# Simple/multi-level fast direct solver for IE

Ondrej Maxian, Anqi Mao

October 28, 2020





① CH13: A simple direct solver for integral equations Introduction

Block separable matrices

#### Background

Formulate a physical problem in the form of an integral equation such as

$$lpha q(oldsymbol{x}) + \int_{\Gamma} k(oldsymbol{x},oldsymbol{y}) \, ds(oldsymbol{y}) = f(oldsymbol{x}), \qquad oldsymbol{x} \in \Gamma,$$

and then discretize it to obtain a linear system

$$\mathbf{A}\mathbf{q} = \mathbf{f} \tag{1}$$

Question: how to solve the linear system efficiently?

#### Solvers for discretized IE

# Usually, the coefficient matrix **A** is dense.

Gaussian elimination: cubic complexity iterative solver:  $T_{solve} \simeq N_{iter} \times T_{matvec}$  $T_{matvec}$ : linear complexity (FMM, H-matrix)

*N<sub>iter</sub>*: preconditioner

fast direct solvers: linear complexity

build stage: build approximate inverse **B** of **A** solve stage: compute approximate solution  $\mathbf{q}_{approx} = \mathbf{B}\mathbf{f}$ compelling in solving a sequence of linear systems simple single-level scheme  $\rightarrow$  multi-level scheme

#### Block separable matrices

**A** :  $N \times N$ . Tessellate it into  $p \times p$  blocks. Each block:  $n \times n$ .

$$\mathbf{A} = \begin{bmatrix} \mathbf{D}_{1} & \mathbf{A}_{1,2} & \mathbf{A}_{1,3} & \cdots & \mathbf{A}_{1,p} \\ \mathbf{A}_{2,1} & \mathbf{D}_{2} & \mathbf{A}_{2,3} & \cdots & \mathbf{A}_{2,p} \\ \vdots & \vdots & \vdots & & \vdots \\ \mathbf{A}_{p,1} & \mathbf{A}_{p,2} & \mathbf{A}_{p,3} & \cdots & \mathbf{D}_{p} \end{bmatrix}$$

#### Assume

- upper bound k for ranks of all off-diagonal blocks
- ▶ basis matrices  $\{\mathbf{U}_k\}_{k=1}^p$  and  $\{\mathbf{V}_k\}_{k=1}^p$  such that

$$\begin{array}{lll} \mathbf{A}_{\sigma,\tau} & = & \mathbf{U}_{\sigma} & \tilde{\mathbf{A}}_{\sigma,\tau} & \mathbf{V}_{\tau}^*, & \sigma,\tau \in \{1,\,2,\,\ldots,\,p\}, & \sigma \neq \tau. \\ n \times n & n \times k & k \times k & k \times n \end{array}$$

#### Block separable matrices

#### Therefore, **A** admits a block factorization:

where  $\mathbf{U} = \operatorname{diag}(\mathbf{U}_1, \mathbf{U}_2, \ldots, \mathbf{U}_n),$  $\mathbf{V} = \operatorname{diag}(\mathbf{V}_1, \, \mathbf{V}_2, \, \ldots, \, \mathbf{V}_p),$  $\mathbf{D} = \operatorname{diag}(\mathbf{D}_1, \, \mathbf{D}_2, \, \ldots, \, \mathbf{D}_p),$ and  $\tilde{\textbf{A}} = \left[ \begin{array}{cccc} 0 & \tilde{\textbf{A}}_{12} & \textbf{A}_{13} & \cdots \\ \tilde{\textbf{A}}_{21} & 0 & \tilde{\textbf{A}}_{23} & \cdots \\ \tilde{\textbf{A}}_{31} & \tilde{\textbf{A}}_{32} & 0 & \cdots \\ \cdot & \cdot & \cdot \end{array} \right] .$ 

For p = 4,

#### Variation of the Woodbury formula

# Lemma (variation of the Woodbury formula)

Suppose that **A** is an invertible  $N \times N$  matrix, K is a positive integer smaller than N, and **A** admits the factorization:

Then

where

$$\begin{split} \hat{\mathbf{D}} &= (\mathbf{V}^*\mathbf{D}^{-1}\mathbf{U})^{-1},\\ \mathbf{E} &= \mathbf{D}^{-1}\mathbf{U}\hat{\mathbf{D}},\\ \mathbf{F} &= (\hat{\mathbf{D}}\mathbf{V}^*\mathbf{D}^{-1})^*,\\ \mathbf{G} &= \mathbf{D}^{-1} - \mathbf{D}^{-1}\mathbf{U}\hat{\mathbf{D}}\mathbf{V}^*\mathbf{D}^{-1} \end{split}$$

provided all inverses that appear exist. Moreover, rank( $\mathbf{G}$ ) = N - K.

#### Proof

Fix an **f**. Set  $\mathbf{q} = \mathbf{A}^{-1}\mathbf{f}$ . Then  $\mathbf{A}\mathbf{q} = \mathbf{f}$ . Set  $\tilde{\mathbf{q}} = \mathbf{V}^*\mathbf{q}$ . We get a linear system

$$\left[ \begin{array}{cc} D & U\tilde{A} \\ -V^* & I \end{array} \right] \left[ \begin{array}{c} q \\ \tilde{q} \end{array} \right] = \left[ \begin{array}{c} f \\ 0 \end{array} \right]$$

From the first row,  $\mathbf{q} = \mathbf{D}^{-1}\mathbf{f} - \mathbf{D}^{-1}\mathbf{U}\tilde{\mathbf{A}}\tilde{\mathbf{q}}$ . Substituting into the second row yields

 $(\mathbf{I} + \mathbf{V}^* \mathbf{D}^{-1} \mathbf{U} \tilde{\mathbf{A}}) \, \tilde{\mathbf{q}} = \mathbf{V}^* \mathbf{D}^{-1} \mathbf{f}$ 

Multiply both sides by  $\hat{\mathbf{D}} = (\mathbf{V}^* \mathbf{D}^{-1} \mathbf{U})^{-1}$  to get

$$\left(\hat{\mathbf{D}} + \tilde{\mathbf{A}}\right)\tilde{\mathbf{q}} = \hat{\mathbf{D}}\mathbf{V}^{*}\mathbf{D}^{-1}\mathbf{f}$$

Therefore, we can express q as

$$\begin{split} \mathbf{q} &= \mathbf{D}^{-1} \mathbf{f} - \mathbf{D}^{-1} \mathbf{U} \tilde{\mathbf{A}} \tilde{\mathbf{q}} \\ &= \mathbf{D}^{-1} \mathbf{f} - \mathbf{D}^{-1} \mathbf{U} (\hat{\mathbf{D}} \mathbf{V}^* \mathbf{D}^{-1} \mathbf{f} - \hat{\mathbf{D}} \tilde{\mathbf{q}}) \\ &= \underbrace{\left( \mathbf{D}^{-1} - \mathbf{D}^{-1} \mathbf{U} \hat{\mathbf{D}} \mathbf{V}^* \mathbf{D}^{-1} \right)}_{=\mathbf{G}} \mathbf{f} + \underbrace{\mathbf{D}^{-1} \mathbf{U} \hat{\mathbf{D}}}_{=\mathbf{E}} (\hat{\mathbf{D}} + \tilde{\mathbf{A}})^{-1} \underbrace{\hat{\mathbf{D}} \mathbf{V}^* \mathbf{D}^{-1}}_{=\mathbf{F}^*} \mathbf{f} \end{split}$$

#### **Proof:** rank(G) = N - K

Observe that  

$$\mathbf{V}^*\mathbf{G} = \mathbf{V}^*\mathbf{D}^{-1} - \mathbf{V}^*\mathbf{D}^{-1}\mathbf{U}\hat{\mathbf{D}}\mathbf{V}^*\mathbf{D}^{-1} = \mathbf{V}^*\mathbf{D}^{-1} - \hat{\mathbf{D}}^{-1}\hat{\mathbf{D}}\mathbf{V}^*\mathbf{D}^{-1}$$
  
 $= \mathbf{V}^*\mathbf{D}^{-1} - \mathbf{V}^*\mathbf{D}^{-1} = \mathbf{0}$ 

Thus,

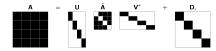
$$\mathsf{rank}(\mathbf{V}^*) + \mathsf{rank}(\mathbf{G}) - N \leq 0 \Rightarrow \mathsf{rank}(\mathbf{G}) \leq N - K$$

Also,

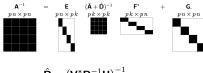
$$\mathsf{rank}(\mathbf{A}^{-1}) \leq \mathsf{rank}(\mathbf{E}(\tilde{\mathbf{A}} + \hat{\mathbf{D}})^{-1}\mathbf{F}^*) + \mathsf{rank}(\mathbf{G}) \Rightarrow \mathsf{rank}(\mathbf{G}) \geq \mathit{N} - \mathit{K}$$

## Apply the lemma

Recall the block structure of **A**, for p = 4



Compute  $A^{-1}$  by the lemma



$$\begin{split} \mathbf{D} &= (\mathbf{V}^{T}\mathbf{D}^{-1}\mathbf{U})^{T}, \\ \mathbf{E} &= \mathbf{D}^{-1}\mathbf{U}\hat{\mathbf{D}}, \\ \mathbf{F} &= (\hat{\mathbf{D}}\mathbf{V}^{*}\mathbf{D}^{-1})^{*}, \\ \mathbf{G} &= \mathbf{D}^{-1} - \mathbf{D}^{-1}\mathbf{U}\hat{\mathbf{D}}\mathbf{V}^{*}\mathbf{D}^{-1} \end{split}$$

 $\triangleright$   $\hat{D}$ , E, F, G are cheap to form (block diagonal)

▶ invert  $pn \times pn$  matrix  $\mathbf{A} \Rightarrow$  invert small  $pk \times pk$  matrix  $\mathbf{\tilde{A}} + \mathbf{\hat{D}}$ 

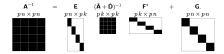
#### Remark

A more common version of the Woodbury formula

$$\left(\boldsymbol{\mathsf{D}}+\boldsymbol{\mathsf{U}}\tilde{\boldsymbol{\mathsf{A}}}\boldsymbol{\mathsf{V}}^*\right)^{-1}=\boldsymbol{\mathsf{D}}^{-1}-\boldsymbol{\mathsf{D}}^{-1}\boldsymbol{\mathsf{U}}\left(\tilde{\boldsymbol{\mathsf{A}}}^{-1}+\boldsymbol{\mathsf{V}}^*\boldsymbol{\mathsf{D}}^{-1}\boldsymbol{\mathsf{U}}\right)^{-1}\boldsymbol{\mathsf{V}}^*\boldsymbol{\mathsf{D}}^{-1}$$

- ► If both à and V\*D<sup>-1</sup>U are invertible, then the two versions are equivalent
- à is not block diagonal, often not invertible

### Asymptotic complexity



Suppose we are given the factors in a block separable factorization.

► compute 
$$\hat{D}$$
,  $E$ ,  $F$ ,  $G$ :  $pn^3$ 

▶ invert  $\tilde{\mathbf{A}} + \hat{\mathbf{D}}$ :  $(pk)^3$ 

Suppose that k is fixed. What is the optimal choice of p?

$$T \sim p \, (N/p)^3 + (pk)^3 \sim p^{-2} N^3 + p^3 k^3$$

Optimal choice  $p \sim (N/k)^{3/5}$ , which leads to

 $T \sim N^3 p^{-2} + k^3 p^3 \sim N^3 (N/k)^{-6/5} + k^3 (N/k)^{9/5} \sim N^{9/5} k^{6/5}$ 

#### Compute a block separable representation

# Definition

Let **A** be an  $N \times N$  matrix, let I = 1 : N be its index vector, and let  $I = I_1 \cup I_2 \cup \ldots \cup I_p$  be a disjoint partition of I. Then **A** has block rank k w.r.t this partition if there exist matrices  $\{\mathbf{U}_{\tau}\}_{\tau=1}^{p}$ and  $\{\mathbf{V}_{\tau}\}_{\tau=1}^{p}$  such that each off-diagonal block of **A** admits a factorization

where  $n_{\tau}$  is the length of  $I_{\tau}$ .

block separable: block rank k is small block separable (to precision  $\epsilon$ ): block rank k is small (within preset tolerance  $\epsilon$ ) Compute a block separable representation

For any given  $\tau$ , the columns of  $\mathbf{U}_{\tau}$  span the columns of every block  $\mathbf{A}_{\tau,\sigma}$  for  $\sigma \neq \tau$ .

In other words, the columns of  $\boldsymbol{U}_{\tau}$  span all the columns in the matrix

$$oldsymbol{\mathsf{A}}(I_{ au},I_{ au}^{ ext{c}})=ig[oldsymbol{\mathsf{A}}_{ au,1},\,oldsymbol{\mathsf{A}}_{ au,2},\,\ldots,\,oldsymbol{\mathsf{A}}_{ au, au-1},\,oldsymbol{\mathsf{A}}_{ au, au+1},\,\ldots,\,oldsymbol{\mathsf{A}}_{ au,p}ig]$$

where  $I_{\tau}^{c} = I \setminus I_{\tau}$ . Solve the task using SVD.

When a block separable matrix arises from the discretization of a boundary integral operator, there exist compression techniques of linear complexity.