Sept 30,2019

Last time:

$$u'' + p(t) u + q(t) u = g(t)$$

TVP version
 $u(t_0) = u_0$
 $u'(t_0) = u'_i$
Boundary Value version
 $u(a) = u_a$
Solve on entire
 $u(b) = u_b$

Get rout to the point: More or less, we will only be concerned with the equation y'' + p(t)y' + q(t)y = q(t). If g=0, we have the following EEU throaten:

Thus If
$$p_{iq}$$
 are continuous in $\alpha < t < B$, then the equation
 $y'' + p(t) y' + q(t) y = 0$
(*) $y(t_0) = y_0$ to $e(\alpha, \beta)$
 $y'(t_0) = y'_0$ to $e(\alpha, \beta)$
has exactly one solution on (α, β) . In particular, if $y_0 = y_0' = 0$,
then $y = 0$ on (α, β) .

To begin studying this equation, start by examining the operator L: Functions - > Functions :

$$Jf = f'' + pf' + qf$$

$$J \text{ is a living operator / transformation / map:}$$

$$J(cf + dg) = (cf'' + dg'') + p(cf' + dg') + q(f + g)$$

$$= c(f'' + pf' + qf) + d(g'' + pg' + qg)$$

$$= cJf + dJg$$

$$= 7 \text{ solutions of (*) substituting Jy=0.}$$

$$\frac{Ex}{dt^2} + y=0 \implies Jy = \frac{d^2y}{dt^2} + y=0 \quad (x*)$$

$$Trivindly, solutions are y_1 = \cos t$$

$$y_2 = \sin t$$
and therefore any livient combination of y_1, y_2 are solutions
$$J(c_1 \cos t + c_3 \sin t) = 0.$$

Adding conditions y(to)=yo, y'lto)=yo determine ci,cz.

The obvious question is : are all solutions to
$$(**)$$
 of the
form $c_{1}y_{1} + c_{1}y_{1}$? Yes?
Thus: Let $y_{1}y_{2}$ be solutions to $y = 0$ on $(*, \beta)$. If
 $y_{1}y_{2}' - y_{1}'y_{2} \neq 0$ is anywhere in $(*,\beta)$
 $y_{1}y_{2}' - y_{1}'y_{2} \neq 0$ is the
general solution to $y_{2}=c_{1}y_{1} + c_{2}y_{2}$ to the
general solution to $y_{2}=0$.
Proof: Let y be any solution to $y_{2}=0$. Compute
 $y_{0}=y(k_{0})$, $y_{0}'=y(k_{0})$. Then we must solve for c_{1},c_{2} withte
system:
 $y_{0}=y(k_{0})=c_{1}y_{1}(k_{0})+c_{2}y_{2}(k_{0})$
 $y_{0}'=y'(k_{0})=c_{1}y_{1}(k_{0})+c_{2}y_{2}(k_{0})$
 $=$ $\begin{pmatrix} y_{1}(k_{0}) - y_{2}(k_{0}) \\ y_{1}'(k_{0}) - y_{2}(k_{0}) \end{pmatrix} \begin{pmatrix} c_{1} \\ c_{2} \end{pmatrix} = \begin{pmatrix} y_{0} \\ y_{0} \end{pmatrix}$
Solution exists and is unique if the determinant is non-zero:
 $y_{1}(k_{0}) y_{1}'(k_{0}) - y_{1}(k_{0}) y_{1}'(k_{0}) \neq 0$.
Therefore, for any to $c_{1}(x_{1}\beta)$, we can compute unique $c_{1}(k_{0}, \beta)$
 $\frac{Definition}{1}$: The quantity $y_{1}y_{2}' - y_{1}'y_{2}$ is called the Wronskinn
of $y_{1}(y_{1})$, denoted by $W(y_{1},y_{2})$.

Thus: Let p_{iq} be continuous on $(\alpha_i\beta)$ and let $y_{ij}y_{2}$ be two solutions to Jy=0. Then $W(y_{ij}y_{2})=0$ identically, or is never equal to 0 on $(\alpha_i\beta)$.

$$P_{100}f$$
: First, note that W satisfies the ODE:
W' + p/t) W = 0.
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$$J_{vst} \quad (ompute \quad W': \\ W/t = y_1(t) y_2'(t) - y_1'(t) y_2(t) \\ = W' = y_1'y_2' + y_1y_2'' - y_1''y_2 - y_1'y_2' \\ = y_1y_2'' - y_1''y_2 \\ Also_1 \quad y_1'' = -p(t) y_1' - q(t) y_1 \\ y_2'' = -p(t) y_2' - q(t) y_2$$

$$W' = y_{1}(-py_{2}'-qy_{2}) - (-py_{1}'-qy_{1})y_{2}$$
$$= -py_{1}y_{2}' - qy_{1}y_{2} + py_{1}'y_{2} + qy_{1}y_{2}$$
$$= -p(y_{1}y_{2}' - y_{1}'y_{2})$$
$$= -pW$$

Given that
$$W' + pW = 0$$
, then
 $-\int pHI dt$
 $WItI = C C$
never equal to zero.

therefore, either C=0 and W=0 everywhere, or $W \neq 0$ for any t. <u>Definition</u>: Two functions fig are linearly dependent on an interval [a,b] if f(t) = c g(t) for $t \in [a,b]$. Otherwise they are linearly independent (M <u>This</u> Two solutions y_{1,y_2} to (*) on [a,b] are linearly independent if and only if $W[y_{1,y_2}] \neq 0$ on [a,b]. Therefore, $y_{1,k}y_2$ form a fundamental solution set iff they are linearly independent

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Review for Prelim Exam 1 - Oct 2nd in class, 9:30 - 10:45 - Closed book Topics - First order equations (§1.2) -linear vs. nonlinear - general solutions - solution to y' + a(t) y = b(t) (Application: Carbon datig) $\overline{\beta} 1i3$ - integrating factors. - Separable equations (\$ 1.4), orthogonal trajectories (\$1.8) - Exact equations (\$ 1.9) - conditions for exactness - solution methods - integrating fuctors - Existence & Uniqueness to IUP [\$1.10] - Conditions required to prove existence/uniqueness (Thm 2') - Picard iterations - Newton's Method (§ [, 11.]) - rate of convergence - Euleris Mathod (§1.13) - Explicit vs. Implicit - Rate of convergence.

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