & \cdots \\ \mu & \mu & \cdots & \mu \end{bmatrix}$$

SVD

$$A - \bar{A} = USV^T = U \begin{bmatrix} 7.79 & 0 & 0 & 0 \\ 0 & 1.62 & 0 & 0 \\ 0 & 0 & 1.55 & 0 \\ 0 & 0 & 0 & 0.62 \end{bmatrix} V^T$$

First left singular vector

$$U_1 = \begin{pmatrix} \text{D. Knight} & \text{Sp. 3} & \text{Love Act.} & \text{B.J.'s Diary} & \text{P. Woman} & \text{Sup. 2} \\ -0.45 & -0.39 & 0.39 & 0.39 & 0.39 & -0.45 \end{pmatrix}$$

First right singular vector

$$V_1 = \begin{matrix} & \text{Bob} & \text{Molly} & \text{Mary} & \text{Larry} \\ (0.48 & 0.52 & -0.48 & -0.52) \end{matrix}$$

Rank 1 model

$$\bar{A} + \sigma_1 U_1 V_1^T = \begin{matrix} & \text{Bob} & \text{Molly} & \text{Mary} & \text{Larry} & \\ \left(\begin{matrix} 1.34 (1) & 1.19 (1) & 4.66 (5) & 4.81 (4) \\ 1.55 (2) & 1.42 (1) & 4.45 (4) & 4.58 (5) \\ 4.45 (4) & 4.58 (5) & 1.55 (2) & 1.42 (1) \\ 4.43 (5) & 4.56 (4) & 1.57 (2) & 1.44 (1) \\ 4.43 (4) & 4.56 (5) & 1.57 (1) & 1.44 (2) \\ 1.34 (1) & 1.19 (2) & 4.66 (5) & 4.81 (5) \end{matrix} \right) & \text{The Dark Knight} \\ & & & & & \text{Spiderman 3} \\ & & & & & \text{Love Actually} \\ & & & & & \text{B.J.'s Diary} \\ & & & & & \text{Pretty Woman} \\ & & & & & \text{Superman 2} \end{matrix}$$

Matrix completion

	Bob	Molly	Mary	Larry	
⎛	1	?	5	4	The Dark Knight
	?	1	4	5	Spiderman 3
	4	5	2	?	Love Actually
	5	4	2	1	Bridget Jones's Diary
	4	5	1	2	Pretty Woman
	1	2	?	5	Superman 2

Low-rank matrix estimation

First idea:

$$\min_{\tilde{X} \in \mathbb{R}^{m \times n}} \text{rank}(\tilde{X}) \quad \text{such that } \tilde{X}_\Omega \approx y$$

Computationally intractable because of missing entries

Tractable alternative:

$$\min_{\tilde{X} \in \mathbb{R}^{m \times n}} \left\| \tilde{X}_\Omega - y \right\|_2^2 + \lambda \left\| \tilde{X} \right\|_*$$

Matrix completion via nuclear-norm minimization

	Bob	Molly	Mary	Larry	
	1	2 (1)	5	4	The Dark Knight
	2 (2)	1	4	5	Spiderman 3
	4	5	2	2 (1)	Love Actually
	5	4	2	1	Bridget Jones's Diary
	4	5	1	2	Pretty Woman
	1	2	5 (5)	5	Superman 2

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Background subtraction



Low rank + sparse model

$$\min_{\tilde{L}, \tilde{S} \in \mathbb{R}^{m \times n}} \left\| \tilde{L} \right\|_* + \lambda \left\| \tilde{S} \right\|_1 \quad \text{such that } \tilde{L} + \tilde{S} = Y$$

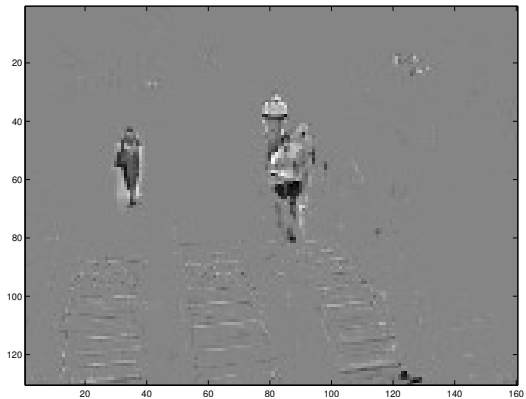
Frame 17



Low-rank component



Sparse component



Frame 42



Low-rank component



Sparse component



Frame 75



Low-rank component



Sparse component



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Nonnegative matrix factorization

Topic modeling

$$A := \begin{pmatrix} \text{singer} & \text{GDP} & \text{senate} & \text{election} & \text{vote} & \text{stock} & \text{bass} & \text{market} & \text{band} & \text{Articles} \\ 6 & 1 & 1 & 0 & 0 & 1 & 9 & 0 & 8 & \text{a} \\ 1 & 0 & 9 & 5 & 8 & 1 & 0 & 1 & 0 & \text{b} \\ 8 & 1 & 0 & 1 & 0 & 0 & 9 & 1 & 7 & \text{c} \\ 0 & 7 & 1 & 0 & 0 & 9 & 1 & 7 & 0 & \text{d} \\ 0 & 5 & 6 & 7 & 5 & 6 & 0 & 7 & 2 & \text{e} \\ 1 & 0 & 8 & 5 & 9 & 2 & 0 & 0 & 1 & \text{f} \end{pmatrix}$$

SVD

$$A - \bar{A} = USV^T = U \begin{bmatrix} 19.32 & 0 & 0 & 0 & 0 & 0 \\ 0 & 14.46 & 0 & 0 & 0 & 0 \\ 0 & 0 & 4.99 & 0 & 0 & 0 \\ 0 & 0 & 0 & 2.77 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1.67 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0.93 \end{bmatrix} V^T$$

Left singular vectors

	a	b	c	d	e	f
U_1	= (-0.51	-0.40	-0.54	-0.11	-0.38	-0.38)
U_2	= (0.19	-0.45	-0.19	-0.69	-0.2	-0.46)
U_3	= (0.14	-0.27	-0.09	-0.58	-0.69	-0.29)

Right singular vectors

	singer	GDP	senate	election	vote	stock	bass	market	band
$V_1 =$	$(-0.38$	0.05	0.40	0.27	0.40	0.17	-0.52	0.14	$-0.38)$
$V_2 =$	$(0.16$	-0.46	0.33	0.15	0.38	-0.49	0.10	-0.47	$0.12)$
$V_3 =$	$(-0.18$	-0.18	-0.04	-0.74	-0.05	0.11	-0.10	-0.43	$-0.43)$

Nonnegative matrix factorization

$$M \approx WH, \quad W_{i,j} \geq 0, \quad 1 \leq i \leq m, 1 \leq j \leq r, \\ H_{i,j} \geq 0, \quad 1 \leq i \leq r, 1 \leq i \leq n,$$

Right nonnegative factors

	singer	GDP	senate	election	vote	stock	bass	market	band	
H_1	=	(0.34	0	3.73	2.54	3.67	0.52	0	0.35	0.35)
H_2	=	(0	2.21	0.21	0.45	0	2.64	0.21	2.43	0.22)
H_3	=	(3.22	0.37	0.19	0.2	0	0.12	4.13	0.13	3.43)

Left nonnegative factors

$$\begin{array}{rcccccc} & & a & b & c & d & e & f \\ W_1 & = & (0.03 & 2.23 & 0 & 0 & 1.59 & 2.24) \\ W_2 & = & (0.1 & 0 & 0.08 & 3.13 & 2.32 & 0) \\ W_3 & = & (2.13 & 0 & 2.22 & 0 & 0 & 0.03) \end{array}$$