# Liouville quantum gravity from random matrix dynamics 

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We establish the first connection between $2 d$ Liouville quantum gravity and natural dynamics of random matrices. In particular, we show that if $\left(U_{t}\right)$ is a Brownian motion on the unitary group at equilibrium, then the measures

$$
\left|\operatorname{det}\left(U_{t}-e^{\mathrm{i} \theta}\right)\right|^{\gamma} \mathrm{d} t \mathrm{~d} \theta
$$

converge in the limit of large dimension to the $2 d$ LQG measure, a properly normalized exponential of the $2 d$ Gaussian free field. Gaussian free field type fluctuations associated with these dynamics were first established by Spohn (1998) and convergence to the LQG measure in $2 d$ settings was conjectured since the work of Webb (2014), who proved the convergence of related one dimensional measures by using inputs from Riemann-Hilbert theory.

The convergence follows from the first multi-time extension of the result by Widom (1973) on FisherHartwig asymptotics of Toeplitz determinants with real symbols. To prove these, we develop a general surgery argument and combine determinantal point processes estimates with stochastic analysis on Lie group, providing in passing a probabilistic proof of Webb's $1 d$ result. We believe the techniques will be more broadly applicable to matrix dynamics out of equilibrium, joint moments of determinants for classes of correlated random matrices, and the characteristic polynomial of non-Hermitian random matrices.
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## 1 Introduction

The Gaussian multiplicative chaos (GMC), introduced by Kahane in [65], is the fractal measure

$$
e^{\gamma \phi(z)} \mathrm{d} z:=\lim _{\varepsilon \rightarrow 0} e^{\gamma \phi_{\varepsilon}(z)-\frac{\gamma^{2}}{2} \mathbb{E}\left(\phi_{\varepsilon}(z)^{2}\right)} \mathrm{d} z,
$$

where $\phi_{\varepsilon}$ is a mollification of a log-correlated Gaussian field $\phi$ on a domain $D \subset \mathbb{R}^{d}$ and $\mathrm{d} z$ denotes the Lebesgue measure on $\mathbb{R}^{d}$. The regularization and renormalization are necessary because of the negative Sobolev regularity of the field. The convergence holds in probability with respect to the topology of weak convergence and the parameter $\gamma \in(0, \sqrt{2 d})$ since the limit is zero above this range 87, 89, 13, 86. The specific case where $\phi$ is a two dimensional Gaussian free field (GFF) (a Gaussian field whose covariance function is the inverse of the Laplacian) or a one dimensional restriction thereof, has proved to be connected with many different domains in mathematical physics. To name a few, it is the volume form in Liouville quantum gravity (LQG), a metric measure space corresponding to the formal Riemannian metric tensor " $e^{\gamma h}\left(\mathrm{~d} x^{2}+\mathrm{d} y^{2}\right)$ " $85,38,33,54$; appears in the scaling limit of random planar maps $73,76,78,56$; interplays through conformal welding with Schramm Loewner Evolutions and the Conformal Loop Ensemble, the scaling limit of interfaces in critical spins and percolation models $6,39,91,77,3$; played a central role in the rigorous formulation and the resolution of Liouville Conformal Field Theory $29,70,52$; and appears in the construction of a stochastic version of the Ricci flow [36. The literature on this topic is abundant and we refer to the survey 92 and references therein.

The Brownian motion on the unitary group $U(N)$ is a rich object in random matrix theory. It preserves the Haar measure and, under this initial condition, its eigenvalues have Circular Unitary Ensemble distribution at each fixed time. They satisfy the Dyson dynamics 40 on the circle and, by the Karlin-McGregor formula 66], can be seen as Brownian motions on the unit circle conditioned not to intersect. As ubiquitous in random matrix theory, we are concerned with the large $N$ limit of observables of this process. The large $N$ limit of the unitary Brownian motion itself is the free unitary Brownian motion 16,28 and this has applications to the large $N$ limit of the Yang-Mills measure on the Euclidean plane with unitary structure group as observed in 74 . In this paper, we prove the following

Theorem 1.1. Let $\left(U_{t}\right)$ be a unitary Brownian motion at equilibrium, as defined in 2.6). Then for every $\gamma \in(0,2 \sqrt{2})$,

$$
\begin{equation*}
\lim _{N \rightarrow \infty} \frac{\left|\operatorname{det}\left(U_{t}-e^{\mathrm{i} \theta}\right)\right|^{\gamma}}{\mathbb{E}\left(\left|\operatorname{det}\left(U_{t}-e^{\mathrm{i} \theta}\right)\right|^{\gamma}\right)} \mathrm{d} t \mathrm{~d} \theta=e^{\gamma h(z)} \mathrm{d} z \tag{1.1}
\end{equation*}
$$

where $h$ is the Gaussian free field on the cylinder $\mathbb{R} \times \mathbb{R} / 2 \pi \mathbb{Z}, \mathbb{E}(h(z) h(w))=\pi\left(-\Delta_{\mathcal{C}}\right)^{-1}(z, w)$, where $\Delta_{\mathcal{C}}=\partial_{t}^{2}+\partial_{\theta}^{2}$. Moreover, the convergence is in distribution with respect to the weak topology.

The usual parametrization $\gamma \in(0, \sqrt{2 d})$ in GMC theory corresponds to log-correlated fields. Here, the field is $\frac{1}{2} \log$-correlated and by a change of parametrization our result covers this entire range (see 2.16 ) below for an exact formula of the covariance of this free field, and background).

In 97, Webb opened a connection between Gaussian multiplicative chaos and random matrix theory by linking the characteristic polynomial of the Circular Unitary Ensemble (CUE) to a one-dimensional GMC and conjectured that similar results also hold for the Gaussian Unitary Ensemble, one-dimensional $\beta$-ensembles, and more generally for random matrix models presenting log-correlations, including in dimension two. His proof and the ones of the following works 14,79 relied on existing results for Fisher-Hartwig asymptotics based on the Riemann-Hilbert approach (or adaptations thereof). Another approach appeared in [26], still for $d=1$, which showed that the limit of an object different from the characteristic polynomial, the spectral measure of circular $\beta$-ensembles, coincides with a Gaussian multiplicative chaos. In our paper, as an application of our main theorem below, we provide the first convergence to the $2 d$ LQG measure, taking a new angle in viewing this problem as one in random matrix dynamics.

By considering the unit disk instead of a semi-infinite cylinder (i.e., replacing $\mathrm{d} t \mathrm{~d} \theta$ by $e^{-2 t} \mathrm{~d} t \mathrm{~d} \theta$ with $z=e^{-t} e^{\mathrm{i} \theta}, t \in(0, \infty)$ in the limit (1.1) , Theorem 1.1 translates into convergence towards the measure $e^{\gamma \bar{h}(z)} \mathrm{d} z$ on the unit disk where $\bar{h}$ is the lateral part in the polar decomposition of the 2 d whole plane GFF $h$, i.e. $\bar{h}(z)=h(z)-f_{|z| \mathbb{U}} h$; the subtracted process $r \mapsto f_{r \mathbb{U}} h$ being a Brownian motion independent of $\bar{h}$.

The field $\bar{h}$ and the associated chaos measure were introduced in the mating of trees 39], used in the proof of the DOZZ formula 70 and the dynamics of the restriction of $\bar{h}$ on concentric circles played a crucial role in the proof of the conformal bootstrap in Liouville theory [52]. The unitary Brownian motion is the most natural model among random matrix dynamics that induce the field $\bar{h}$ and its own dynamics.
1.1 Multi-time Fisher-Hartwig asymptotics. The main contribution of this paper is the dynamical extension of asymptotics of Toeplitz determinants with singularities. In the following discussion, the Fourier transform is normalized as $\hat{f}_{k}=\int_{0}^{2 \pi} f\left(e^{\mathrm{i} \theta}\right) e^{-\mathrm{i} k \theta} \frac{\mathrm{~d} \theta}{2 \pi}$ and we let

$$
(f, g)_{\mathrm{H}}=(f, g)_{\mathrm{H}^{1 / 2}}=\sum_{k \in \mathbb{Z}}|k| \hat{f}_{k} \hat{g}_{-k} .
$$

The Toeplitz determinant $D_{N}(f)=\operatorname{det}\left(\hat{f}_{j-k}\right)_{j, k=0}^{N-1}$ has been the subject of many investigations. For example, a simple version of the strong Szegő theorem states that if $f=e^{V}$ with $V$ real-valued and smooth enough, $D_{N}(f) \sim \exp \left(N \hat{V}_{0}+\frac{1}{2}\|V\|_{\mathrm{H}}^{2}\right)$ for large dimension.

For a wide class of irregular functions $f$, Fisher and Hartwig [45 made a seminal general conjecture about the asymptotic form of $D_{N}(f)$, which has been corrected by Basor and Tracy 11 and is settled in full generality 31 by Riemann-Hilbert methods, after multiple important contributions, e.g. 10, 99 41]. For example, in the special case where $f(z)=e^{V(z)} \prod_{j=1}^{m}\left|z-z_{j}\right|^{2 \alpha_{j}}$ with $m \geqslant 1$ fixed singularities $z_{j}$ on the unit circle, $\alpha_{j}>-1 / 2$, and smooth centered real $V$, the Fisher-Hartwig asymptotics states that

$$
\begin{equation*}
D_{N}(f)=e^{\frac{1}{2}\|V\|_{\mathrm{H}}^{2}-\sum_{j=1}^{m} \alpha_{j} V\left(z_{j}\right)} N^{\sum_{j=1}^{m} \alpha_{j}^{2}} \prod_{1 \leqslant j<k \leqslant m}\left|z_{j}-z_{k}\right|^{-2 \alpha_{j} \alpha_{k}} \prod_{j=1}^{m} \frac{\mathrm{G}\left(1+\alpha_{j}\right)^{2}}{\mathrm{G}\left(1+2 \alpha_{j}\right)}(1+\mathrm{o}(1)), \tag{1.2}
\end{equation*}
$$

where the Barnes function G is defined in Subsection 2. Motivations in statistical physics for general FisherHartwig asymptotics are multiple, see in particular the beautiful exposition of applications to the phase transition of the 2 d Ising model in 32 .

Such Toeplitz determinant asymptotics are related to random matrix theory as they correspond to moments of characteristic polynomials of random matrices. For example, the Heine formula implies that the left-hand side of $\sqrt{1.2}$ coincides with $\mathbb{E}\left[\prod_{j=1}^{m}\left|P_{N}\left(z_{j}\right)\right|^{2 \alpha_{j}} e^{\operatorname{Tr} V(U)}\right]$, where $P_{N}(z)=\operatorname{det}(z-U)$ and $U$ is a $N \times N$ Haar-distributed unitary matrix. The main contribution of our paper is the first Fisher-Hartwig asymptotics for singularities in space and time. More precisely, Theorem 1.2 below is a multi-time extension of (1.2), a formula due to Harold Widom in 1973.

To state this main result, we first denote $\mathscr{A}$ (resp. $\mathscr{B}$ ) a finite subset of $\{z=t+\mathrm{i} \theta, t \in \mathbb{R}, 0 \leqslant \theta \leqslant 2 \pi\}$ (resp. $\mathbb{R}$ ), with fixed cardinality but possibly $N$-dependent points. The functions $f_{s}$ in the statement below are of regularity $\mathscr{C}^{3}$ on an arbitrary mesoscopic scale $N^{-1+\delta}, \delta \in(0,1]$. We also remind the definition of the Poisson kernel $\mathrm{P}_{t}$ in (2.1).

Theorem 1.2. Let $\left(U_{t}\right)$ be a unitary Brownian motion at equilibrium, as defined in 2.6). Let $0<\delta \leqslant 1, C$ be fixed constants. There exists $\varepsilon>0$ such that uniformly in $\max _{\mathscr{B}}|s|+\max _{\mathscr{A}}|z| \leqslant C, \min _{\left(z, z^{\prime}\right) \in \mathscr{A}^{2}, z \neq z^{\prime}} \mid e^{z}-$ $e^{z^{\prime}} \mid>N^{-1+\delta}, \gamma_{z} \in[0, C], f_{s} \in \mathscr{S}_{\delta, C}$ (see Definition 2.1), we have

$$
\begin{align*}
\mathbb{E}\left[e^{\sum_{s \in \mathscr{B}} \operatorname{Tr} f_{s}\left(U_{s}\right)} \prod_{z=t+\mathrm{i} \theta \in \mathscr{A}} \mid\right. & \left.\left.\operatorname{det}\left(U_{t}-e^{\mathrm{i} \theta}\right)\right|^{\gamma_{z}}\right]=e^{N \sum_{\mathscr{B}} f f_{s}+\frac{1}{2} \sum_{\mathscr{A} 2}\left(f_{s}, \mathrm{P}_{\left|s-s^{\prime}\right|} f_{s^{\prime}}\right) \mathrm{H}-\sum_{z \in \mathscr{A}, s \in \mathscr{B}} \frac{\gamma_{z}^{2}\left(\mathrm{P}_{|t-s|}-\mathrm{P}_{\infty}\right) f_{s}\left(e^{\mathrm{i} \theta}\right)}{}} \begin{aligned}
& \times \prod_{\mathscr{A}} N^{\frac{\gamma_{z}^{2}}{4}} \frac{\mathrm{G}\left(1+\frac{\gamma_{z}}{2}\right)^{2}}{\mathrm{G}\left(1+\gamma_{z}\right)} \prod_{z, w \in \mathscr{A}, z \neq w}\left(\frac{\max \left(\left|e^{z}\right|,\left|e^{w}\right|\right)}{\left|e^{z}-e^{w}\right|}\right)^{\frac{1}{4} \gamma_{z} \gamma_{w}}\left(1+\mathrm{O}\left(N^{-\varepsilon}\right)\right)
\end{aligned} \text { (1.3)}
\end{align*}
$$

where the multiplicative constant in O depends on $|\mathscr{A}|,|\mathscr{B}|$.
When there is no singularity $(\mathscr{A}=\varnothing)$, this formula is a dynamical generalization of the strong Szegő theorem. It can also be thought of as an upgrade to any mesoscopic scale and to exponential generating functions of Spohn's convergence of the Dyson Brownian motion dynamics to the free field (see section 2.2).

However the main originality and applications of Theorem 1.2 are due to the logarithmic insertions, see for example Remarks 6.3 and 6.4 on straightforward corollaries on logarithmically correlated fields,
their maximum and optimal eigenvalues deviations along Dyson Brownian motion. Based on (1.3) it is also not hard to obtain that for any smooth space-time curve $\mathscr{C}$ in $\left(e^{\mathrm{i} \theta}, t\right)$ with Lebesgue measure $\lambda_{\mathscr{C}}$, $\left|\operatorname{det}\left(U_{t}-e^{\mathrm{i} \theta}\right)\right|^{\gamma} \mathrm{d} \lambda_{\mathscr{C}}$ converges up to normalization to a one dimensional Gaussian multiplicative chaos in the $\mathrm{L}^{1}$ phase (i.e. $\gamma<2$ for $d=1$ ). In particular this recovers the fixed time results from 97,79 .

The proof of Theorem 1.2 applies to other singularities: the discontinuities from $\operatorname{Im} \log$. We only treat the logarithmic singularity from Re log for the sake of conciseness, but one can easily state a consequence of the discontinuous case. Indeed, define $\operatorname{Im} \log \operatorname{det}\left(1-e^{-\mathrm{i} \theta} U_{t}\right)=\sum_{k} \operatorname{Im} \log \left(1-e^{\mathrm{i}\left(\theta_{k}(t)-\theta\right)}\right)$, with the branch choice $\operatorname{Im} \log \left(1-e^{\mathrm{i} \varphi}\right)=(\varphi-\pi) / 2$ if $\varphi \in[0, \pi),(\varphi+\pi) / 2$ if $\varphi \in(-\pi, 0)$. As $\operatorname{Im} \log \operatorname{det}\left(1-e^{-\mathrm{i} \theta} U_{t}\right)-\operatorname{Im} \log \operatorname{det}\left(1-U_{t}\right)=$ $\pi\left(\mathrm{N}_{t}(0, \theta)-\mathbb{E} \mathrm{N}_{t}(0, \theta)\right)$, where $\mathrm{N}_{t}(0, \theta)=\left|\left\{\theta_{k}(t) \in(0, \theta]\right\}\right|$, we have

$$
\begin{equation*}
\lim _{N \rightarrow \infty} Z_{N, \gamma}^{-1} e^{\gamma \pi\left(\mathrm{N}_{t}(0, \theta)-\mathbb{E N}_{t}(0, \theta)\right)} \mathrm{d} t \mathrm{~d} \theta=e^{\gamma h(z)} \mathrm{d} z \tag{1.4}
\end{equation*}
$$

for every $\gamma \in(0,2 \sqrt{2})$ and some constants $Z_{N, \gamma}$.
Although an extension of Theorem 1.2 to include $\operatorname{Im} \log$ and complex-valued $f_{s}$ is straightforward, a generalization to complex-valued $\gamma_{z}$ is not. In the static case, the most general version of Fisher-Hartwig asymptotics 31 allows general complex exponents, with asymptotics involving a subtle variational problem. It is not even clear how to formulate a related conjecture in our multi-time setting.

More generally, moments of characteristic polynomials of wide classes of random matrices have been a topic of major interest, see e.g. $8,19,22,47$, to name a few in the case of integer exponents by algebraic and supersymmetric methods, and $14,44,24,98$ for fractional exponents by Riemann-Hilbert methods. Theorem 1.2 initiates joint (fractional) moments for correlated random matrices, a topic connected to the quenched complexity of high dimensional landscapes 7,48.

Our paper considers random matrices from the canonical setting, the unitary group, but we expect the convergence to LQG will remain in other settings (and the proof method through surgery as described below will apply, although major technical obstacles remain). Such settings include dynamics on other Lie groups, out of equilibrium or with a Dyson Brownian motion at arbitrary temperature. In fact, the upcoming work 20] on a non-Hermitian analogue of Fisher-Hartwig asymptotics will follow a scheme similar to the surgery that we now explain.
1.2 Outline. To prove our main result, we develop a general surgery argument that allows us to go beyond the usual free field limit and which works very roughly speaking as follows: 1) we "cut" the long range non-singular part of the determinants in 1.3 ) and prove a (space-time) decoupling of the resulting product of localized singularities 2 ) we carry out a general "gluing operation" for non-singular terms 3 ) we evaluate asymptotics of one localized singularity by gluing the opposite of the associated long range nonsingular part to the determinant itself, together with the Selberg integral formula 4) with these in hands, it remains to glue back the non-singular parts and the additional smooth functions to the localized singularities.

Decoupling. The first ingredient consists in a space-time decoupling of the truncated singularities. Usual techniques to prove decorrelation for linear statistics or extrema of eigenvalues do not seem to work for the product of local singularities, either because our functions are not in $\mathrm{H}^{1 / 2}$ or because such decouplings give additive error terms. We find a new general multiplicative decorrelation of local linear statistics which can apply to a large class of determinantal point processes. We prove in Section 3.1, by using the Eynard-Mehta machinery, that the process of the eigenvalues at different times is a determinantal point process. Despite the simplicity of the expression of the kernel we find, it seems to us that this stationary case has not been derived before (nor with arbitrary initial condition); in this case, there is no canonical ordering as the particles are winding around the circle. As a second step, to work out the decoupling, the starting point of our proof is an infinite dimensional version of the Hoffman-Wielandt inequality, applied to a related self-adjoint operator, from which we then extract the sought decoupling of our observable. This is the content of Section 3.2

Matrix dynamics. Our "gluing" operation starts with the usual method (initiated in random matrix theory in [58]) of Hamiltonian perturbation and then we a) perform an integration by parts, b) obtain asymptotics. As explained at the beginning of Section 5, due to our combined multitime and singular settings, step a) requires an original approach: the integration by parts formula from Proposition 5.3 encodes information about eigenvalues but also eigenvectors, while loop equations traditionally correspond to hierarchies only for particles/eigenvalues. For the proof of Proposition 5.3. we use the Girsanov theorem on the

Lie algebra $\mathfrak{u}_{N}$ of the unitary group (the unitary Brownian motion $(U)$ is the solution of a matrix SDE driven by a Brownian motion $(B)$ on $\left.\mathfrak{u}_{N}\right)$. This entails characterizing the Fréchet derivatives of the UBM, $D_{F} U_{t}:=\lim _{\varepsilon \rightarrow 0} \varepsilon^{-1}\left(U(B+\varepsilon F)_{t}-U(B)_{t}\right)$ (shifting $B$ in a progressively measurable direction $(F)=\int_{0}^{*} f_{s} d s$ ), as solutions of matrix SDEs, and solving explicitly these. We exploit the stationarity of the process to consider long times so that observables of the UBM are well encoded by the noise driving the process and in particular by its associated integration by parts formula. The terms arising from this satisfy a law of large numbers and can be calculated, completing step b). To control the error terms involved in this step, we prove an averaged (over projections) and multi-time local law (Proposition 4.5 the main result of Section 4), which is new including in the context of Hermitian random matrices. As opposed to a free field central limit theorem, here again some care is needed as singularities imply error bounds below microscopic scales.

In Section 6, by applying the general surgery introduced above, we prove Theorem 1.2 first, and then use it for our main application, i.e. the convergence to the Liouville quantum gravity measure.

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## 2 PRELIMINARIES

Basic notations. In this paper, $\mathrm{d} \lambda$ denotes the Lebesgue measure on the unit circle $\mathbb{U}$, and $\mathrm{d} m$ the Lebesgue measure on $\mathbb{C}$. We remind that the Fourier coefficients of $f$ are defined as $\hat{f}_{k}=\frac{1}{2 \pi} \int_{0}^{2 \pi} e^{-\mathrm{i} k \theta} f(\theta) d \theta$. The Poisson kernel plays an important role and is normalized as follows:

$$
\begin{equation*}
\mathrm{P}_{t} f(z)=\int_{0}^{2 \pi} f\left(e^{\mathrm{i} \theta}\right) \operatorname{Re} \frac{1+z e^{-\mathrm{i} \theta-t}}{1-z e^{-\mathrm{i} \theta-t}} \frac{\mathrm{~d} \theta}{2 \pi} \tag{2.1}
\end{equation*}
$$

Its restriction to $\mathbb{U}$ is given by $\mathrm{P}_{t} f\left(e^{\mathrm{i} \theta}\right)=\sum_{k} \hat{f}_{k} e^{-|k| t} e^{\mathrm{i} k \theta}$.
The Barnes G-function is defined as the Weierstrass product

$$
\mathrm{G}(z+1)=(2 \pi)^{z / 2} e^{-\frac{z+z^{2}(1+\gamma)}{2}} \prod_{k=1}^{\infty}\left(1+\frac{z}{k}\right)^{k} e^{\frac{z^{2}}{2 k}-z}
$$

Here, and only here, $\gamma$ is the Euler constant. The Barnes function satisfies the functional equation $\mathrm{G}(z+1)=$ $\Gamma(z) \mathrm{G}(z)$ where $\Gamma$ is the Gamma function.

Moreover, for a matrix $A, \operatorname{Tr}(A)=\sum_{i} A_{i, i}$ and we denote by $A^{T}$ the transpose of $A . A^{*}=\overline{A^{T}}$. If $M, N$ are two complex valued matrices, $\langle M, N\rangle=\operatorname{Tr}\left(\bar{M}^{T} N\right)$ and $\langle M, N\rangle_{\mathfrak{R}}=\operatorname{Re}\langle M, N\rangle$.

Finally, the statement of Theorem 1.2 and its proof make use the following functional space $\mathscr{S}_{\delta, C}$ described below.

Definition 2.1. For $0<\kappa \leqslant 1$ and $k \in \mathbb{N}$ we introduce the norm on $\{f: \mathbb{U} \rightarrow \mathbb{R}\}$

$$
\|f\|_{\infty, k, \kappa}=\sum_{j=0}^{k} N^{j(\kappa-1)}\left\|f^{(j)}\right\|_{\infty}
$$

We define $\mathrm{A}_{\kappa, C}$ as the set of functions $g: \mathbb{U} \rightarrow \mathbb{R}$ supported on an arc of radius $N^{-1+\kappa}$ and smooth on that scale in the sense that $\|g\|_{\infty, 3, \kappa} \leqslant C \log N$. For $0<\delta \leqslant 1$, let $\mathscr{S}_{\delta, C}$ be the set of functions $f: \mathbb{U} \rightarrow \mathbb{R}$ which satisfy $\|f\|_{\mathrm{H}}^{2} \leqslant C \log N$ and can be written

$$
f=\sum_{i=1}^{m} f_{i}, m \leqslant \log N, f_{i} \in \mathrm{~A}_{\kappa, C}(\kappa \in[\delta, 1])
$$

Two examples of particular interest are as follows. First, functions of type $f\left(e^{\mathrm{i} \theta}\right)=g\left(N^{1-\kappa}(\theta-\varphi)\right)$ with $g$ compactly supported and $\mathscr{C}^{3}$ are in $\mathrm{A}_{\kappa, C} \subset \mathscr{S}_{\delta, C}$ for any $C>0$ and $\kappa \in[\delta, 1]$. Second, any regularization of the function $f\left(e^{\mathrm{i} \theta}\right)=\log \left|e^{\mathrm{i} \theta}-e^{\mathrm{i} \varphi}\right|$ on scale $N^{-1+\delta}$ is in $\mathscr{S}_{\delta, C}$ for fixed, large enough $C$ (e.g. $\theta \mapsto N^{1-\delta} \int f\left(e^{\mathrm{i} \psi}\right) \chi\left(N^{1-\delta}(\theta-\psi)\right) \mathrm{d} \psi$ with $\chi \geqslant 0$ smooth, compactly supported, $\left.\int \chi=1\right)$.
2.1 Unitary Brownian motion. With its most common normalization, the Brownian motion on the unitary group $U(N)$ satisfies the following stochastic differential equation (SDE)

$$
\begin{equation*}
\mathrm{d} \tilde{U}_{t}=\tilde{U}_{t} \mathrm{~d} B_{t}-\frac{1}{2} \tilde{U}_{t} \mathrm{~d} t \tag{2.2}
\end{equation*}
$$

where $d B_{t}$ is a Brownian motion on the space of skew Hermitian matrices. We consider an orthogonal basis of skew Hermitian matrices for $\langle\cdot, \cdot\rangle_{\Re}$ given by matrices of the form $\frac{1}{\sqrt{2 N}}\left(E_{k, \ell}-E_{\ell, k}\right), \frac{\mathrm{i}}{\sqrt{2 N}}\left(E_{k, \ell}+E_{\ell, k}\right), \frac{\mathrm{i}}{\sqrt{N}} E_{k, k}$. Here, $E_{k, \ell}$ is the matrix whose $k, \ell$ entry is 1 and other entries are 0 . Note that this is an orthonormal basis for $N\langle\cdot, \cdot\rangle_{\mathfrak{R}}$. We write this basis $\left\{X_{1}, \ldots, X_{N^{2}}\right\}$. The Brownian motion $\left(B_{t}\right)$ can be realized as

$$
\begin{equation*}
B_{t}=\sum_{k} X_{k} \tilde{B}_{t}^{k} \tag{2.3}
\end{equation*}
$$

where the ( $\tilde{B}^{k}$ )'s are independent standard Brownian motions. It goes back to Dyson 40 that the eigenvalues $\tilde{z}_{k}$ of $\left(\tilde{U}_{t}\right)$ satisfy

$$
\begin{equation*}
\mathrm{d} \tilde{z}_{k}=\frac{1}{\sqrt{N}} \mathrm{i} \tilde{z}_{k} \mathrm{~d} B_{k}-\frac{1}{N} \sum_{j \neq k} \frac{\tilde{z}_{k} \tilde{z}_{j}}{\tilde{z}_{k}-\tilde{z}_{j}} \mathrm{~d} t-\frac{1}{2} \tilde{z}_{k} \mathrm{~d} t \tag{2.4}
\end{equation*}
$$

In this paper, it will be more natural to consider a small time change in the unitary Brownian motion: the normalization

$$
\begin{equation*}
U_{t}:=\tilde{U}_{2 t} \tag{2.5}
\end{equation*}
$$

in other words the dynamics

$$
\begin{equation*}
\mathrm{d} U_{t}=\sqrt{2} U_{t} \mathrm{~d} B_{t}-U_{t} \mathrm{~d} t \tag{2.6}
\end{equation*}
$$

will provide convergence to the free field on the cylinder with its canonical, locally isotropic, covariance function $\mathbb{E}(h(z) h(w))=\pi\left(-\Delta_{\mathcal{C}}\right)^{-1}(z, w)$, as in Theorem 1.1. Moreover, 2.6 corresponds to the normalization in 95 , the first result on convergence of dynamics of random matrix type to the free field, as explained in Subsection 2.2. Indeed Spohn considers the $\beta$-Dyson Brownian motion on the unit circle, i.e. the time evolution of $N$ particles on the unit circle $\left\{e^{\mathrm{i} \theta_{1}(t)}, \ldots, e^{\mathrm{i} \theta_{N}(t)}\right\}$ satisfying

$$
\begin{equation*}
\mathrm{d} \theta_{j}=\frac{\beta}{2 N} \sum_{i \neq j} \cot \left(\frac{\theta_{j}-\theta_{i}}{2}\right) \mathrm{d} t+\sqrt{\frac{2}{N}} \mathrm{~d} B_{j}(t) \tag{2.7}
\end{equation*}
$$

where the $\left(B_{j}\right)$ 's are independent standard Brownian motions. For the unitary Brownian motions strong solutions exist as [23, Theorem 3.1] proves more generally that for $\beta \geqslant 1$, the particles almost surely do not collide but almost surely do when $\beta \in(0,1)$. With $z_{k}=e^{\mathrm{i} \theta_{k}}$, the dynamics 2.7 reads

$$
\begin{equation*}
\mathrm{d} z_{k}=\mathrm{i} z_{k} \sqrt{\frac{2}{N}} \mathrm{~d} B_{k}-\frac{\beta}{N} \sum_{j \neq k} \frac{z_{k} z_{j}}{z_{k}-z_{j}} \mathrm{~d} t+\frac{z_{k}}{N}\left(\frac{\beta}{2}-1\right) \mathrm{d} t-\frac{\beta}{2} z_{k} \mathrm{~d} t . \tag{2.8}
\end{equation*}
$$

By comparing $(2.4)$ and 2.8 , the dynamics of the eigenvalues of the unitary Brownian motion as normalized in 2.5 coincide with the $\beta$-Dyson Brownian motion from 95 when $\beta=2$.

Finally, we will use the Itô formula for the considered dynamics 2.6):

$$
\begin{equation*}
\mathrm{d} f\left(U_{t}\right)=\sqrt{2} \sum_{k} \mathcal{L}_{X_{k}} f\left(U_{t}\right) \mathrm{d} \tilde{B}_{t}^{k}+\Delta_{U(N)} f\left(U_{t}\right) \mathrm{d} t \tag{2.9}
\end{equation*}
$$

where $\mathcal{L}_{X} f(U)=\left.\frac{d}{d t}\right|_{t=0} f\left(U e^{t X}\right)$ and $\Delta_{U(N)} f(U)=\sum_{k} \frac{d^{2}}{d t^{2}}{ }_{t t=0} f\left(U e^{t X_{k}}\right)$ is the Laplacian on $U(N)$.
2.2 The characteristic polynomial process and the free field. In the paragraphs below, starting from a formal application of Spohn's result 95], we explain how the large dimension limit of the logarithm of the characteristic polynomial process is naturally related with dynamics associated with the GFF. These explanations are not necessary for proving our theorems, but they shed some lights on the structure of the main objects we consider. We also use this as an opportunity to set some notations and record covariance identities that we will use, in particular when stating the convergence to the chaos measures $e^{\gamma h}$ and $e^{\gamma \bar{h}}$.

Characteristic polynomial process induced by the Dyson dynamics. Given the dynamics (2.7), Spohn 95 considered the stochastic process (indexed by functions $f$ ) given by

$$
\xi_{N}(f, t):=\sum_{j=1}^{N} f\left(\theta_{j}(t)\right)
$$

As $\mathbb{E} \xi_{N}(f, t)=N \hat{f}_{0}=N f f$, it is natural to restrict to functions $f$ with zero mean and Spohn proved that the limiting dynamics are given, with $\Delta_{\mathbb{U}}=(\partial / \partial \theta)^{2}$, by

$$
\begin{equation*}
\mathrm{d} \xi(f, t)=\xi\left(-(\beta / 2) \sqrt{-\Delta_{\mathbb{U}}} f, t\right) \mathrm{d} t+\mathrm{d} \mathcal{W}\left(f^{\prime}, t\right) \tag{2.10}
\end{equation*}
$$

where $d \mathcal{W}(f, t)$ is a Gaussian noise characterized by $\mathbb{E}(d \mathcal{W}(f, t) d \mathcal{W}(g, s))=2 \delta(t-s) d t d s \frac{1}{2 \pi} \int_{0}^{2 \pi} f(x) g(x) d x$.
Now, we discuss the characteristic polynomial process induced by these dynamics, namely

$$
\begin{equation*}
h_{N}(t, x):=\xi_{N}\left(f_{x}, t\right) \tag{2.11}
\end{equation*}
$$

where $f_{x}(\theta):=\log \left|e^{\mathrm{i} \theta}-e^{\mathrm{i} x}\right|=-\operatorname{Re} \sum_{k \geqslant 1} \frac{1}{k} e^{\mathrm{i} k \theta} e^{-i k x}=-\sum_{k \geqslant 1} \frac{1}{k} \cos (k(\theta-x))$. This field has zero mean in the sense that for every $N, t, \int_{\mathbb{U}} h_{N}(t, \cdot)=0$. We formally take $f=f_{x}$ in 2.10 and look for the induced dynamics. Note first that $\sqrt{-(\partial / \partial \theta)^{2}} f_{x}(\theta)=\sqrt{-(\partial / \partial x)^{2}} f_{x}(\theta)$ so the drift is given by $-\frac{\beta}{2}\left(-\Delta_{\mathbb{U}}\right)^{1 / 2}$. Concerning the noise part, an elementary calculation gives

$$
\mathbb{E}\left(\mathcal{W}\left(f_{x}^{\prime}, t\right) \mathcal{W}\left(f_{y}^{\prime}, t\right)\right)=2 \frac{1}{2 \pi} \int_{0}^{2 \pi} f_{x}^{\prime}(\theta) f_{y}^{\prime}(\theta) d \theta=\pi \delta(x-y)
$$

where $W$ is an $L^{2}(\lambda)$ space-time white noise with zero mean (see below 2.14) for a representation with Brownian motions). Altogether, it is natural to expect from Spohn's result that

$$
\begin{equation*}
\mathrm{d} h_{t}=-\frac{\beta}{2}\left(-\Delta_{\mathbb{U}}\right)^{1 / 2} h_{t} \mathrm{~d} t+\sqrt{\pi} W(\mathrm{~d} x, \mathrm{~d} t) \tag{2.12}
\end{equation*}
$$

Note also that $\int_{\mathbb{U}} h_{t}(x) \mathrm{d} x=0$ for every $t \in \mathbb{R}$ since $h_{t}(x)=\lim _{N} \sum \log \left|e^{\mathrm{i} \theta_{k}^{N}(t)}-e^{\mathrm{i} x}\right|$.
Dynamics of the averaged trace of the $2 d$ GFF on Euclidean circles. We consider here the trace of the whole-plane GFF on Euclidean circles and explain in which sense the dynamics $(2.12)$ are related to it. The whole-plane GFF can be seen as a $\sigma$-finite measure (with Lebesgue measure on the zero mode) or as a random field modulo constant. Recalling that in the context of characteristic polynomials $\int_{\mathbb{U}} h_{N}(t, \cdot)=0$, we are here therefore only interested in $h_{t}=\Phi\left(e^{-t}.\right)-f \Phi\left(e^{-t}.\right)$, where $\Phi$ is a whole plane GFF, and this doesn't depend on the zero mode of the free field (so, for instance one can take $\Phi$ to have zero mean on $\mathbb{U}$ for which the covariance is given in [96, Section 2.1.1], for more on the GFF, see 90,34 ). From the log-covariance of the whole-plane GFF, one has (see, e.g., 70, Section 3]),

$$
\begin{equation*}
\left.\mathbb{E}\left(h_{s}\left(e^{\mathrm{i} x}\right) h_{t}\left(e^{\mathrm{i} y}\right)\right)\right)=\log \frac{\max \left(\left|e^{-s}\right|,\left|e^{-t}\right|\right)}{\left|e^{-s} e^{\mathrm{i} x}-e^{-t} e^{\mathrm{i} y}\right|} \tag{2.13}
\end{equation*}
$$

In particular, $\mathbb{E}\left(h_{0}\left(e^{\mathrm{i} x}\right) h_{0}\left(e^{\mathrm{i} y}\right)\right)=-\log \left|e^{\mathrm{i} x}-e^{\mathrm{i} y}\right|$ and $h_{0}$ can be realized as $h_{0}=\sum_{k} A_{k}(0) \cos (k \cdot)+$ $B_{k}(0) \sin (k \cdot)$ where $\left(A_{k}(0)\right)$ and $\left(B_{k}(0)\right)$ are independent Gaussian variables, with $A_{k}(0) \sim B_{k}(0) \sim \mathcal{N}\left(0, \frac{1}{k}\right)$. $\mathrm{H}=\mathrm{H}^{1 / 2}$ is exactly the Cameron-Martin space of $h_{0}$.

The Gaussian field given by 2.13 has the same distribution as the one given by the following dynamics

$$
\begin{equation*}
\mathrm{d} h_{t}=-\left(-\Delta_{\mathbb{U}}\right)^{1 / 2} h_{t} \mathrm{~d} t+\sqrt{2 \pi} W(\mathrm{~d} t, \mathrm{~d} w) \tag{2.14}
\end{equation*}
$$

where $W$ is an $L^{2}(\lambda)$ space-time white noise on the unit circle and $h_{0}$ has the distribution of a centered Gaussian field with covariance given by $\mathbb{E}\left(h_{0}\left(e^{\mathrm{i} x}\right) h_{0}\left(e^{\mathrm{i} y}\right)\right)=-\log \left|e^{\mathrm{i} x}-e^{\mathrm{i} y}\right|$. The space-time white noise $W(\mathrm{~d} t, \mathrm{~d} w)$ can be realized as $\sum_{k \geqslant 1} \frac{\cos (k \cdot)}{\sqrt{\pi}} \mathrm{d} V_{k}(t)+\frac{\sin (k \cdot)}{\sqrt{\pi}} \mathrm{d} W_{k}(t)$ for some independent standard Brownian motions $\left(V_{k}\right)$, ( $W_{k}$ ). Therefore, with $h_{t}=\sum_{k} A_{k}(t) \cos (k \cdot)+B_{k}(t) \sin (k \cdot)$, the above dynamics can be written as $\mathrm{d} A_{k}(t)=-k A_{k}(t) \mathrm{d} t+\sqrt{2} \mathrm{~d} V_{k}(t)$ and, similarly, $\mathrm{d} B_{k}(t)=-k B_{k}(t) \mathrm{d} t+\sqrt{2} \mathrm{~d} W_{t}$. This is an infinite dimensional Ornstein-Uhlenbeck process and $A_{k}(t)=e^{-k t} A_{k}(0)+\sqrt{2} \int_{0}^{t} e^{-k(t-s)} \mathrm{d} V_{k}(s)$ (similarly for $B_{k}$ ).

The identification in law of these two processes follows by a covariance calculation since both fields are Gaussian. Indeed, using the coordinates $z=t+\mathrm{i} x, w=s+\mathrm{i} y$ so $\max (t, s)=\log \max \left(\left|e^{z}\right|,\left|e^{w}\right|\right)$, this follows from

$$
\sum_{k \geqslant 1} \frac{\cos (k(x-y))}{k} e^{-k|t-s|}=-\log \left|1-e^{-|t-s|} e^{\mathrm{i}(y-x)}\right|=\log \frac{\max \left(\left|e^{z}\right|,\left|e^{w}\right|\right)}{\left|e^{z}-e^{w}\right|}
$$

Note that if $\left(h_{t}\right)$ solves (2.14), $\tilde{h}_{t}=a h_{b t}$ solves $\mathrm{d} \tilde{h}_{t}=-b\left(-\Delta_{\mathbb{U}}\right)^{1 / 2} \tilde{h}_{t} \mathrm{~d} t+a \sqrt{b} \sqrt{2 \pi} \widetilde{W}(\mathrm{~d} x, \mathrm{~d} t)$.
2.12) is natural from the point of view of the characteristic polynomial process. From the GFF point of view, the explicit form of 2.14 naturally arises from the Markov property of the free field. Indeed, instead of viewing $\left(h_{t}\right)$ as the trace of the free field on $e^{-t} \mathbb{U}$, it is equivalent to view it as the harmonic part of the Markov decomposition of $\Phi$ on $e^{-t} \mathbb{D}, h_{t}(z)=H h_{t \mid \mathbb{U}}(z)$ where $H$ denotes the harmonic extension. Then, writing $\Phi=h_{0}+\phi_{0}$ on $\mathbb{D}$, where $\phi_{0}$ is an independent GFF with zero boundary values, it follows that

$$
\begin{equation*}
h_{t}(z)=h_{0}\left(e^{-t} z\right)+H_{t}\left(\phi_{0}\right)\left(e^{-t} z\right) \tag{2.15}
\end{equation*}
$$

where $H_{t}$ denotes the harmonic projection on $e^{-t} \mathbb{D}$. 2.15 readily implies that $\left(h_{t}\right)$ is a Markov process. On the circle $w \in \mathbb{U}$, formally, $\left.\frac{\mathrm{d}}{\mathrm{d} t}\right|_{t=0} h_{0}\left(e^{-t} w\right)=\frac{\mathrm{d}}{\mathrm{d} t \mid t=0}{ }_{H h_{0}}\left(e^{-t} w\right)=\partial_{n} H h_{0}$ where $\partial_{n}$ is the inward pointing normal derivative and $\partial_{n} H$ is the Dirichlet-to-Neumann operator, which here coincides with $-\left(-\Delta_{\mathbb{U}}\right)^{1 / 2}$. This is a formal way for retrieving the drift part of 2.14 . In fact, from 2.15 and using the martingale problem approach, one can rigorously prove that the dynamics of $\left(h_{t}\right)$ are given by (2.14). This approach is more robust and avoids having to guess the exact dynamics. For more details, a generalization can be found in 35 which considers instead of Euclidean growth the metric growth associated with the LQG metric.

Free field on the cylinder. When $\beta=2$, the covariance of the limiting field associated with 2.12 is

$$
\begin{equation*}
\mathbb{E}(h(z) h(w))=\frac{1}{2} \log \frac{\max \left(\left|e^{z}\right|,\left|e^{w}\right|\right)}{\left|e^{z}-e^{w}\right|}=\frac{1}{2} \sum_{k \geqslant 1} \frac{\cos (k(x-y))}{k} e^{-k|t-s|}=\mathrm{P}_{|t-s|} C(x-y) \tag{2.16}
\end{equation*}
$$

where

$$
\begin{equation*}
C(x, y)=C(x-y)=-\frac{1}{2} \log \left|e^{\mathrm{i} x}-e^{\mathrm{i} y}\right| \tag{2.17}
\end{equation*}
$$

This is an expression of the Green function associated with the Laplacian on $\mathcal{C}:=\mathbb{R} \times \mathbb{U}, \Delta_{\mathcal{C}}=\partial_{t}^{2}+\partial_{\theta}^{2}$. Indeed, with $\hat{F}(\xi, k):=\frac{1}{2 \pi} \int_{\mathbb{R}} \int_{\mathbb{U}} F(t, x) e^{-\mathrm{i} t \xi} e^{-\mathrm{i} k x} \mathrm{~d} t \mathrm{~d} x$, we have $F(t, x)=\frac{1}{2 \pi} \sum_{k \neq 0} \int_{\mathbb{R}} \hat{F}(\xi, k) e^{\mathrm{i} k x} e^{\mathrm{i} t \xi} \mathrm{~d} \xi$ so $-\Delta_{\mathcal{C}} F(t, x)=\frac{1}{2 \pi} \sum_{k \neq 0} \int_{\mathbb{R}}\left(k^{2}+\xi^{2}\right) \hat{F}(\xi, k) e^{\mathrm{i} k x} e^{\mathrm{i} t \xi} \mathrm{~d} \xi$ and $\left(-\Delta_{\mathcal{C}}\right)^{-1}$ has symbol given by $\frac{1}{k^{2}+\xi^{2}}$. We retrieve the covariance kernel

$$
\left(-\Delta_{\mathcal{C}}\right)^{-1} F(t, x)=\frac{1}{2 \pi} \sum_{k \neq 0} \int_{\mathbb{R}} \hat{F}(\xi, k) \frac{e^{\mathrm{i} k x} e^{\mathrm{i} t \xi}}{k^{2}+\xi^{2}} \mathrm{~d} \xi=\int_{\mathbb{R} \times \mathbb{U}} F(s, y)\left(-\Delta_{\mathcal{C}}^{-1}\right)(s, x ; t, y) \mathrm{d} s \mathrm{~d} y
$$

where $\left(-\Delta_{\mathcal{C}}\right)^{-1}(s, x ; t, y)$ is given by

$$
\frac{1}{(2 \pi)^{2}} \sum_{k \neq 0} \int_{\mathbb{R}} \frac{e^{\mathrm{i} k(x-y)} e^{\mathrm{i} \xi(t-s)}}{k^{2}+\xi^{2}} \mathrm{~d} \xi=\frac{1}{(2 \pi)^{2}} \sum_{k \neq 0} \int_{\mathbb{R}} \frac{1}{k^{2}} \frac{e^{\mathrm{i} k(x-y)} e^{\mathrm{i} \xi(t-s)}}{1+(\xi / k)^{2}} \mathrm{~d} \xi=\frac{1}{(2 \pi)^{2}} \sum_{k \neq 0} \int_{\mathbb{R}} \frac{1}{|k|} \frac{e^{\mathrm{i} k(x-y)} e^{\mathrm{i} \omega k(t-s)}}{1+\omega^{2}} \mathrm{~d} \omega .
$$

By using $\frac{1}{\pi} \int_{\mathbb{R}} \frac{e^{\mathrm{i} \omega x}}{1+\omega^{2}} \mathrm{~d} \omega=e^{-|x|}$, we get $\frac{1}{4 \pi} \sum_{k \neq 0} \frac{1}{|k|} e^{i k(x-y)} e^{-|k||t-s|}=\frac{1}{2 \pi} \sum_{k \geqslant 1} \frac{\cos (k(x-y))}{k} e^{-|k||t-s|}$ hence

$$
\begin{equation*}
\mathbb{E}(h(z) h(w))=\mathbb{E}(h(s, x) h(t, y))=\pi\left(-\Delta_{\mathcal{C}}\right)^{-1}(s, x ; t, y) \tag{2.18}
\end{equation*}
$$

2.3 Some formulas. In the following paragraphs, we present some standard formulas, accompanied with a proof to be self-contained and some identities that will be used later on in the manuscript.

Helffer-Sjőstrand formula. This paragraph presents the natural unitary analogue of the classical HelfferSjőstrand formula, originally used to develop an alternative functional calculus for self-adjoint operators 30 and of great use in random matrix theory, see 42].

Let $\tilde{g}=g(w)$ be a quasi-analytic extension of $g$, i.e. $g$ and $\tilde{g}$ coincide on the unit circle and $\partial_{\bar{w}} \tilde{g}(w)=$ $\mathrm{O}(||w|-1|)$ (this property will eventually be essential when bounding some error terms. We could also
impose $\partial_{\bar{w}} \tilde{g}(w)=\mathrm{O}\left(\| w|-1|^{p}\right)$ for arbitrary fixed $p \geqslant 1$ but this typically does not give any improvement in the following argument). In practice we will use the following natural analogue of the Hermitian formulas from 30, 42, with representation in polar coordinates $\left(w=r e^{\mathrm{i} \theta}\right)$, as in 2]:

$$
\begin{equation*}
\tilde{g}(w)=\left(g\left(e^{\mathrm{i} \theta}\right)-\mathrm{i} g^{\prime}\left(e^{\mathrm{i} \theta}\right) \log r\right) \chi(r) \tag{2.19}
\end{equation*}
$$

where $\chi=\chi_{c}=1$ on $\exp ([-c, c]), 0$ on $\exp \left([-2 c, 2 c]^{c}\right)$, and $\left|\chi^{\prime}\right| \leqslant 10 c^{-1},\left|\chi^{\prime \prime}\right| \leqslant 10 c^{-2}$. Furthermore, we used the notation $g^{\prime}\left(e^{\mathrm{i} \theta}\right)$ for the differential of $\theta \mapsto g\left(e^{\mathrm{i} \theta}\right)$, and similarly for $g^{\prime \prime}$. Note that for this specific form of $\tilde{g}$ we have

$$
\begin{equation*}
\partial_{\bar{w}} \tilde{g}(w)=\frac{e^{\mathrm{i} \theta}}{2}\left(g\left(e^{\mathrm{i} \theta}\right)-\mathrm{i} g^{\prime}\left(e^{\mathrm{i} \theta}\right) \log r\right) \chi^{\prime}(r)+\frac{e^{\mathrm{i} \theta}}{2 r} g^{\prime \prime}\left(e^{\mathrm{i} \theta}\right) \chi(r) \log r . \tag{2.20}
\end{equation*}
$$

Let $m$ denote the Lebesgue measure on $\mathbb{C}$. Assume also that $\tilde{g}$ is compactly supported. Green's theorem in complex coordinates can be written (in the case of outer boundary)

$$
\int_{D} \partial_{\bar{w}} f(w) \mathrm{d} m(w)=\frac{1}{2} \int_{D}\left(\partial_{x} f-\partial_{y}(-\mathrm{i} f)\right) \mathrm{d} m(w)=\frac{1}{2} \int_{\partial D}(-\mathrm{i} f \mathrm{~d} x+f \mathrm{~d} y)=-\frac{\mathrm{i}}{2} \int_{\partial D} f(w) \mathrm{d} w
$$

This gives, for any $|z| \leqslant 1$, (note that we have a sign change due to inner boundary)

$$
\begin{align*}
& \frac{1}{\pi} \int_{|w|>1} \partial_{\bar{w}} \tilde{g}(w) \cdot \frac{z+w}{z-w} \frac{\mathrm{~d} m(w)}{w}=\frac{1}{\pi} \int_{|w|>1} \partial_{\bar{w}}\left(\tilde{g}(w) \frac{z+w}{z-w}\right) \frac{\mathrm{d} m(w)}{w}= \\
& \frac{\mathrm{i}}{2 \pi} \int_{|w|=1} g(w) \frac{z+w}{z-w} \frac{\mathrm{~d} w}{w}=-\int_{0}^{2 \pi} g\left(e^{\mathrm{i} \theta}\right) \frac{z+e^{\mathrm{i} \theta}}{z-e^{\mathrm{i} \theta}} \frac{\mathrm{~d} \theta}{2 \pi} \tag{2.21}
\end{align*}
$$

For $z=r e^{i \phi}$ and $r<1$, this gives

$$
\begin{equation*}
\operatorname{Re} \frac{1}{\pi} \int_{|w|>1} \partial_{\bar{w}} \tilde{g}(w) \cdot \frac{z+w}{z-w} \frac{\mathrm{~d} m(w)}{w}=\int_{0}^{2 \pi} g\left(e^{\mathrm{i} \theta}\right) \operatorname{Re} \frac{1+r e^{\mathrm{i}(\phi-\theta)}}{1-r e^{\mathrm{i}(\phi-\theta)}} \frac{\mathrm{d} \theta}{2 \pi}=\left(\mathrm{P}_{-\log r} g\right)\left(e^{\mathrm{i} \phi}\right) \tag{2.22}
\end{equation*}
$$

Moreover, for any $|z| \geqslant 1$,

$$
\begin{aligned}
& \frac{1}{\pi} \int_{|w|<1} \partial_{\bar{w}} \tilde{g}(w) \cdot \frac{z+w}{z-w} \frac{\mathrm{~d} m(w)}{w}=\frac{1}{\pi} \int_{|w|<1} \partial_{\bar{w}}\left(\tilde{g}(w) \frac{z+w}{z-w}\right) \frac{\mathrm{d} m(w)}{w}= \\
&-\frac{\mathrm{i}}{2 \pi} \int_{|w|=1} g(w) \frac{z+w}{z-w} \frac{\mathrm{~d} w}{w}=\int_{0}^{2 \pi} g\left(e^{\mathrm{i} \theta}\right) \frac{z+e^{\mathrm{i} \theta}}{z-e^{\mathrm{i} \theta}} \frac{\mathrm{~d} \theta}{2 \pi}
\end{aligned}
$$

Finally, for general $z$ we have

$$
\begin{align*}
\frac{1}{2 \pi} \int_{\mathbb{C}} \partial_{\bar{w}} \tilde{g}(w) \cdot \frac{z+w}{z-w} \frac{\mathrm{~d} m(w)}{w}= & \frac{1}{2 \pi} \lim _{\varepsilon \rightarrow 0} \int_{D(z, \varepsilon)^{\mathrm{c}}} \partial_{\bar{w}}\left(\tilde{g}(w) \frac{z+w}{z-w}\right) \frac{\mathrm{d} m(w)}{w}= \\
& \frac{\mathrm{i}}{4 \pi} \lim _{\varepsilon \rightarrow 0} \int_{C(z, \varepsilon)} \tilde{g}(w) \frac{z+w}{z-w} \frac{\mathrm{~d} w}{w}=\frac{\mathrm{i}}{2 \pi} \tilde{g}(z) \lim _{\varepsilon \rightarrow 0} \int_{C(z, \varepsilon)} \frac{1}{z-w} \mathrm{~d} w=\tilde{g}(z) \tag{2.23}
\end{align*}
$$

Poisson summation. We denote by $p_{t}(x)$ the one-dimensional heat kernel on the real line, i.e., $p_{t}(x)=$ $\frac{e^{-x^{2} / 2 t}}{\sqrt{2 \pi t}}$. The formula below is a generalization of the usual Poisson summation formula and is related with the transformation formula of the theta function.
Lemma 2.2. For every $\delta \in \mathbb{R}, x \in \mathbb{R}$ and $t>0, \sum_{k \in \mathbb{Z}} e^{2 \mathrm{i} \pi k \delta} p_{t}(x+2 k \pi)=\frac{1}{2 \pi} \sum_{n \in \mathbb{Z}} e^{\mathrm{i} x(n+\delta)} e^{-\frac{(n+\delta)^{2} t}{2}}$.
Proof. This follows by writing, with $B_{t}$ distributed as a centered Gaussian variable with variance $t$,

$$
e^{-\frac{(n+\delta)^{2} t}{2}}=\mathbb{E}\left(e^{i(n+\delta) B_{t}}\right)=\sum_{k \in \mathbb{Z}} \int_{2 k \pi}^{2(k+1) \pi} e^{\mathrm{i}(n+\delta) y} p_{t}(y) \mathrm{d} y=\sum_{k \in \mathbb{Z}} \int_{0}^{2 \pi} e^{\mathrm{i}(n+\delta)(u+2 k \pi)} p_{t}(u+2 k \pi) \mathrm{d} u
$$

multiplying it by $e^{-\mathrm{i} y(n+\delta)}$ and by summation, i.e.

$$
\sum_{n \in \mathbb{Z}} e^{-\mathrm{i} y(n+\delta)} e^{-\frac{(n+\delta)^{2} t}{2}}=\lim _{N \rightarrow \infty} \int_{0}^{2 \pi}\left(\sum_{n=-N}^{N} e^{\mathrm{i} n(u-y)}\right) e^{\mathrm{i} \delta(u-y)} \sum_{k \in \mathbb{Z}} e^{2 \mathrm{i} k \pi \delta} p_{t}(u+2 k \pi) \mathrm{d} u
$$

The limit follows from basic properties of the Dirichlet kernel.
$1 d$ Markov processes such as random walks or diffusions conditioned not to intersect arise in many statistical mechanics models. In the continuous setting, the Karlin-McGregor formula 66 allows to understand the probability distribution of these non-intersecting paths by viewing them as measures defined by products of several determinants. The Eynard-Mehta theorem states that these are determinantal point processes (point processes for which the correlation functions can be expressed as determinants of an associated kernel), a large class that appears in random matrix theory, growth processes, directed polymers, tilings and combinatorics, to name a few. Nice introductions and more background can be found in 63,18 and references therein.
3.1 The extended kernel. Motivated by universality associated with nonequilibrium eigenvalue statistics, Pandey and Shukla 80 studied in 1991 the Dyson dynamics with $\beta=2$ started from two initial conditions, COE and CSE, and expressed their correlation functions as determinants. Below, we show that when started from equilibrium, namely CUE initial condition, the associated process is a determinantal point process and provide an expression of its kernel. We have a modern treatment, using the Eynard-Mehta theorem and we then discuss the case of arbitrary initial conditions. As a comparison, the stationary GUE case where the Brownian motions are on the real line instead of the circle can be found in 62 (see, e.g., Equation (2.12)). Here, some extra care is needed, one of the reasons being that there is no canonical ordering of the particles since they are winding around the unit circle.

Proposition 3.1. The eigenvalues of the unitary Brownian motion $\left(U_{t}\right)_{t \geqslant 0}$ from (2.6), started from the Haar measure $\left\{\left(j, e^{\mathrm{i} \theta_{k}\left(t_{j}\right)}\right)_{1 \leqslant k \leqslant N}: 1 \leqslant j \leqslant J\right\}$ form a determinantal point process with kernel given by

$$
\begin{align*}
K(i, x ; j, y)= & \frac{\mathbb{1}_{i \leqslant j}}{2 \pi} e^{-\left(\frac{N-1}{2}\right)^{2} \frac{\left|t_{i}-t_{j}\right|}{N}} \sum_{1 \leqslant k \leqslant N} e^{\left(k-\frac{N+1}{2}\right)^{2} \frac{\left|t_{i}-t_{j}\right|}{N}} e^{\mathrm{i}(x-y)\left(k-\frac{N+1}{2}\right)}  \tag{3.1}\\
& -\frac{\mathbb{1}_{i>j}}{2 \pi} e^{\left(\frac{N-1}{2}\right)^{2} \frac{\left|t_{i}-t_{j}\right|}{N}} \sum_{k \in[1, N]^{c}} e^{-\left(k-\frac{N+1}{2}\right)^{2} \frac{\left|t_{i}-t_{j}\right|}{N}} e^{\mathrm{i}(x-y)\left(k-\frac{N+1}{2}\right)} . \tag{3.2}
\end{align*}
$$

Namely, for any bounded and measurable function $g: \llbracket 1, J \rrbracket \times \mathbb{U} \rightarrow \mathbb{R}$, we have

$$
\mathbb{E}\left(\prod_{j=1}^{J} \prod_{i=1}^{N}\left(1+g\left(j, z_{i}\left(t_{j}\right)\right)\right)=\sum_{k=0}^{\infty} \frac{1}{k!} \int_{(\llbracket 1, J \rrbracket \times \mathbb{U})^{k}}\left(\prod_{j=1}^{k} g\left(j, x_{j}\right)\right) \operatorname{det}\left(K\left(\left(r_{i}, x_{i}\right) ;\left(r_{j}, x_{j}\right)\right)_{i, j=1}^{k} \lambda(d x) \#(d r)\right.\right.
$$

Sketch of the proof. First, using [55], we give an expression of the transition probability of Brownian motions on the circle conditioned on non-intersecting for all time. Then, using an argument from 5], we rewrite it as a product of determinants in order to apply the Eynard-Mehta theorem and compute thereby an expression of the associated extended kernel.

Proof. To lighten the notations, we prove it for $J=2$, the generalization to any fixed $J$ is straightforward. First, we need a result by Hobson and Werner [55]. In this paper, the authors consider Brownian motions on the circle killed when intersecting. Conditioning on non-intersecting (for all times) corresponds to considering the dynamics

$$
\mathrm{d} \theta_{j}=\frac{1}{2} \sum_{i \neq j} \cot \left(\frac{\theta_{j}-\theta_{i}}{2}\right) \mathrm{d} t+\mathrm{d} B_{j}(t)
$$

see (4.1) in their paper, where the $\theta_{j}$ 's are the angles and the $B_{j}$ 's are standard Brownian motions. This is the time change $t \rightarrow \frac{t N}{2}$ and $\beta=2$ in 2.7 (so we will eventually take $t \rightarrow \frac{2 t}{N}$ in our formula).

Let $A_{s, t}$ be the event that trajectories do not intersect between times $s$ and $t$, and $\mathbb{P}$ the distribution if independent BMs on the torus. With the notations from [55], the transition probability $q_{t}$ of $Z$ ((4.1) in 55) is

$$
\begin{align*}
q_{t}(x, y)=\lim _{T \rightarrow \infty} \mathbb{P}\left((x, 0) \rightarrow(y, t) \mid A_{0, T}\right)=\lim _{T \rightarrow \infty} & \frac{\mathbb{P}\left((x, 0) \rightarrow(y, t), A_{0, t}\right) \mathbb{P}_{y}\left(A_{0, T-t}\right)}{\mathbb{P}_{x}\left(A_{0, T}\right)} \\
& =\lim _{T \rightarrow \infty} \frac{\mathbb{P}_{y}\left(A_{0, T-t}\right)}{\mathbb{P}_{x}\left(A_{0, T}\right)} q_{t}^{*}(x, y)=e^{\lambda_{N} t} \frac{|\Delta(y)|}{|\Delta(x)|} q_{t}^{*}(x, y) \tag{3.3}
\end{align*}
$$

where we used the notation $\Delta(x)=\prod_{k<\ell}\left(e^{\mathrm{i} x_{\ell}}-e^{\mathrm{i} x_{k}}\right)$ and the result from 55:

$$
\mathbb{P}_{x}\left(A_{0, T}\right) \underset{T \rightarrow \infty}{\sim} c_{N} e^{-\lambda_{N} T}|\Delta(x)|, \quad \lambda_{N}:=\frac{N(N-1)(N+1)}{24}
$$

Here, $q_{t}^{*}$ denotes the transition density of $N$ Brownian motions on the circle killed when any two of them collide. 55 gives an expression of this term and we borrow an argument by Arista and O'Connell 5. Section 5.1] to rewrite it. When $x, y$ belong to the set $\left\{z_{1}<\cdots<z_{N}<z_{1}+2 \pi\right\} \cap\left\{z_{1} \in[-\pi, \pi)\right\}$,

$$
q_{t}^{*}\left(e^{\mathrm{i} x}, e^{\mathrm{i} y}\right)=\frac{1}{N} \sum_{u=0}^{N-1} \operatorname{det}\left(\sum_{k \in \mathbb{Z}} \eta^{u k} p_{t}\left(x_{i}, y_{j}+2 \pi k\right)\right)
$$

where $\eta=e^{\mathrm{i} \frac{2 \pi}{N}}$. With $\nu_{[\ell]}$ the representative of $\nu$ shifted by $\ell$ in $\left\{z_{1}<\cdots<z_{N}<z_{1}+2 \pi\right\} \cap\left\{z_{1} \in[-\pi, \pi)\right\}$ (i.e., $z_{i} \rightarrow z_{i+\ell} \bmod N$ ), it was remarked in 5] that

$$
\begin{equation*}
\sum_{\ell=0}^{N-1} q_{t}^{*}\left(e^{\mathrm{i} x}, e^{\mathrm{i} y_{[\ell]}}\right)=\operatorname{det}\left(\sum_{k \in \mathbb{Z}}(-1)^{k(N-1)} p_{t}\left(x_{i}, y_{j}+2 k \pi\right)\right) \tag{3.4}
\end{equation*}
$$

The point process induced by the (ordered) vector $Z_{t}=\left\{e^{\mathrm{i} \theta_{1}(t)}, \ldots, e^{\mathrm{i} \theta_{N}(t)}\right\}$ is associated with counting functions $M_{U}\left(Z_{t}\right)$ where $U$ is an open subset of $\mathbb{U}$. Using that $F\left(M_{U}(w)\right)$ is invariant under permutation and that the application $y \mapsto y_{[\ell]}$ is measure preserving, we have

$$
\left.\int_{\text {ordered }} q_{t}\left(x, y_{[\ell]}\right) F\left(M_{U}(y)\right) \mathrm{d} y=\int_{\text {ordered }} q_{t}\left(x, y_{[\ell]}\right) F\left(M_{U}\left(y_{[\ell]}\right)\right)\right) \mathrm{d} y=\int_{\text {ordered }} q_{t}(x, y) F\left(M_{U}(y)\right) \mathrm{d} y
$$

where "ordered" $=\left\{w=\left(e^{\mathrm{i} z_{i}}\right)_{1 \leqslant i \leqslant N}: z_{1}<\cdots<z_{N}<z_{1}+2 \pi, z_{1} \in[-\pi, \pi)\right\}$. So, by using that $\left|\Delta\left(y_{[\ell]}\right)\right|=|\Delta(y)|$ and combining (3.3) and (3.4), we have

$$
\mathbb{E}_{x}\left(F\left(M_{U}\left(Z_{t}\right)\right)\right)=\int_{\text {ordered }} \frac{1}{N} \sum_{\ell=0}^{N-1} q_{t}\left(x, y_{[\ell]}\right) F\left(M_{U}(y)\right) \mathrm{d} y=\int_{\text {ordered }} w_{t, x}^{N}(y) F\left(M_{U}(y)\right) \mathrm{d} y
$$

where

$$
\begin{equation*}
w_{t, x}^{N}(y):=\frac{e^{\lambda_{N} t}}{N} \frac{|\Delta(y)|}{|\Delta(x)|} \operatorname{det}\left(\sum_{k \in \mathbb{Z}}(-1)^{k(N-1)} p_{t}\left(x_{i}, y_{j}+2 k \pi\right)\right) \tag{3.5}
\end{equation*}
$$

Note that when $y_{1}<\cdots<y_{N}<y_{1}+2 \pi$, for $k<\ell,\left|e^{\mathrm{i} y_{\ell}}-e^{\mathrm{i} y_{k}}\right|=2\left|\sin \left(\frac{y_{\ell}-y_{k}}{2}\right)\right|=2 \sin \left(\frac{y_{\ell}-y_{k}}{2}\right)$ since $y_{\ell}-y_{k} \in(0,2 \pi)$ hence

$$
|\Delta(y)|=\prod_{k<\ell} 2\left(e^{\mathrm{i} y_{\ell}}-e^{\mathrm{i} y_{k}}\right) \cdot \frac{e^{-\mathrm{i} \frac{y_{k}+y_{\ell}}{2}}}{2 \mathrm{i}}=\mathrm{i}^{-\frac{N(N-1)}{2}} \Delta\left(e^{\mathrm{i} y_{1}}, \ldots, e^{\mathrm{i} y_{N}}\right) e^{-\mathrm{i} \frac{N-1}{2} \sum y_{k}}=\mathrm{i}^{-\frac{N(N-1)}{2}} \operatorname{det}\left(e^{\mathrm{i} y_{i}\left(j-1-\frac{N-1}{2}\right)}\right)
$$

So, 3.5 is invariant under permutation of the $x_{i}$ 's and under permutation of the $y_{i}$ 's.
Starting from the Haar measure, for symmetric functions $F$ and $G$, we have

$$
\begin{aligned}
\mathbb{E}\left(F\left(Z_{0}\right) G\left(Z_{t}\right)\right) & \propto \int_{\mathbb{U}^{N}} F(x) \mathbb{E}_{x}\left(G\left(Z_{t}\right)\right)|\Delta(x)|^{2} \mathrm{~d} x \\
& \propto \int_{\text {ordered }^{2}} F(x) G(y) w_{t, x}^{N}(y)|\Delta(x)|^{2} \mathrm{~d} x \mathrm{~d} y
\end{aligned}
$$

Furthermore, $|\Delta(x)|^{2}=\prod_{k<\ell}\left(e^{\mathrm{i} x_{\ell}}-e^{\mathrm{i} x_{k}}\right) \prod_{k<\ell}\left(e^{-\mathrm{i} x_{\ell}}-e^{-\mathrm{i} x_{k}}\right)=\Delta\left(e^{\mathrm{i} x_{1}}, \ldots, e^{\mathrm{i} x_{N}}\right) \Delta\left(e^{-\mathrm{i} x_{1}}, \ldots, e^{-\mathrm{i} x_{N}}\right)$, so

$$
\frac{|\Delta(y)|}{|\Delta(x)|}|\Delta(x)|^{2}=\operatorname{det}\left(e^{\mathrm{i} y_{i}\left(j-\frac{N+1}{2}\right)}\right) \Delta\left(e^{-\mathrm{i} x_{1}}, \ldots, e^{-\mathrm{i} x_{N}}\right) e^{+\mathrm{i} \frac{N-1}{2} \sum x_{k}}=\operatorname{det}\left(e^{-\mathrm{i} x_{i}\left(j-\frac{N+1}{2}\right)}\right) \operatorname{det}\left(e^{\mathrm{i} y_{i}\left(j-\frac{N+1}{2}\right)}\right)
$$

and the joint density is proportional to

$$
\operatorname{det}\left(e^{-\mathrm{i} x_{i}\left(j-\frac{N+1}{2}\right)}\right) \operatorname{det}\left(\sum_{k \in \mathbb{Z}}(-1)^{k(N-1)} p_{t}\left(x_{i}, y_{j}+2 k \pi\right)\right) \operatorname{det}\left(e^{\mathrm{i} y_{i}\left(j-\frac{N+1}{2}\right)}\right) .
$$

We conclude that the weight function associated to our random point process is of the form a product of several determinants. By the Eynard-Mehta theorem [43] (see 63, Section 2] or [18, Theorem 4.2]), this is a determinantal point process, with kernel given by

$$
\begin{aligned}
& K(0, x ; 0, y)=\sum_{1 \leqslant i, j \leqslant N}\left(G^{-T}\right)_{i, j} \Phi_{i}(x) \int_{\mathbb{U}} T(y, z) \Psi_{j}(z) \lambda(\mathrm{d} z) \\
& K(0, x ; 1, y)=\sum_{1 \leqslant i, j \leqslant N}\left(G^{-T}\right)_{i, j} \Phi_{i}(x) \Psi_{j}(y) \\
& K(1, x ; 0, y)=-T(y, x)+\sum_{1 \leqslant i, j \leqslant N}\left(G^{-T}\right)_{i, j} \int_{\mathbb{U}} \Phi_{i}(z) T(z, x) \lambda(\mathrm{d} z) \int_{\mathbb{U}} T(y, z) \Psi_{j}(z) \lambda(\mathrm{d} z) \\
& K(1, x ; 1, y)=\sum_{1 \leqslant i, j \leqslant N}\left(G^{-T}\right)_{i, j} \int_{\mathbb{U}} \Phi_{i}(z) T(z, x) \lambda(\mathrm{d} z) \Psi_{j}(y)
\end{aligned}
$$

where $G_{i, j}=\int_{\mathbb{U}^{2}} \Phi_{i}(x) T(x, y) \Psi_{j}(y) \lambda(\mathrm{d} x) \lambda(\mathrm{d} y)$ and

$$
\begin{equation*}
\Phi_{i}(x)=e^{-\mathrm{i} x\left(i-\frac{N+1}{2}\right)}, \quad T(x, y)=\sum_{k \in \mathbb{Z}}(-1)^{k(N-1)} p_{t}(x, y+2 k \pi), \quad \Psi_{j}(x)=e^{\mathrm{i} x\left(j-\frac{N+1}{2}\right)} \tag{3.6}
\end{equation*}
$$

By taking $\delta=-\frac{N+1}{2}, x \rightarrow x-y$ in the summation formula of Lemma 2.2 , we have

$$
\begin{equation*}
T(x, y)=\frac{1}{2 \pi} \sum_{n \in \mathbb{Z}} e^{\mathrm{i}(x-y)\left(n-\frac{N+1}{2}\right)} e^{-\frac{1}{2}\left(n-\frac{N+1}{2}\right)^{2} t}=\frac{1}{2 \pi} \sum_{n \in \mathbb{Z}} u_{n} \Psi_{n}(x) \Phi_{n}(y) \tag{3.7}
\end{equation*}
$$

where $u_{n}=e^{-\frac{1}{2}\left(n-\frac{N+1}{2}\right)^{2} t}$. This and $\int_{\mathbb{U}} \Phi_{i}(x) \Psi_{j}(x) \lambda(d x)=2 \pi \delta_{0}(j-i)$ imply

$$
\begin{equation*}
\int_{\mathbb{U}} T(x, y) \Psi_{j}(y) \lambda(\mathrm{d} y)=u_{j} \Psi_{j}(x) \tag{3.8}
\end{equation*}
$$

so $G_{i, j}=\int_{\mathbb{U}^{2}} \Phi_{i}(x) T(x, y) \Psi_{j}(y) \lambda(d x) \lambda(\mathrm{d} y)=\int_{\mathbb{U}} \Phi_{i}(x) u_{j} \Psi_{j}(x) \lambda(\mathrm{d} x)=2 \pi u_{j} \delta_{0}(j-i)$. We observe that $\left(G^{-T}\right)_{i, j}=(2 \pi)^{-1} \delta_{0}(j-i) u_{j}^{-1}, T(x, y)=T(y, x)$ and $u_{N+1-i}=u_{i}$. Therefore, we obtain

$$
\begin{aligned}
& K(0, x ; 0, y)=\frac{1}{2 \pi} \sum_{i=1}^{N} \sum_{j=1}^{N} \delta_{0}(j-i) u_{j}^{-1} \Phi_{i}(x) u_{j} \Psi_{j}(y)=\frac{1}{2 \pi} \sum_{k=1}^{N} e^{\mathrm{i}(x-y)\left(k-\frac{N+1}{2}\right)}=K(1, x ; 1, y) \\
& K(0, x ; 1, y)=\frac{1}{2 \pi} \sum_{k=1}^{N} e^{\frac{1}{2}\left(k-\frac{N+1}{2}\right)^{2} t} e^{\mathrm{i}(x-y)\left(k-\frac{N+1}{2}\right)} \\
& K(1, x ; 0, y)=-\sum_{k \in \mathbb{Z}}(-1)^{k(N-1)} p_{t}(y, x+2 k \pi)+\frac{1}{2 \pi} \sum_{k=1}^{N} e^{-\frac{1}{2}\left(k-\frac{N+1}{2}\right)^{2} t} e^{\mathrm{i}(x-y)\left(k-\frac{N+1}{2}\right)}
\end{aligned}
$$

The result follows by using (3.7), taking $t \rightarrow \frac{2 t}{N}$ and conjugating the kernel by $e^{\left(\frac{N-1}{2}\right)^{2} \frac{t}{N}}$.
Proposition 3.1 and elementary calculations lead to the following corollary, which expresses the multi-time covariance of linear statistics in a remarkably simple form, even though we won't make use of it.

Corollary 3.2 (Covariance of linear statistics). Consider the dynamics (2.6) and denote $\operatorname{sgn}(x)=\mathbb{1}_{x>0}-$ $\mathbb{1}_{x<0}$. For $H^{1 / 2}$ functions $f$ and $g$, we have for every $N, t \geqslant 0$,

$$
\operatorname{Cov}\left(\sum_{k} f\left(z_{k}(0)\right), \sum_{k} g\left(z_{k}(t)\right)\right)=\sum_{|j| \leqslant N-1} \hat{f}_{j} \hat{g}_{-j} \operatorname{sgn}(j) e^{-|j| t} \frac{\sinh \left(\frac{j^{2} t}{N}\right)}{\sinh \left(\frac{j t}{N}\right)}+\sum_{|j| \geqslant N} \hat{f}_{j} \hat{g}_{-j} e^{-j^{2} \frac{t}{N}} \frac{\sinh (j t)}{\sinh \left(\frac{j t}{N}\right)}
$$

Later on, we will use the following pointwise estimates on the off-diagonal terms of the kernel obtained in Proposition 3.1.

Lemma 3.3 (Pointwise estimates). With $x-y=\frac{\mu}{N}$ and $t=\frac{\tau}{N}$, we have as $N \rightarrow \infty$,

$$
\begin{align*}
& \frac{1}{N} K(0, x ; 1, y)=\frac{1}{2 \pi} \int_{|z|<1 / 2} e^{\left(z^{2}-\frac{1}{4}\right) \tau+\mathrm{i} \mu z} \mathrm{~d} z+\mathrm{O}\left(\frac{\tau+|\mu|}{N}\right)  \tag{3.9}\\
& \frac{1}{N} K(1, x ; 0, y)=\frac{1}{2 \pi} \int_{|z|>1 / 2} e^{\left(\frac{1}{4}-z^{2}\right) \tau+\mathrm{i} \mu z} \mathrm{~d} z+\mathrm{O}\left(\frac{\tau+|\mu|}{N}\right) \tag{3.10}
\end{align*}
$$

Furthermore, when $\max (\tau,|\mu|) \gg 1,|K(0, x ; 1, y)|+|K(1, x ; 0, y)|=\mathrm{O}(N / \max (\tau,|\mu|))$.
We won't need (3.9) and 3.10. The interest stems from the fact that when $\tau$ and $|\mu|$ are $\mathrm{O}(1)$, they describe the limiting kernel at the microscale.

Proof. The first assertion follows by using a Riemann sum approximation. Indeed, with $t=\frac{\tau}{N}$ and $x-y=\frac{\mu}{N}$, we have

$$
\frac{1}{N} K(0, x ; 1, y)=\frac{1}{2 \pi} \sum_{k=1}^{N} e^{\left(\frac{k}{N}-\frac{1}{N}\right)\left(\frac{k}{N}-1\right) \tau+\mathrm{i} \mu\left(\frac{k}{N}-\frac{1}{2}-\frac{1}{2 N}\right)}=\frac{1}{2 \pi} \int_{0}^{1} e^{x(x-1) \tau+\mathrm{i} \mu\left(x-\frac{1}{2}\right)} \mathrm{d} x+O\left(\frac{\tau+|\mu|}{N}\right)
$$

and we note $\int_{0}^{1} e^{z(z-1) \tau+\mathrm{i} \mu\left(z-\frac{1}{2}\right)} \mathrm{d} x=\int_{|z|<1 / 2} e^{\left(z^{2}-\frac{1}{4}\right) \tau+\mathrm{i} \mu x} \mathrm{~d} x$. Along the same lines, we obtain (3.10).
The second and third assertions follow from elementary calculation. We explain the main ideas. For the second one, we note that the main contribution to $\sum_{k=-N}^{N} e^{\left(\left(\frac{k}{N}\right)^{2}-1\right) \tau}$ is $\sum_{(1-\varepsilon) N \leqslant|k| \leqslant N} e^{\left(\left(\frac{k}{N}\right)^{2}-1\right) \tau} \leqslant$ $2 \sum_{(1-\varepsilon) N \leqslant|k| \leqslant N} e^{-\left(1-\frac{k}{N}\right) \tau} \leqslant 2\left(e^{\frac{\tau}{N}}-1\right)^{-1}=\mathrm{O}(N / \tau)$. The last one follows by a discrete integration by parts. Set $v_{k}=e^{\left(\left(\frac{k}{N}\right)^{2}-1\right) \tau}, e_{k}=e^{\mathrm{i} \frac{k \mu}{N}}, w_{0}=0$ and $w_{k}=e_{k}+w_{k-1}$ for $1 \leqslant k \leqslant N$. Then, the term of interest, $\sum_{k=1}^{N} v_{k} e_{k}$ is equal to $v_{N} w_{N}+\sum_{k=1}^{N-1}\left(v_{k}-v_{k+1}\right) w_{k}$. Finally, $w_{k}=\sum_{\ell=1}^{k} e_{\ell}=\mathrm{O}(1)\left(e^{\mathrm{i} \frac{\mu}{N}}-1\right)^{-1}=\mathrm{O}(N / \mu)$ and $v_{k}$ is increasing.

Out of equilibrium. In the case of non-stationary initial data, the point process of eigenvalues at a fixed time is also determinantal point process and we provide here an expression of an associated kernel. In the Hermitian case, a self contained proof can be found in [37, Appendix]. As seen above, the density of unlabeled eigenvalues (e.g., use a test function which is invariant under permutation) is proportional to

$$
w_{t, x}^{N}(y):=\frac{e^{\lambda_{N} t}}{N} \frac{|\Delta(y)|}{|\Delta(x)|} \operatorname{det}\left(\sum_{k \in \mathbb{Z}}(-1)^{k(N-1)} p_{t}\left(x_{i}, y_{j}+2 k \pi\right)\right)
$$

Note that when $y_{1}<\cdots<y_{N}<y_{1}+2 \pi$, we saw that we can write $|\Delta(y)|=\mathrm{i}^{-\frac{N(N-1)}{2}} \operatorname{det}\left(e^{\mathrm{i} y_{i}\left(j-1-\frac{N-1}{2}\right)}\right)$ so that, recalling the notation $T$ and $\Psi$ in (3.6), we can identify (up to multiplicative constant) the weights $\operatorname{det} T\left(x_{i}, y_{j}\right) \operatorname{det} \Psi_{i}\left(y_{j}\right)$. This is a biorthogonal ensemble (see [18, Section 4]) so a determinantal point process whose correlation kernel is given by $K_{t, x}(z, y)=\sum_{i, j}^{N} A_{i, j}^{-T} T\left(x_{i}, z\right) \Psi_{j}(y)$ where, using (3.8), $A_{i, j}=$ $\int_{\mathbb{U}} T\left(x_{i}, y\right) \Psi_{j}(y) \lambda(d y)=u_{j} \Psi_{j}\left(x_{i}\right)$ and $u_{n}=e^{-\frac{1}{2}\left(n-\frac{N+1}{2}\right)^{2} t}$. Now, by recalling Cramer's formula,

$$
\sum_{j=1}^{n}\left(A^{-1}\right)_{i, j} b_{j}=\left(A^{-1} b\right)_{i}=\frac{\operatorname{det}(\operatorname{col} i \text { of } A \text { is replaced by } b)}{\operatorname{det}(A)}
$$

and we find

$$
\begin{equation*}
K_{t, x}(z, y)=\sum_{i, j} \Psi_{j}(y)\left(A^{-1}\right)_{j, i} T\left(x_{i}, z\right)=\sum_{i} T\left(x_{i}, z\right) \frac{\operatorname{det}(\text { line } i \text { of } A \text { is replaced by } \Psi(y))}{\operatorname{det}(A)} \tag{3.11}
\end{equation*}
$$

We denote by $\bar{A}^{i}$ the matrix for which the line $i$ in $A$ is replaced by $\Psi(y)$, i.e., $\bar{A}_{i, j}^{i}=\Psi_{j}(y)$ for $j \leqslant N$. Recalling 3.6, we have

$$
\begin{aligned}
\operatorname{det} A & =\left(\prod_{j} u_{j}\right) \operatorname{det} \Psi_{j}\left(x_{i}\right)=\prod_{j} u_{j} \prod_{i} e^{-\mathrm{i} x_{i}\left(\frac{N-1}{2}\right)} \prod_{i<j}\left(e^{\mathrm{i} x_{j}}-e^{\mathrm{i} x_{i}}\right) \\
\operatorname{det} A^{i} & =\left(\prod_{j} u_{j}\right) \operatorname{det}\left(\Psi_{j}\left(x_{k}\right) 1_{k \neq i}+u_{j}^{-1} \Psi_{j}(y) 1_{k=i}\right)
\end{aligned}
$$

On the line $i$, we use (with $\left.B_{t} \sim \mathcal{N}(0, t)\right), u_{j}^{-1} e^{\mathrm{i} y(j-1)}=\mathbb{E} e^{-\frac{N-1}{2} B_{t}} e^{\left(\mathrm{i} y+B_{t}\right)(j-1)}$. So, with simplifications coming from the quotient of Vandermonde determinants

$$
\frac{\operatorname{det} \bar{A}^{i}}{\operatorname{det} A}=e^{-\mathrm{i}\left(y-x_{i}\right)\left(\frac{N-1}{2}\right)} \mathbb{E} e^{-\frac{N-1}{2} B_{t}} \prod_{j \neq i} \frac{e^{\mathrm{i} y+B_{t}}-e^{\mathrm{i} x_{j}}}{e^{\mathrm{i} x_{i}}-e^{\mathrm{i} x_{j}}}=\mathbb{E} \prod_{j \neq i} \frac{\sin \left(\frac{y-\mathrm{i} B_{t}-x_{j}}{2}\right)}{\sin \left(\frac{x_{i}-x_{j}}{2}\right)}
$$

and, going back to 3.11, we obtain

$$
\begin{equation*}
K_{t, x}(z, y)=\sum_{i} T\left(x_{i}, z\right) \mathbb{E} \prod_{j \neq i} \frac{\sin \left(\frac{y-\mathrm{i} B_{t}-x_{j}}{2}\right)}{\sin \left(\frac{x_{i}-x_{j}}{2}\right)} \tag{3.12}
\end{equation*}
$$

This expression is the analog of the Hermitian one used, e.g., in 60, 37. By using the residue theorem and expressing $\mathbb{E}$ as an integral, it is possible to give a contour integral representation of (3.12).
3.2 Asymptotic space-time decoupling. In the context of random matrices, using the determinant point processes machinery to obtain correlation/decorrelation estimates is not uncommon. A good illustration of the typical techniques can be found in 81 which exploits the kernel obtained for the GUE minor process in 64 to derive such estimates. The starting point is usually a norm estimate for the differences of Fredholm determinants such as $|\operatorname{det}(I+A)-\operatorname{det}(I+B)| \leqslant|A-B| e^{1+|A|+|B|}$ (see 81, Section 6.3]) or a similar inequality for 2-regularized determinants (see [81, Section 10]). In our problem, such inequalities do not seem to be adapted since they give an additive error term and we look for a multiplicative one. We introduce here a method adapted for such errors.

For $j \in \llbracket 1, J \rrbracket$ and $E_{j}$ 's on the unit circle, we define

$$
\begin{equation*}
f_{j}(z)=\left|z-E_{j}\right|^{\gamma} \chi\left(\frac{z-E_{j}}{\theta}\right)+|2 \theta|^{\gamma}\left(1-\chi\left(\frac{z-E_{j}}{\theta}\right)\right), \quad \theta=\lambda / N \tag{3.13}
\end{equation*}
$$

where $\chi$ is fixed, smooth, $\chi(z) \in[0,1], \chi(z)=1$ for $|z| \leqslant 1$ and $\chi(z)=0$ for $|z| \geqslant 2$. Here, $\lambda \rightarrow \infty$ as $N \rightarrow \infty$. The main result of this section, concerning the decoupling of the eigenvalues of the unitary Brownian motion 2.5 , is the following.

Proposition 3.4 (Decoupling). Let $c, C>0$ such that $\min _{i \neq j}\left|\left(E_{i}, t_{i}\right)-\left(E_{j}, t_{j}\right)\right| \geqslant N^{-1+c}$ and $\gamma_{z} \in[0, C]$ for any singularity $z$. There exists $\kappa=\kappa(c, C)>0, \delta=\delta(c, C)>0$ such that if $\lambda=N^{\kappa}$, we have

$$
\mathbb{E}\left[\prod_{j=1}^{J} \prod_{i=1}^{N} f_{j}\left(z_{i}\left(t_{j}\right)\right)\right]=\prod_{j=1}^{J} \mathbb{E}\left[\prod_{i=1}^{N} f_{j}\left(z_{i}\left(t_{j}\right)\right)\right]\left(1+\mathrm{O}\left(N^{-\delta}\right)\right)
$$

Proof. The proof is easier to follow and has simpler notations for $J=2$ but generalizes immediately to an arbitrary fixed $J$. In this case we write $d=\max (\mu, \tau)$ where $\mu=N\left|E_{1}-E_{2}\right|$ and $\tau=N\left|t_{1}-t_{2}\right|$, with $t_{1}=0$, $t_{2}=t$ so $d \geqslant N^{c}$. Furthermore, it is equivalent to prove that

$$
\mathbb{E}\left[\prod_{i=1}^{N} g_{1}\left(z_{i}\left(t_{1}\right)\right) \cdot \prod_{i=1}^{N} g_{0}\left(z_{i}\left(t_{0}\right)\right)\right]=\mathbb{E}\left[\prod_{i=1}^{N} g_{1}\left(z_{i}\left(t_{1}\right)\right)\right] \cdot \mathbb{E}\left[\prod_{i=1}^{N} g_{0}\left(z_{i}\left(t_{0}\right)\right)\right] \cdot\left(1+\mathrm{O}\left(N^{-\delta}\right)\right)
$$

where $g_{j}(x)=\frac{f_{j}(x)}{f\left(E_{j} e^{2 \mathrm{i} \lambda / N}\right)}$, since they are equal up to a multiplicative constant. Below, $\delta$ is smaller from line to line.

First step: submicroscopic smoothing. In this step, we prove that

$$
\begin{align*}
\mathbb{E}\left[\prod_{i=1}^{N} g_{1}\left(z_{i}\left(t_{1}\right)\right)\right] & =\mathbb{E}\left[\prod_{i=1}^{N} h_{1}\left(z_{i}\left(t_{1}\right)\right)\right]\left(1+\mathrm{O}\left(N^{-\delta}\right)\right)  \tag{3.14}\\
\mathbb{E}\left[\prod_{i=1}^{N} g_{1}\left(z_{i}\left(t_{1}\right)\right) \cdot \prod_{i=1}^{N} g_{0}\left(z_{i}\left(t_{0}\right)\right)\right] & =\mathbb{E}\left[\prod_{i=1}^{N} h_{1}\left(z_{i}\left(t_{1}\right)\right) \cdot \prod_{i=1}^{N} h_{0}\left(z_{i}\left(t_{0}\right)\right)\right]\left(1+\mathrm{O}\left(N^{-\delta}\right)\right), \tag{3.15}
\end{align*}
$$

where $h_{i}$ coincides with $g_{i}$ in $\left[E_{i} e^{-\mathrm{i} N^{-1-\alpha}}, E_{i} e^{\mathrm{i} N^{-1-\alpha}}\right]^{\mathrm{c}}$, is constant equal to

$$
\begin{equation*}
\varepsilon:=g_{i}\left(E_{i} e^{i \frac{2}{3} N^{-1-\alpha}}\right)=\frac{c_{\gamma}}{\left(\lambda N^{\alpha}\right)^{\gamma}} \tag{3.16}
\end{equation*}
$$

on $\left[E_{i} e^{-\mathrm{i} \frac{1}{2} N^{-1-\alpha}}, E_{i} e^{\mathrm{i} \frac{1}{2} N^{-1-\alpha}}\right]$, interpolates in between and dominates $g_{i}$. Here, $\alpha$ is a small constant to be chosen. In particular, $h$ is uniformly bounded from below by $\varepsilon$ and we will use this lower bound in the second step.

We introduce $\breve{g}=e^{\log g-f \log g}$, and similarly $\breve{h}$. We note that

$$
\begin{equation*}
\delta(g, h):=|f \log g-f \log h| \leqslant \mathrm{O}\left(N^{-1-\alpha} \log N\right) \tag{3.17}
\end{equation*}
$$

and the pointwise inequality $g \leqslant h$ gives $\breve{g} \leqslant \breve{h} e^{\delta(g, h)}$. Using these observations and Cauchy-Schwarz, we find
$e^{-N \delta(g, h)} \mathbb{E}\left[\prod \breve{g}\right] \leqslant \mathbb{E}\left[\prod \breve{h}\right]=\mathbb{E}\left[\prod \breve{h} \mathbb{1}_{\vec{\exists}|\lambda-E| \leqslant N^{-1-\alpha}}\right]+\mathbb{E}\left[\prod \breve{h} \mathbb{1}_{\exists|\lambda-E| \leqslant N^{-1-\alpha}}\right] \leqslant e^{N \delta(g, h)} \mathbb{E}\left[\prod \breve{g}\right]+\mathbb{E}\left[\prod \breve{h}^{2}\right]^{1 / 2} N^{-\frac{\alpha}{2}}$.
To evaluate $\mathbb{E}\left[\Pi \breve{h}^{2}\right]$, we introduce $h_{s}$ which dominates $h$, smoothes its singularity on scale $N^{-1-\kappa}$ ( with $\alpha>\kappa$ ), and satisfies

$$
\delta\left(h, h_{s}\right)=\left|f \log h_{s}-f \log h\right|=\mathrm{O}\left(N^{-1-\kappa} \log N\right), \quad\left\|h_{s}\right\|_{\mathrm{H}}^{2} \leqslant \kappa \mathrm{O}(\log N) .
$$

(to check the second assertion, use the representation $\|f\|_{\mathrm{H}}^{2}=\operatorname{cst} \iint \log |x-y| f^{\prime}(x) f^{\prime}(y)$ and cancellations coming from the two possible signs of $\left.\partial_{\theta} \log \left|e^{\mathrm{i} \theta}-e^{\mathrm{i} \phi}\right|\right)$. By Lemma 5.4 and these properties, we have $\mathbb{E}\left[\Pi \breve{h}^{2}\right] \leqslant e^{N \delta\left(h, h_{s}\right)} \mathbb{E}\left[\Pi \breve{h}_{s}^{2}\right]^{1 / 2} \leqslant N^{c_{1} \cdot \kappa}$ where $c_{1}=c_{1}(C)$. So we have proved

$$
\left(1-\mathrm{O}\left(N^{-\alpha / 2}\right)\right) \mathbb{E}\left[\prod \breve{g}\right] \leqslant \mathbb{E}\left[\prod \breve{h}\right] \leqslant\left(1+\mathrm{O}\left(N^{-\alpha / 2}\right)\right) \mathbb{E}\left[\prod \breve{g}\right]+\mathrm{O}\left(N^{c_{2} \kappa-\frac{\alpha}{2}}\right) .
$$

By Jensen we have $\mathbb{E}[\Pi \breve{g}] \geqslant 1$, so the above error is actually negligible and (3.14) holds with $\breve{g}, \breve{h}$ instead of $g, h$ and $\delta=\alpha / 2-c_{2} \kappa$ provided

$$
\begin{equation*}
\alpha \geqslant 10 c_{2} \kappa . \tag{3.18}
\end{equation*}
$$

The result for $g, h$ follows by another application of (3.17). For the double product, namely (3.15), the same proof applies since the Jensen inequality still holds and Cauchy-Schwarz inequality is replaced by Hölder inequality.

Second step: operators, spectrums. For such parameters we now need to prove

$$
\mathbb{E}\left[\prod_{i=1}^{N} h_{1}\left(z_{i}\left(t_{1}\right)\right) \cdot \prod_{i=1}^{N} h_{0}\left(z_{i}\left(t_{0}\right)\right)\right]=\mathbb{E}\left[\prod_{i=1}^{N} h_{1}\left(z_{i}\left(t_{1}\right)\right)\right] \cdot \mathbb{E}\left[\prod_{i=1}^{N} h_{0}\left(z_{i}\left(t_{0}\right)\right)\right] \cdot\left(1+\mathrm{O}\left(N^{-\delta}\right)\right)
$$

We introduce $k_{i}=\sqrt{1-h_{i}}, \theta=\lambda / N$. By definition of $f, g=1$ for $|x-E|>2 \theta$, this holds for $h$ as well so the support of $k$ is of order $\mathrm{O}(\theta)$.

Let $\widetilde{K}$ be the kernel for independence between times 0 and $t$, and $K$ the kernel we are interested in. Let $\mathcal{K}, \widetilde{\mathcal{K}}$ be the corresponding convolution kernels, namely $\mathcal{K}(r, x ; s, y)=k_{r}(x) K(r, x ; s, y) k_{s}(y)$.

The spectrum of $\widetilde{\mathcal{K}}$ is the union of the spectra of $\widetilde{\mathcal{K}_{0}}$ and $\widetilde{\mathcal{K}_{1}}$, the corresponding fixed time operators. We have

$$
\mathbb{E}\left[\prod^{\left.\left(1+x\left(h_{0}-1\right)\right)\left(z_{i}(0)\right)\right]=\operatorname{det}\left(\operatorname{Id}-x \widetilde{\mathcal{K}_{0}}\right) . ~ . ~}\right.
$$

As $h_{0} \geqslant \varepsilon, x \mapsto 1+x\left(h_{0}-1\right)>0$ on $\left[0, \frac{1}{1-\varepsilon}\right)$, and the left-hand side is $>0$ for any $x \in\left[0, \frac{1}{1-\varepsilon}\right)$, we have $1-x \mu_{i} \neq 0$ for any $x \in\left[0, \frac{1}{1-\varepsilon}\right)$ and eigenvalue $\mu_{i}$ of $\widetilde{\mathcal{K}_{0}}$. We observe that $\widetilde{\mathcal{K}_{0}}$ is nonnegative so the spectrum of $\widetilde{\mathcal{K}_{0}}$ is in $[0,1-\varepsilon)$, and the same property holds for $\widetilde{\mathcal{K}_{1}}$ and $\widetilde{\mathcal{K}}$.

We now consider the Fredholm determinant of interest, i.e.

$$
\mathbb{E}\left[\prod h_{0}\left(z_{i}(0)\right) \prod h_{1}\left(z_{i}(t)\right)\right]=\operatorname{det}(\operatorname{Id}-\mathcal{K}) .
$$

Since the entries of $\mathcal{K}$ are real-valued, we also have

$$
\mathbb{E}\left[\prod h_{0}\left(z_{i}(0)\right) \prod h_{1}\left(z_{i}(t)\right)\right]=\operatorname{det}\left(\operatorname{Id}-\mathcal{K}^{*}\right),
$$

so

$$
\mathbb{E}\left[\prod h_{0}\left(z_{i}(0)\right) \prod h_{1}\left(z_{i}(t)\right)\right]^{2}=\operatorname{det}\left((\operatorname{Id}-\mathcal{K})\left(\operatorname{Id}-\mathcal{K}^{*}\right)\right) .
$$

Indeed, the multiplication rule for determinants $\operatorname{det}(I+A) \operatorname{det}(I+B)=\operatorname{det}((I+A)(I+B))$ is justified for trace class operators $A$ and $B$. Here, this follows by an argument similar to the one of 61, Proposition 2.4]

We introduce the operators $\mathbf{K}:=\mathcal{K}+\mathcal{K}^{*}-\mathcal{K} \mathcal{K}^{*}$ and $\widetilde{\mathbf{K}}:=\widetilde{\mathcal{K}}+\widetilde{\mathcal{K}^{*}}-\widetilde{\mathcal{K}} \widetilde{\mathcal{K}}^{*}$. Since $\widetilde{\mathcal{K}}$ is self-adjoint, the eigenvalues of $\widetilde{\mathbf{K}}$ are of type $\mu+\mu-\mu^{2}$ for $\mu \in[0,1-\varepsilon)$, so its spectrum is included in $\left[0,1-\varepsilon^{2}\right)$.

Third step: Hoffman-Wielandt inequality. We know that if we order the eigenvalues $\lambda_{i}$ (resp. $\tilde{\lambda}_{i}$ ) of $\mathcal{K}+\mathcal{K}^{*}-\mathcal{K} \mathcal{K}^{*}$ (resp. $\widetilde{\mathcal{K}}+\widetilde{\mathcal{K}^{*}}-\widetilde{\mathcal{K}} \widetilde{\mathcal{K}^{*}}$ ) properly, we have by the Hoffman-Wielandt inequality (more precisely an infinite dimension version from 67,

$$
\begin{aligned}
\sum\left|\lambda_{i}-\tilde{\lambda}_{i}\right|^{2} \leqslant\|\mathbf{K}-\widetilde{\mathbf{K}}\|_{\mathrm{HS}}^{2} & =\left\|\left(\mathcal{K}+\mathcal{K}^{*}-\mathcal{K} \mathcal{K}^{*}\right)-\left(\widetilde{\mathcal{K}}+\widetilde{\mathcal{K}^{*}}-\widetilde{\mathcal{K}} \widetilde{\mathcal{K}^{*}}\right)\right\|_{\mathrm{HS}}^{2} \\
& \leqslant C\|\mathcal{K}-\widetilde{\mathcal{K}}\|_{\mathrm{HS}}^{2}+C\left(\|\widetilde{\mathcal{K}}\|_{\mathrm{HS}}^{2}+\|\mathcal{K}\|_{\mathrm{HS}}^{2}\right)\|\mathcal{K}-\widetilde{\mathcal{K}}\|_{\mathrm{HS}}^{2}
\end{aligned}
$$

We will use this and the estimates on the kernel to prove the following inequalities,

$$
\begin{equation*}
\|\mathcal{K}\|_{\mathrm{HS}}=\mathrm{O}(\lambda), \quad\|\mathcal{K}-\widetilde{\mathcal{K}}\|_{\mathrm{HS}}=\mathrm{O}(\lambda / d), \quad \sqrt{\sum\left|\lambda_{i}-\tilde{\lambda}_{i}\right|^{2}} \leqslant\|\mathbf{K}-\widetilde{\mathbf{K}}\|_{\mathrm{HS}}=\mathrm{O}\left(\lambda^{2} / d\right) . \tag{3.19}
\end{equation*}
$$

Let us mention an important consequence for what follows: this implies, for $N$ large enough, for any $i$,

$$
\begin{equation*}
-1 / 2 \leqslant \lambda_{i} \leqslant 1-\varepsilon^{2}+\mathrm{O}\left(\lambda^{2} / d\right)=1-\varepsilon^{2}+\mathrm{o}\left(\varepsilon^{2}\right), \quad \text { when } \lambda^{2} / d=\mathrm{o}\left(\varepsilon^{2}\right) . \tag{3.20}
\end{equation*}
$$

For the first inequality, since $\lambda_{i} \geqslant \tilde{\lambda}_{i}-\left|\lambda_{i}-\tilde{\lambda}_{i}\right| \geqslant-\left|\lambda_{i}-\tilde{\lambda}_{i}\right|, \sum_{\lambda_{i}<0}\left|\lambda_{i}\right|^{2} \leqslant \sum_{i}\left|\lambda_{i}-\tilde{\lambda}_{i}\right|^{2}=\mathrm{o}(1)$ when $\lambda^{2}=\mathrm{o}(d)$, which will be the case. So for large enough $N$, for any $i$ we have $\lambda_{i}>-\frac{1}{2}$. For the second one, for any $i, \lambda_{i} \leqslant \tilde{\lambda}_{i}+\left|\lambda_{i}-\tilde{\lambda}_{i}\right| \leqslant 1-\varepsilon^{2}+\mathrm{O}\left(\lambda^{2} / d\right)$.

Now, we prove these estimates. From (3.1) and since the size of the support of $k_{i}$ is $\mathrm{O}(\lambda / N)$, we have $\int\left|g_{0}(x) K(0, x ; 0, y) g_{0}(y)\right|^{2} d x d y \leqslant C \frac{\lambda^{2}}{N^{2}} N^{2}$ so $\|\widetilde{\mathcal{K}}\|_{\text {HS }}=\mathrm{O}(\lambda)$.

Furthermore $\|\mathcal{K}-\widetilde{\mathcal{K}}\|_{\text {HS }}=\mathrm{O}(\lambda / d)$ since Lemma 3.3 gives a pointwise upper bound $\mathrm{O}(N / d)$ on the offdiagonal terms of the kernel and the size of the support is $\mathrm{O}(\lambda / N)$. Therefore, we find $\|\mathbf{K}-\widetilde{\mathbf{K}}\|_{\mathrm{HS}}=\mathrm{O}\left(\lambda^{2} / d\right)$.

Fourth step: expansion of eigenvalues. We will conclude by proving

$$
\begin{equation*}
\left|\log \widetilde{\mathbb{E}}\left[\prod h_{1}\left(z_{i}(0)\right) \prod h_{2}\left(z_{i}(t)\right)\right]-\log \mathbb{E}\left[\prod h_{1}\left(z_{i}(0)\right) \prod h_{2}\left(z_{i}(t)\right)\right]\right|=\mathrm{O}\left(\frac{\lambda^{4}}{\varepsilon \sqrt{d}}\right) . \tag{3.21}
\end{equation*}
$$

We bound from above the left-hand side above by expressing it with Fredholm determinants and using the following expansion of the logarithm for $\mathbf{K}$ (and similarly for $\widetilde{\mathbf{K}}$ ),

$$
\log \operatorname{det}\left((\operatorname{Id}-\mathcal{K})\left(\operatorname{Id}-\mathcal{K}^{*}\right)\right)=\log \operatorname{det}(\operatorname{Id}-\mathbf{K})=-\sum_{j, \ell \geqslant 1} \frac{\lambda_{j}^{\ell}}{\ell} .
$$

Thus, we obtain with $m$ to be chosen,

$$
|\log \operatorname{det}(\operatorname{Id}-\widetilde{\mathbf{K}})-\log \operatorname{det}(\operatorname{Id}-\mathbf{K})| \leqslant \sum_{\ell=1}^{m}\left|\operatorname{Tr}\left(\mathbf{K}^{\ell}\right)-\operatorname{Tr}\left(\widetilde{\mathbf{K}}^{\ell}\right)\right| / \ell+\sum_{j \geqslant 1, \ell \geqslant m} \frac{\left|\lambda_{j}\right|^{\ell}+\left|\tilde{\lambda}_{j}\right|^{\ell}}{\ell} .
$$

First, we bound from above the contribution for $\ell \geqslant m$,

$$
\sum_{j \geqslant 1, \ell \geqslant m} \frac{\left|\lambda_{j}\right|^{\ell}}{\ell} \leqslant \frac{1}{m} \sum_{j} \frac{\left|\lambda_{j}\right|^{2}}{1-\left|\lambda_{j}\right|} \leqslant \frac{1}{m \varepsilon^{2}}\|\mathbf{K}\|_{\text {HS }}^{2} \leqslant \frac{\lambda^{4}}{m \varepsilon^{2}}
$$

where we used $\lambda_{j} \in\left[-1 / 2,1-\varepsilon^{2}\right]$ in the second inequality. We proceed similarly to bound the contribution of the $\tilde{\lambda}_{j}$ 's.

Now we prove that the remaining term $\sum_{\ell=1}^{m}\left|\operatorname{Tr}\left(\mathbf{K}^{\ell}\right)-\operatorname{Tr}\left(\widetilde{\mathbf{K}}^{\ell}\right)\right| / \ell=m \mathrm{O}\left(\lambda^{4} / d\right)$. For $\ell=1$, we use

$$
|\operatorname{Tr}(\mathbf{K}-\widetilde{\mathbf{K}})|=\left|\operatorname{Tr}\left(\mathcal{K} \mathcal{K}^{*}-\widetilde{\mathcal{K}} \widetilde{\mathcal{K}}^{*}\right)\right|=\left|\|\mathcal{K}\|_{\mathrm{HS}}^{2}-\|\widetilde{\mathcal{K}}\|_{\mathrm{HS}}^{2}\right| \leqslant\|\mathcal{K}-\widetilde{\mathcal{K}}\|_{\mathrm{HS}}\left(\|\mathcal{K}\|_{\mathrm{HS}}+\|\widetilde{\mathcal{K}}\|_{\mathrm{HS}}\right)=\mathrm{O}\left(\lambda^{2} / d\right)
$$

For $\ell \geqslant 2$, we write

$$
\left|\operatorname{Tr}\left(\mathbf{K}^{\ell}\right)-\operatorname{Tr}\left(\tilde{\mathbf{K}}^{\ell}\right)\right| / \ell \leqslant \sum_{i}\left|\lambda_{i}^{\ell}-\tilde{\lambda}_{i}^{\ell}\right| / \ell \leqslant \sum_{i}\left|\lambda_{i}-\widetilde{\lambda}_{i}\right|\left(\left|\lambda_{i}\right|^{\ell-1}+\left|\widetilde{\lambda}_{i}\right|^{\ell-1}\right)
$$

Then, by Cauchy-Schwarz we have

$$
\sum_{i}\left|\lambda_{i}-\widetilde{\lambda}_{i}\left\|\left.\lambda_{i}\right|^{\ell-1} \leqslant\left(\sum_{i}\left|\lambda_{i}-\widetilde{\lambda}_{i}\right|^{2}\right)^{1 / 2}\left(\sum_{i}\left|\lambda_{i}\right|^{2 \ell-2}\right)^{1 / 2} \leqslant\right\| \mathbf{K}-\widetilde{\mathbf{K}}\left\|_{\mathrm{HS}}\right\| \mathbf{K} \|_{\mathrm{HS}}=\mathrm{O}\left(\lambda^{4} / d\right)\right.
$$

where we used the Hoffman-Wielandt inequality, the fact that $\left|\lambda_{j}\right| \leqslant 1$ and $\ell \geqslant 2$ in the second inequality. The term with $\left|\tilde{\lambda}_{i}\right|$ can be bounded similarly.

Altogether, the left-hand side in 3.21 is bounded from above (up to a multiplicative constant) by $\frac{\lambda^{4}}{m \varepsilon^{2}}+m \frac{\lambda^{4}}{d}$. By taking $m=\sqrt{d} / \varepsilon$, we get $\frac{\lambda^{4}}{\varepsilon \sqrt{d}}$.

Conclusion. We explain how we choose the parameters. We will pick them such that $c \gg \alpha \gg \kappa$. Recalling $d=\max (\mu, \tau) \geqslant N^{c}, \lambda=N^{\kappa}, \varepsilon=N^{-\gamma(\alpha+\kappa)}$ all works if we choose $\alpha=\frac{c}{10 C}, \kappa=\frac{c}{100 C^{2}}$, i.e., (3.18) is satisfied, $\frac{\lambda^{2}}{\varepsilon^{2} d}=\mathrm{o}(1)$ in 3.20), $\frac{\lambda^{4}}{\varepsilon \sqrt{d}}=N^{-\delta}$ in the right-hand side of 3.21.

## 4 Resolvent estimates

This section proves quantitative limits for the unitary analogue of the resolvent. Some of our intermediate results are similar to existing local laws proved for random self-adjoint matrices (see e.g. results and references from [42, Chapter 6]). These resolvent estimates are the source of the almost optimal scales in Theorem 1.2, and follow from a family of stochastic advection equations. As explained in the following subsection, dynamical methods for rigidity of the eigenvalues or bounds on eigenvectors have been increasingly important in random matrix theory. We obtain for the first time optimal resolvent estimates in both a multi-time and full rank setting, in the Proposition 4.5. This is made possible thanks to (1) Lemma 4.1 below which covers arbitrary projections of the resolvent, (2) an iterative method to obtain first estimates on eigenvalues, then finite rank diagonal projections of the resolvent, then finite rank off-diagonal projections, and finally full rank.

The methods in this section could apply to some initial conditions out of equilibrium. For the sake of simplicity we only consider dynamics close to equilibrium, as this paper's main goal is showing a connection between random matrix dynamics and Liouville quantum gravity, not proving its universality.
4.1 Stochastic advection equation for general observables. This subsection proves the stochastic advection equation for a generalization of the Borel transform

$$
m_{t}(z)=\frac{1}{N} \sum_{k} \frac{z+e^{\mathrm{i} \theta_{k}(t)}}{z-e^{\mathrm{i} \theta_{k}(t)}}=\frac{1}{N} \operatorname{Tr}\left(\frac{z+U_{t}}{z-U_{t}}\right)
$$

which is defined, for any $N \times N$ deterministic matrix $A$, as

$$
\begin{equation*}
m_{t, A}(z)=\operatorname{Tr}\left(\frac{z+U_{t}}{z-U_{t}} \cdot A\right) \tag{4.1}
\end{equation*}
$$

The lemma below is instrumental for all results of this section.
Lemma 4.1. Under the unitary Brownian motion dynamics (2.6), we have

$$
\mathrm{d} m_{t, A}(z)=z m_{t}(z) \partial_{z} m_{t, A}(z) \mathrm{d} t+2 z \operatorname{Tr}\left(\frac{1}{z-U} A \frac{U}{z-U} \sqrt{2} \mathrm{~d} B_{t}\right)
$$

At equilibrium we have $\mathbb{E}\left(m_{t}(z)\right)=\mathbb{1}_{|z|>1}-\mathbb{1}_{|z|<1}$, so from the above lemma at leading order $m_{t, A}$ should be well approximated by the solution of the advection equation

$$
\begin{equation*}
\frac{\mathrm{d}}{\mathrm{~d} t} f_{t}(z)=z\left(\mathbb{1}_{|z|>1}-\mathbb{1}_{|z|<1}\right) \partial_{z} f_{t}(z) \tag{4.2}
\end{equation*}
$$

which has characteristics

$$
\begin{equation*}
z_{t}=z e^{t} \mathbb{1}_{|z|>1}+z e^{-t} \mathbb{1}_{|z|<1} \tag{4.3}
\end{equation*}
$$

In other words we expect

$$
m_{t, A}(z) \approx m_{0, A}\left(z_{t}\right)
$$

It has been known since Pastur's work 84 that the Stieltjes transform of the Hermitian Dyson Brownian motion satisfies an advection equation analogous to 4.2 , in the limit of large dimension. More general resolvent dynamics corresponding to $A$ with rank one can be used for regularization and universality purpose, as proved first in $[72]$, for eigenvalues statistics at the edge of deformed Wigner matrices. For the same model, (12, 94 used stochastic advection equations and characteristics to understand the shape of bulk eigenvectors. Moreover, the stochastic complex Burgers equation for the Stieltjes transform extends to general $\beta$-ensembles and allows to prove rigidity of the particles [57, 1], also through regularization along the characteristics. For a general class of discrete particle systems, analogues of the Stieltjes transform were also recently shown to satisfy equations of type (4.2) 51].

More directly relevant to our model, the unitary Brownian motion, complex Burgers equation for the Borel transform were first shown by Biane [15, 16], and they are instrumental in Adhikari and Landon's recent result on optimal location of eigenvalues out of equilibrium, starting at identity [2].

While most of these works focus on the trace of the resolvent, Lemma 4.1 considers general full-rank projections observables: it covers the Stieltjes transform (i.e. $A=$ Id below, used in Proposition 4.2), onedimensional projections (i.e. $A=q q^{*}$, used in Proposition 4.3), and a full-rank $A$ is needed for the proof of Proposition 4.5, a main estimate towards Theorem 1.2 .

Proof of Lemma 4.1. Recall the definition of the skew Hermitian Brownian motion in 2.3). From Itô's formula (2.9), we have

$$
\begin{aligned}
\mathrm{d} \frac{z+U}{z-U} & =2 z \mathrm{~d} \frac{1}{z-U} \\
& =2 z \sum_{k} \frac{1}{z-U} \sqrt{2} U X_{k} \mathrm{~d} \tilde{B}_{t}^{k} \frac{1}{z-U}+2 z\left(\sum_{k} \frac{1}{z-U} U X_{k}^{2} \frac{1}{z-U}+2 \frac{1}{z-U} U X_{k} \frac{1}{z-U} U X_{k} \frac{1}{z-U}\right) \mathrm{d} t \\
& =2 z \frac{1}{z-U} U \sqrt{2} \mathrm{~d} B_{t} \frac{1}{z-U}-2 z \frac{U}{(z-U)^{2}} \mathrm{~d} t+4 z \sum_{k} \frac{1}{z-U} U X_{k} \frac{1}{z-U} U X_{k} \frac{1}{z-U} \mathrm{~d} t
\end{aligned}
$$

We have used $\sum_{k=1}^{N^{2}} X_{k}^{2}=-$ Id. This implies (we use that for any two complex valued matrices $P$ and $Q$, $\left.\sum_{k=1}^{N^{2}} \operatorname{Tr}\left(P X_{k} Q X_{k}\right)=-N^{-1} \operatorname{Tr}(P) \operatorname{Tr}(Q)\right)$

$$
\begin{aligned}
\mathrm{d} \operatorname{Tr}\left(\frac{z+U}{z-U} A\right) & =2 z \operatorname{Tr} \frac{1}{z-U} A \frac{U}{z-U} \sqrt{2} \mathrm{~d} B-2 z \operatorname{Tr} \frac{U}{(z-U)^{2}} A \mathrm{~d} t-4 z N^{-1} \operatorname{Tr} \frac{U}{(z-U)^{2}} A \operatorname{Tr} \frac{U}{z-U} \mathrm{~d} t \\
& =2 z \operatorname{Tr} \frac{1}{z-U} A \frac{U}{z-U} \sqrt{2} \mathrm{~d} B+2 z N^{-1} \partial_{z} \operatorname{Tr} \frac{z+U}{z-U} A \operatorname{Tr} \frac{\operatorname{Id}}{2} \mathrm{~d} t+2 z N^{-1} \partial_{z} \operatorname{Tr} \frac{z+U}{z-U} A \operatorname{Tr} \frac{U}{z-U} \mathrm{~d} t
\end{aligned}
$$

As $\frac{\mathrm{Id}}{2}+\frac{U}{z-U}=\frac{1}{2} \frac{z+U}{z-U}$, we obtain the expected result.

### 4.2 Rigidity. The following parameters

$$
\varphi=e^{(\log \log N)^{2}}, \Delta=(\log N)^{2}
$$

will often be used in this section, and so will be the notation

$$
\eta_{v}=||v|-1| .
$$

We order $0 \leqslant \theta_{1}(s) \leqslant \ldots \leqslant \theta_{N}(s) \leqslant 2 \pi$ and for any $t \geqslant s$ we define $\theta_{1}(t) \leqslant \ldots \leqslant \theta_{N}(t)$ by continuity. We consider $\gamma_{k}=\frac{2 \pi k}{N}$ and the following good sets,

$$
\mathscr{G}=\bigcap_{1 \leqslant k \leqslant N}\left\{\left|\theta_{k}-\gamma_{k}\right| \leqslant \frac{\varphi^{6}}{N}\right\}, \tilde{\mathscr{G}}=\bigcap_{1 \leqslant k \leqslant N}\left\{\left|\theta_{k}-\gamma_{k}\right| \leqslant \frac{\varphi}{N}\right\}
$$

We also denote $\boldsymbol{\theta}(t)=\left(\theta_{1}(t), \ldots, \theta_{N}(t)\right)$. The proposition below is a unitary analogue of classical rigidity results for Hermitian random matrices, see 42 and references therein.

Proposition 4.2. For any $D>0$ there exists $N_{0}$ such that for any $N \geqslant N_{0}$ we have

$$
\mathbb{P}\left(\bigcap_{s \leqslant t \leqslant s+\Delta}\{\boldsymbol{\theta}(t) \in \mathscr{G}\} \mid \boldsymbol{\theta}(s) \in \widetilde{\mathscr{G}}\right) \geqslant 1-N^{-D} .
$$

Proof. The proof will proceed through (1) resolvent estimate at fixed space and time, (2) uniform extension to any time and mesoscopic scales, (3) extension to submicroscopic scales, (4) rigidity of gaps between eigenvalues, (5) rigidity of positions.

First step: resolvent estimate. We choose $A=\operatorname{Id} / N$ in Lemma 4.1. which gives (in this section we define new independent Brownian motions through $\mathrm{d} \hat{B}_{j k}(s)=\left(P_{s} \mathrm{~d} B(s) P_{s}^{*}\right)_{j k}$ with $P_{s}$ unitary diagonalizing $U_{s}$, $U_{s}=P_{s} D_{s} P_{s}^{*}$, and abbreviate $\hat{B}_{j}=\hat{B}_{j j}$ )

$$
\begin{equation*}
\mathrm{d} m_{t}(z)=m_{t}(z) z \partial_{z} m_{t}(z) \mathrm{d} t+\frac{2 \sqrt{2} \mathrm{i} z}{N^{3 / 2}} \sum_{k=1}^{N} \frac{z_{k}(t)}{\left(z-z_{k}(t)\right)^{2}} \mathrm{~d} \hat{B}_{k}(t) \tag{4.4}
\end{equation*}
$$

The following implementation of invariance along characteristics in this first step is similar to the proof of 2. Theorem 1.2].

Without loss of generality we assume $s=0$ and we first consider some $|z| \in\left[1+\varphi^{8 / 5} / N, 2\right]$. Equations (4.4) and 4.3 imply

$$
\begin{equation*}
\mathrm{d} m_{u}\left(z_{t-u}\right)=\left(m_{u}\left(z_{t-u}\right)-1\right) z_{t-u} \partial_{z} m_{u}\left(z_{t-u}\right) \mathrm{d} u+\frac{2 \sqrt{2} \mathrm{i} z_{t-u}}{N^{3 / 2}} \sum_{k=1}^{N} \frac{z_{k}(u)}{\left(z_{t-u}-z_{k}(u)\right)^{2}} \mathrm{~d} \hat{B}_{k}(u) \tag{4.5}
\end{equation*}
$$

We consider the stopping time (with respect to the filtration generated by $\hat{B}_{1}, \ldots, \hat{B}_{N}$ )

$$
\begin{equation*}
\tau=\inf \left\{u \in[0, t]:\left|m_{u}\left(z_{t-u}\right)-1\right| \geqslant \frac{\varphi^{3 / 2}}{N \eta_{z_{t-u}}}\right\} \wedge t \tag{4.6}
\end{equation*}
$$

with the convention $\inf \varnothing=+\infty$. We also abbreviate

$$
M(s)=\int_{0}^{s} \frac{2 \sqrt{2} \mathrm{i} z_{t-u}}{N^{3 / 2}} \sum_{k=1}^{N} \frac{z_{k}(u)}{\left(z_{t-u}-z_{k}(u)\right)^{2}} \mathrm{~d} \hat{B}_{k}(u)
$$

From

$$
\begin{equation*}
\frac{\operatorname{Re} m_{u}(z)}{|z|^{2}-1}=\frac{1}{N} \sum_{j} \frac{1}{\left|z-z_{j}(u)\right|^{2}} \tag{4.7}
\end{equation*}
$$

the quadratic variation of the martingale $(M(s \wedge \tau))_{s}$ (the sum of the quadratic variations of its real and imaginary parts) is bounded at time $s$ with

$$
\begin{equation*}
\frac{1}{N^{3}} \int_{0}^{s} \sum_{i} \frac{\left|z_{t-u}\right|^{2} \mathrm{~d} u}{\left|z_{i}(u)-z_{t-u}\right|^{4}} \leqslant \frac{C}{N^{2}} \int_{0}^{s} \frac{\left|z_{t-u}\right|^{2} \operatorname{Re}\left(m_{u}\left(z_{t-u}\right)\right)}{\left(1+\left|z_{t-u}\right|\right) \eta_{z_{t-u}}^{3}} \mathrm{~d} u \leqslant \frac{C}{N^{2} \eta_{z_{t-s}}^{2}} \tag{4.8}
\end{equation*}
$$

where we have used $\left|\operatorname{Re}\left(m_{u}\left(z_{t-u}\right)\right)-1\right|=\mathrm{o}(1)$ because $u \leqslant \tau$ and $\eta_{z}>\varphi^{8 / 5} / N$. This classically implies (see e.g. 93, Appendix B.6, equation (18)]) that for any $D>0$ there exists $N_{0}$ such that $\mathbb{P}\left(\cap_{0 \leqslant s \leqslant t}\left\{\left|M_{s \wedge \tau}\right|<\right.\right.$
$\left.\left.\frac{\varphi^{1 / 20}}{N \eta_{z_{t-s}}}\right\}\right) \geqslant 1-N^{-D}$ for any $N>N_{0}$. More precisely we have $\mathbb{P}\left(\left|M_{s \wedge \tau}\right|<\frac{\varphi^{1 / 20}}{N \eta_{z_{t-s}}}\right) \geqslant 1-N^{-2 D}$ and uniformity in time follows from a grid argument similar to the second step of this proof detailed below.

On the event $\cap_{0 \leqslant s \leqslant t}\left\{\left|M_{s \wedge \tau}\right|<\frac{\varphi^{1 / 20}}{N \eta_{z_{t-s}}}\right\}$, which has overwhelming probability, for any $s \leqslant t \wedge \tau$ from 4.5 we have, denoting $h(s)=m_{s \wedge \tau}\left(z_{t-s \wedge \tau}\right)-1$,

$$
|h(s)| \leqslant \int_{0}^{s}\left|z_{t-u}\right| \cdot|h(u)| \cdot\left|\partial_{z} m_{u}\left(z_{t-u}\right)\right| \mathrm{d} u+\frac{\varphi^{1 / 20}}{N \eta_{z_{t-s}}}+\frac{\varphi^{11 / 10}}{N \eta_{z_{t-s}}}
$$

where we have used $\left|m_{0}(z)-1\right| \leqslant \varphi^{11 / 10} /\left(N \eta_{z}\right)$ by Riemann sum approximation because $\boldsymbol{\theta}(0) \in \tilde{\mathscr{G}}$. Together with $\left|\partial_{z} m\right| \leqslant 2(\operatorname{Re} m) \cdot\left(|z|^{2}-1\right)^{-1}$ from 4.7), this implies

$$
|h(s)| \leqslant \int_{0}^{s}|h(u)| \cdot \frac{\left|z_{t-u}\right| 2 \operatorname{Re} m_{u \wedge \tau}\left(z_{t-u \wedge \tau}\right)}{\left(\left|z_{t-u}\right|^{2}-1\right)} \mathrm{d} u+C \frac{\varphi^{11 / 10}}{N \eta_{z_{t-s}}} \leqslant\left(1+\varphi^{-1 / 10}\right) \int_{0}^{s} \frac{|h(u)|}{\log \left|z_{t-u}\right|} \mathrm{d} u+C \frac{\varphi^{11 / 10}}{N \eta_{z_{t-s}}}
$$

where we successively relied on the inequalities $x /\left(x^{2}-1\right)<1 /(2 \log x)$ for $x>1,\left|\operatorname{Re}\left(m_{u}\left(z_{t-u}\right)\right)-1\right| \leqslant$ $\frac{\varphi^{3 / 2}}{N \eta_{z_{t-u}}} \leqslant \varphi^{-1 / 10}$ for $u \leqslant \tau$ and $\eta_{z}>\varphi^{8 / 5} / N$. The integral form of Gronwall lemma then implies

$$
|h(s)| \leqslant C \frac{\varphi^{11 / 10}}{N \eta_{z_{t-s}}}+C \varphi^{11 / 10} \int_{0}^{s} \frac{1}{N \eta_{z_{t-u}} \log \left|z_{t-u}\right|} e^{\left(1+\varphi^{-1 / 10}\right) \int_{u}^{s} \frac{\mathrm{~d} r}{\log \left|z_{t-r}\right|}} \mathrm{d} u
$$

The antiderivative of $\left(\log \left|z_{t-r}\right|\right)^{-1}$ is $\log \log \left|z_{t-r}\right|$, so $\exp \left(\int_{u}^{s} \frac{\mathrm{~d} r}{\log \left|z_{t-r}\right|}\right)=\frac{\log \left|z_{t-u}\right|}{\log \left|z_{t-s}\right|}$. Moreover for our parameters we always have $\left(\frac{\log \left|z_{t-u}\right|}{\log \left|z_{t-s}\right|}\right)^{\varphi^{-1 / 10}} \leqslant C$. Thus we have obtained

$$
|h(s)| \leqslant C \frac{\varphi^{11 / 10}}{N \eta_{z_{t-s}}}+C \varphi^{11 / 10} \int_{0}^{s} \frac{1}{N \eta_{z_{t-u}} \log \left|z_{t-s}\right|} \mathrm{d} u \leqslant \frac{\varphi^{12 / 10}}{N \eta_{z_{t-s}}}
$$

This proves that

$$
\mathbb{P}\left(\left|m_{\tau}\left(z_{t-\tau}\right)-1\right|>\frac{\varphi^{3 / 2}}{N \eta_{z_{t-\tau}}}\right) \leqslant N^{-D}
$$

By definition of $\tau$ this implies $\mathbb{P}(\tau=t) \geqslant 1-N^{-D}$, and therefore there exists $N_{0}$ such that for any $N>N_{0}$, $1+\varphi^{8 / 5} / N<|z|<2$ and $0<t<\Delta$,

$$
\begin{equation*}
\mathbb{P}\left(\left|m_{t}(z)-1\right|>\frac{\varphi^{16 / 10}}{N \eta_{z}}\right) \leqslant N^{-D} \tag{4.9}
\end{equation*}
$$

Second step: Uniformity in space and time. Let $D>0$ be fixed and large, $M=N^{10 D},\left(z_{i}\right)_{1 \leqslant i \leqslant M}$ (resp. $\left(t_{j}\right)_{1 \leqslant j \leqslant M}$ ) be points in $|z| \in\left[1+\varphi^{8 / 5} / N, 2\right]$ (resp. [ $\left.0, \Delta\right]$ ) such that for any such $|z| \in\left[1+\varphi^{8 / 5} / N, 2\right]$ there exists $z_{i}$ with $\left|z-z_{i}\right| \leqslant N^{-4}$ (resp. $0=t_{1}<\cdots<t_{M}=\Delta,\left|t_{j+1}-t_{j}\right| \leqslant N^{-5 D}$ ). Then by union bound in (4.9), there exists $N_{0}$ such that for $N \geqslant N_{0}$ we have

$$
\begin{equation*}
\mathbb{P}\left(\cap_{1 \leqslant i, j \leqslant M}\left\{\left|m_{t_{j}}\left(z_{i}\right)-1\right|<\frac{\varphi^{17 / 10}}{N \eta_{z_{i}}}\right\}\right) \geqslant 1-N^{-2 D} \tag{4.10}
\end{equation*}
$$

Moreover, for any fixed $z_{i}$ and $t_{j}$, a bracket calculation and again, for example 93 , Appendix B. 6 , equation (18)]), imply

$$
\begin{equation*}
\mathbb{P}\left(\max _{t_{j}<t<t_{j+1}}\left|m_{t}\left(z_{i}\right)-m_{t_{j}}\left(z_{i}\right)\right|>N^{-3}\right) \leqslant N^{-100 D} \tag{4.11}
\end{equation*}
$$

Equations 4.10, 4.11 and a union bound give existence of $N_{0}$ such that, for $N \geqslant N_{0}$,

$$
\begin{equation*}
\mathbb{P}\left(\cap_{1 \leqslant i \leqslant M, 0<t<\Delta}\left\{\left|m_{t}\left(z_{i}\right)-1\right|<\frac{\varphi^{18 / 10}}{N \eta_{z_{i}}}\right\}\right) \geqslant 1-N^{-D} \tag{4.12}
\end{equation*}
$$

The function $z \mapsto m_{t}(z)$ is deterministically $N^{2}$-Lipschitz for $|z|>1+\varphi^{8 / 5} / N$. Therefore from the previous equation, for some $N_{0}, N>N_{0}$ implies

$$
\begin{equation*}
\mathbb{P}\left(\bigcap_{1+\varphi^{8 / 5} / N<|z|<2,0<t<\Delta}\left\{\left|m_{t}(z)-1\right| \leqslant \frac{\varphi^{19 / 10}}{N \eta_{z}}\right\}\right) \geqslant 1-N^{-D} \tag{4.13}
\end{equation*}
$$

Third step: Extension below microscopic scales. We now consider $|z| \in\left[1,1+\varphi^{2} / N\right]$. Let $z^{\prime}$ have the same argument as $z$ and $\eta_{z^{\prime}}=\varphi^{2} / N$. The following always holds, for some universal $C$ :

$$
\begin{equation*}
\operatorname{Re} m_{t}(z) \leqslant C \frac{\eta_{z^{\prime}}}{\eta_{z}} \operatorname{Re} m_{t}\left(z^{\prime}\right) \tag{4.14}
\end{equation*}
$$

Therefore, for any $\operatorname{arc} I$ of length at $\operatorname{most} \varphi^{2} / N$ centered at $|w|=1$, denoting $w_{I}=w(1+|I|)$, under the event considered in 4.13 we have

$$
\sum \mathbb{1}_{z_{i}(t) \in I} \leqslant C \sum_{i} \frac{\eta_{w_{I}}^{2}}{\left|w_{I}-z_{i}(t)\right|^{2}} \leqslant C N \eta_{w_{I}} \operatorname{Re}_{t}\left(w_{I}\right) \leqslant C N \eta_{w_{I}} \frac{\eta_{w^{\prime}}}{\eta_{w_{I}}} \operatorname{Re} m_{t}\left(w^{\prime}\right) \leqslant C \varphi^{2} \operatorname{Re} m_{t}\left(w^{\prime}\right) \leqslant C \varphi^{2}
$$

and, denoting $\eta_{k}=e^{k} \eta_{z}, \tilde{z}_{k}=z \frac{1+\eta_{k}}{1+\eta_{z}}$ so that $\eta_{\tilde{z}_{k}}=\eta_{k}$, we obtain by using $\left|\arg (z)-\arg \left(z_{i}\right)\right| \leqslant C\left|z-z_{i}\right|$ in the first inequality and $-\log \left(\varphi^{2} / N\right) \leqslant \varphi \leqslant \varphi^{3} /\left(N \eta_{z}\right)$ in the last one (with $k \geqslant 0$ in all series below),

$$
\begin{align*}
& \left|\operatorname{Im} m_{t}(z)\right| \leqslant \frac{C}{N} \sum_{i} \frac{\left|\arg z-\arg z_{i}\right|}{\left|z-z_{i}\right|^{2}} \leqslant \frac{C}{N} \sum_{k \geqslant 0, e^{k} \eta_{z} \leqslant\left|z-z_{i}\right| \leqslant e^{k+1} \eta_{z}} \frac{1}{\left|z-z_{i}\right|} \\
& \leqslant \frac{C}{N} \sum_{k \geqslant 0} \frac{\left|\left\{\left|z-z_{i}\right| \leqslant \varphi^{2} / N\right\}\right|}{e^{k} \eta_{z}}+\frac{C}{N} \sum_{\varphi^{2} / N \leqslant e^{k} \eta_{z} \leqslant 1, i} \frac{\eta_{k}}{\left|\tilde{z}_{k}-z_{i}\right|^{2}} \leqslant \frac{C \varphi^{2}}{N \eta_{z}}+C \sum_{\varphi^{2} / N \leqslant e^{k} \eta_{z} \leqslant 1} \operatorname{Re} m_{t}\left(\tilde{z}_{k}\right) \leqslant \frac{\varphi^{3}}{N \eta_{z}} . \tag{4.15}
\end{align*}
$$

From (4.14) with $\left|\operatorname{Re} m_{t}(z)-1\right| \leqslant 1+\operatorname{Re} m_{t}(z)$, 4.15) and their analogue for $1 / 2<|z|<1$, 4.13) extends into (we denote $s(z)=\mathbb{1}_{|z|>1}-\mathbb{1}_{|z|<1}$ )

$$
\begin{equation*}
\mathbb{P}\left(\bigcap_{1 / 2<|z|<2,0<t<\Delta}\left\{\left|m_{t}(z)-s(z)\right| \leqslant \frac{\varphi^{4}}{N \eta_{z}}\right\}\right) \geqslant 1-N^{-D} \tag{4.16}
\end{equation*}
$$

Fourth step: Rigidity of gaps. The inclusion

$$
\begin{equation*}
\bigcap_{1 / 2<|z|<2,0<t<\Delta}\left\{\left|m_{t}(z)-m_{0}\left(z_{t}\right)\right| \leqslant \frac{\varphi^{4}}{N \eta_{z}}\right\} \subset \bigcap_{\substack{0 \leqslant t \leqslant \Delta \\ 1 \leqslant i<j \leqslant N}}\left\{\left|\theta_{i}(t)-\theta_{j}(t)-\left(\gamma_{i}-\gamma_{j}\right)\right| \leqslant \frac{\varphi^{5}}{N}\right\} \tag{4.17}
\end{equation*}
$$

holds for large enough $N$ thanks to the following classical argument based on the Helffer-Sjöstrand formula (2.23). Indeed, let $g(z)=1$ for $\arg z \in\left[\gamma_{i}+\varphi^{4} / N, \gamma_{j}-\varphi^{4} / N\right], g(z)=0$ for $\arg z \in\left[\gamma_{i}, \gamma_{j}\right]^{\mathrm{c}}$, and $\left|g^{\prime}\right| \leqslant$ $C N / \varphi^{4},\left|g^{\prime \prime}\right| \leqslant C\left(N / \varphi^{4}\right)^{2}$. We also pick $\chi$ from 2.23) on scale $\varphi^{4} / N$. On the set from the left-hand side of (4.17), we have

$$
\sum g\left(z_{i}(t)\right)=\frac{N}{2 \pi} \int_{\mathbb{C}} \partial_{\bar{w}} \tilde{g}(w) m_{t}(w) \frac{\mathrm{d} m(w)}{w}=\frac{N}{2 \pi} \int_{\mathbb{C}} \partial_{\bar{w}} \tilde{g}(w) m_{0}\left(w_{t}\right) \frac{\mathrm{d} m(w)}{w}+\mathrm{O}\left(\varphi^{4}\right) \cdot \int_{\mathbb{C}} \frac{\left|\partial_{\bar{w}} \tilde{g}(w)\right|}{\eta_{w}} \mathrm{~d} m(w)
$$

As $\boldsymbol{\theta}(0) \in \widetilde{\mathscr{G}}$, we have $m_{0}\left(w_{t}\right)=\left(\mathbb{1}_{|w|>1}-\mathbb{1}_{|w|<1}\right)+\mathrm{O}\left(\frac{\varphi}{N \eta_{w_{t}}}\right)=\left(\mathbb{1}_{|w|>1}-\mathbb{1}_{|w|<1}\right)+\mathrm{O}\left(\frac{\varphi}{N \eta_{w}}\right)$, so that

$$
\begin{array}{r}
\sum g\left(z_{i}(t)\right)=N \int g\left(e^{\mathrm{i} \theta}\right) \frac{\mathrm{d} \theta}{2 \pi}+\mathrm{O}\left(\varphi^{4}\right) \cdot \int\left(\left|g\left(e^{\mathrm{i} \theta}\right)\right|+\left|g^{\prime}\left(e^{\mathrm{i} \theta}\right)\right|\right) \cdot\left|\chi^{\prime}(r)\right| r \mathrm{~d} r \mathrm{~d} \theta+\mathrm{O}\left(\varphi^{4}\right) \cdot \int\left|g^{\prime \prime}\left(e^{\mathrm{i} \theta}\right)\right| \cdot|\chi(r)| r \mathrm{~d} r \mathrm{~d} \theta \\
\\
=N \int g\left(e^{\mathrm{i} \theta}\right) \frac{\mathrm{d} \theta}{2 \pi}+\mathrm{O}\left(\varphi^{4}\right)
\end{array}
$$

Similarly we have $\sum h\left(z_{i}(t)\right)=\frac{N}{2 \pi} \int h+\mathrm{O}\left(\varphi^{4}\right)$ where $h$ has the same regularity as $g$ and $h(z)=1$ for $\arg z \in\left[\gamma_{i}, \gamma_{j}\right], h(z)=0$ for $\arg z \in\left[\gamma_{i}-\varphi^{4} / N, \gamma_{j}+\varphi^{4} / N\right]^{\mathrm{c}}$. These estimates on $\sum g\left(z_{i}(t)\right)$ and $\sum h\left(z_{i}(t)\right)$ prove (4.17), which together with 4.13) gives

$$
\begin{equation*}
\mathbb{P}\left(\bigcap_{\substack{0 \leqslant t \leqslant \Delta \\ 1 \leqslant i<j \leqslant N}}\left\{\left|\theta_{i}(t)-\theta_{j}(t)-\left(\gamma_{i}-\gamma_{j}\right)\right| \leqslant \frac{\varphi^{5}}{N}\right\}\right) \geqslant 1-N^{-D} \tag{4.18}
\end{equation*}
$$

Fifth step: rigidity of positions. Let $\bar{\theta}(t)=\sum_{i} \theta_{i}(t)$. Then 2.7) gives $\mathrm{d} \bar{\theta}(t)=\sum_{j} \sqrt{\frac{2}{N}} \mathrm{~d} B_{j}(t)=\sqrt{2} \mathrm{~d} B(t)$ where $B$ is a standard Brownian motion. This implies that for any $D>0$ there exists $N_{0}$ such that for $N \geqslant N_{0}$

$$
\begin{equation*}
\mathbb{P}\left(\cap_{0<t<\Delta}\{|\bar{\theta}(t)-\bar{\theta}(0)| \leqslant \varphi\}\right) \geqslant 1-N^{-D} . \tag{4.19}
\end{equation*}
$$

We now write

$$
\theta_{i}(t)-\gamma_{i}=\frac{1}{N} \sum_{j=1}^{N}\left(\left(\theta_{i}(t)-\theta_{j}(t)\right)-\left(\gamma_{i}-\gamma_{j}\right)\right)+\frac{1}{N} \sum_{j=1}^{N}\left(\theta_{j}(t)-\theta_{j}(0)\right)+\frac{1}{N} \sum_{j=1}^{N}\left(\theta_{j}(0)-\gamma_{j}\right)
$$

With probability $1-N^{-D}$, the following holds. For all $i$ and $t \in[0, \Delta]$ the first term is at most $\varphi^{5} / N_{\tilde{\sim}}$ (from (4.18), ) the second is at most $\varphi / N$ (by 4.19), and the last one is at most $C \varphi / N$ because $\boldsymbol{\theta}(0) \in \tilde{\mathscr{G}}$. This concludes the proof.
4.3 Finite rank projections. The result below shows the following: eigenvectors perturbations under mean field noise are simply given at the level of the resolvent by moving the spectral parameter through the characteristics. It is a simple analogue of 21 , Theorem 2.1], which considers Hermitian perturbations out of equilibrium, but our dynamical proof is different from 21, which proceeds through the Schur complement formula. Such estimates on arbitrary (finite rank) projections of the resolvent first appeared in the context of Wigner and covariance matrices, see e.g. 17] and references therein.

Proposition 4.3. For any $D>0$ there exists $N_{0}$ such that for any $N \geqslant N_{0}$ and $q \in \mathbb{C}^{N} \mathscr{F}_{s}$-measurable $\left(\mathscr{F}_{s}=\sigma\left(U_{u}, u \leqslant s\right)\right),|q|=1$, we have

$$
\mathbb{P}\left(\left.\bigcap_{\substack{s<t<s+\Delta \\\left|\eta_{z}\right|>\varphi^{20} / N}}\left\{\left|\left\langle q, \frac{z+U_{t}}{z-U_{t}} q\right\rangle-\left\langle q, \frac{z_{t-s}+U_{s}}{z_{t-s}-U_{s}} q\right\rangle\right| \leqslant \frac{\varphi}{\sqrt{N \eta_{z}}} \operatorname{Re}\left\langle q, \frac{z_{t-s}+U_{s}}{z_{t-s}-U_{s}} q\right\rangle\right\} \right\rvert\, \boldsymbol{\theta}(s) \in \mathscr{G}\right) \geqslant 1-N^{-D}
$$

Note that the above real part is always positive.
Proof. We choose $A=q q^{*}$ in Lemma 4.1. Defining

$$
q_{t}(z)=\left\langle q, \frac{z+U_{t}}{z-U_{t}} q\right\rangle
$$

this gives

$$
\mathrm{d} q_{t}(z)=m_{t}(z) z \partial_{z} q_{t}(z)+2 z q^{*} \frac{U}{z-U} \sqrt{2} \mathrm{~d} B_{t} \frac{1}{z-U} q .
$$

We can assume $s=0$ and first consider some $|z|>1+\varphi^{20} / N$. Then
$\mathrm{d} q_{u}\left(z_{t-u}\right)=\left(m_{u}\left(z_{t-u}\right)-1\right) z_{t-u} \partial_{z} q_{u}\left(z_{t-u}\right) \mathrm{d} u+\frac{2 \sqrt{2} \mathrm{i} z_{t-u}}{N^{1 / 2}} \sum_{k, j} q^{*} u_{j}(u) \frac{z_{j}(u)}{z_{t-u}-z_{j}(u)} \mathrm{d} \hat{B}_{j k}(u) \frac{1}{z_{t-u}-z_{k}(u)} u_{k}(u)^{*} q$,
where the $\hat{B}_{j k}$ are independent Brownian motions defined before 4.4 . We define the stopping times

$$
\begin{align*}
\tau_{q} & :=\inf \left\{u \in[0, t]:\left|q_{0}\left(z_{t}\right)-q_{u}\left(z_{t-u}\right)\right|>\frac{\varphi^{1 / 10}}{\sqrt{N \eta_{z_{t-u}}}} \operatorname{Re} q_{0}\left(z_{t}\right)\right\}  \tag{4.21}\\
\tau: & =\inf \left\{u \in[0, t]: \exists k \in \llbracket 1, N \rrbracket,\left|\theta_{k}(u)-\gamma_{k}\right|>\frac{\varphi^{8}}{N}\right\}  \tag{4.22}\\
\sigma: & =\tau \wedge \tau_{q} \tag{4.23}
\end{align*}
$$

The quadratic variation of the martingale term in 4.20 stopped at $\sigma$ is bounded with

$$
\begin{equation*}
\frac{C}{N} \int_{0}^{\sigma} \sum_{j, k}\left|z_{t-u}\right|^{2} \frac{\left|\left\langle q, u_{j}(u)\right\rangle\right|^{2}}{\left|z_{t-u}-z_{j}(u)\right|^{2}} \cdot \frac{\left|\left\langle q, u_{k}(u)\right\rangle\right|^{2}}{\left|z_{t-u}-z_{k}(u)\right|^{2}} \mathrm{~d} u \leqslant \frac{C}{N} \int_{0}^{\sigma} \frac{\left|z_{t-u}\right|^{2}\left(\operatorname{Re}\left(q_{u}\left(z_{t-u}\right)\right)\right)^{2}}{\left(1+\left|z_{t-u}\right|\right)^{2} \eta_{z_{t-u}}^{2}} \mathrm{~d} u \leqslant C \frac{\operatorname{Re}\left(q_{0}\left(z_{t}\right)\right)^{2}}{N \eta_{z_{t-\sigma}}} \tag{4.24}
\end{equation*}
$$

where we have used

$$
\sum_{j} \frac{\left|\left\langle q, u_{j}(u)\right\rangle\right|^{2}}{\left|z-z_{j}(u)\right|^{2}}=\frac{1}{|z|^{2}-1} \operatorname{Re} q_{u}(z)
$$

Similarly to the estimate after 4.2 , this implies that this martingale term is bounded with $\frac{\varphi^{1 / 10}}{\sqrt{N \eta_{z_{t-\sigma}}}} \operatorname{Re} q_{0}\left(z_{t}\right)$ with probability $1-N^{-D}$. Moreover, the finite variation error term from 4.20 is bounded with

$$
\int_{0}^{\sigma}\left|z_{t-u}\right| \cdot\left|m_{u}\left(z_{t-u}\right)-1\right| \cdot\left|\partial_{z} q_{u}\left(z_{t-u}\right)\right| \mathrm{d} u \leqslant C \int_{0}^{\sigma} \frac{\varphi^{8}\left|z_{t-u}\right|}{N \eta_{z_{t-u}}} \cdot \frac{\operatorname{Re} q_{u}\left(z_{t-u}\right)}{\eta_{z_{t-u}}\left(1+\left|z_{t-u}\right|\right)} \mathrm{d} u \leqslant \frac{C \varphi^{8} \operatorname{Re} q_{0}\left(z_{t}\right)}{N \eta_{z_{t-\sigma}}} \leqslant \frac{C \operatorname{Re} q_{0}\left(z_{t}\right)}{\sqrt{N \eta_{z_{t-\sigma}}}}
$$

where we have first used that for $u<\tau$ we have $m_{u}(z)-1=\mathrm{O}\left(\varphi^{8} /\left(N \eta_{z}\right)\right)$, and finally we have used $\left|\eta_{z_{t-\sigma}}\right|>\varphi^{20} / N$. We have therefore proved that for any $D>0$ there is a $N_{0}$ such that for $N \geqslant N_{0}$ and $|z|>1+\varphi^{20} / N$ we have

$$
\mathbb{P}\left(\left|q_{\sigma}\left(z_{t-\sigma}\right)-q_{0}\left(z_{t}\right)\right|>\frac{\varphi^{1 / 10}}{\sqrt{N \eta_{z_{t}-\sigma}}} \operatorname{Re} q_{0}\left(z_{t}\right)\right) \leqslant N^{-D}
$$

By definition of $\tau_{q}$ this implies $\mathbb{P}(\sigma=\tau) \geqslant 1-N^{-D}$. Moreover, from Proposition 4.2, $\mathbb{P}(\tau=t) \geqslant 1-N^{-D}$ (this proposition naturally also holds when replacing exponents $\varphi, \varphi^{6}$ defining $\mathscr{G}, \mathscr{G}$ with $\varphi^{6}, \varphi^{8}$ ), so we have proved

$$
\mathbb{P}\left(\left|q_{t}(z)-q_{0}\left(z_{t}\right)\right|>\frac{\varphi^{1 / 9}}{\sqrt{N \eta_{z_{t-\sigma}}}} \operatorname{Re} q_{0}\left(z_{t}\right)\right) \leqslant N^{-D}
$$

Uniformity in $t \in[0, \Delta]$ and $\eta_{z} \in\left[\varphi^{20} / N, 1 / 2\right]$ follows easily by a grid argument similar to the second step in the proof of Proposition 4.2.

Finally, for uniformity in $\eta_{z}>1 / 2$, denote $f(z)=\left\langle q, \frac{z+U_{t}}{z-U_{t}} q\right\rangle, g(z)=\left\langle q, \frac{z_{t}+U_{0}}{z_{t}-U_{0}} q\right\rangle$. We have proved that with overwhelming probability $\left|\frac{f}{g}(z)-1\right| \leqslant \frac{\varphi^{1 / 9}}{\sqrt{N \eta_{z}}}$. As $f / g-1 \rightarrow 0$ as $|z| \rightarrow \infty$, the Cauchy integral formula for $z$ outside the contour $|w|=6 / 5$ gives, for $|z|>7 / 5, f / g(z)-1=\mathrm{O}\left(\frac{\varphi^{1 / 9}}{|z| \sqrt{N}}\right)$, which concludes the proof.

Polarization in Proposition 4.3 shows that if $u_{a}(s), u_{b}(s)$ are normalized eigenvectors of $U(s)$ and $a \neq b$, then for $|z|>1+\varphi^{20} / N$ we have

$$
\left|\left\langle u_{a}(s), \frac{z+U_{t}}{z-U_{t}} u_{b}(s)\right\rangle\right| \leqslant \varphi \frac{\eta_{z_{t-s}}\left(\left|z_{t-s}\right|+1\right)}{\sqrt{N \eta_{z}}}\left(\frac{1}{\left|z_{t-s}-z_{a}(s)\right|^{2}}+\frac{1}{\left|z_{t-s}-z_{b}(s)\right|^{2}}\right)
$$

with overwhelming probability. This error term is not enough for Proposition 4.5 in the next subsection, so we first obtain the following essentially optimal bound.

Proposition 4.4. For any $D, \varepsilon>0$ there exists $N_{0}$ such that for any $N \geqslant N_{0}$ and $u_{a}(s) u_{b}(s) \in \mathbb{C}^{N}$ eigenvectors of $U(s)$ associated to distinct eigenvalues $\left(\left|u_{a}\right|=\left|u_{b}\right|=1\right)$ we have

Proof. We choose $A=u_{b}(s) u_{a}(s)^{*}$ in Lemma 4.1, and we abbreviate $a=u_{a}(s), b=u_{b}(s)$. Defining

$$
p_{t}(z)=p_{t}^{a, b}(z)=\left\langle a, \frac{z+U_{t}}{z-U_{t}} b\right\rangle
$$

this gives

$$
\mathrm{d} p_{t}(z)=m_{t}(z) z \partial_{z} p_{t}(z)+2 z u_{a}(s)^{*} \frac{U}{z-U} \sqrt{2} \mathrm{~d} B_{t} \frac{1}{z-U} u_{b}(s)
$$

We can assume $s=0$. Note that $p_{0}\left(z_{t}\right)=0$ and we want to bound $p_{t}(z)$. We first consider some $|z|>$ $1+\varphi^{30} / N$. Then
$\mathrm{d} p_{u}\left(z_{t-u}\right)=\left(m_{u}\left(z_{t-u}\right)-1\right) z_{t-u} \partial_{z} p_{u}\left(z_{t-u}\right) \mathrm{d} u+\frac{2 \sqrt{2} \mathrm{i} z_{t-u}}{N^{1 / 2}} \sum_{k, j} a^{*} u_{j}(u) \frac{z_{j}(u)}{z_{t-u}-z_{j}(u)} \mathrm{d} \hat{B}_{j k}(u) \frac{1}{z_{t-u}-z_{k}(u)} u_{k}(u)^{*} b$,
where the $\hat{B}_{j k}$ are independent Brownian motions and $\hat{B}_{j j}=\hat{B}_{j}$ from 4.5. The quadratic variation of the martingale term in 4.25 is bounded with

$$
\frac{C}{N} \int_{0}^{t} \frac{C\left|z_{t-u}\right|^{2}}{\eta_{z_{t-u}}^{2}\left(1+\left|z_{t-u}\right|^{2}\right)} \operatorname{Re}\left\langle a, \frac{z_{t-u}+U(u)}{z_{t-u}-U(u)} a\right\rangle \operatorname{Re}\left\langle b, \frac{z_{t-u}+U(u)}{z_{t-u}-U(u)} b\right\rangle \mathrm{d} u
$$

From Proposition 4.3, with probability $1-N^{-3 D}$ this is bounded with

$$
\frac{C}{N} \int_{0}^{t} \frac{1}{\eta_{z_{t-u}}^{2}} \operatorname{Re}\left\langle a \frac{z_{t}+U(0)}{z_{t}-U(0)} a\right\rangle \operatorname{Re}\left\langle b \frac{z_{t}+U(0)}{z_{t}-U(0)} b\right\rangle \mathrm{d} u \leqslant \frac{C}{N \eta_{z}} \frac{\eta_{z_{t}}\left(1+\left|z_{t}\right|\right)}{\left|z_{t}-z_{a}(0)\right|^{2}} \frac{\eta_{z_{t}}\left(1+\left|z_{t}\right|\right)}{\left|z_{t}-z_{b}(0)\right|^{2}}
$$

so that with probability $1-N^{-2 D}$ the martingale term in 4.25 is bounded with $\frac{\varphi}{\sqrt{N \eta_{z}}} \frac{\eta_{z_{t}}\left(1+\left|z_{t}\right|\right)}{\left|z_{t}-z_{a}(0)\right| \cdot\left|z_{t}-z_{b}(0)\right|}$, which is the expected error.

A new difficulty comes from the finite variation error term in 4.25 : for $a \neq b, \operatorname{Re} p^{a, b}$ has no a priori sign. We therefore first simply bound $\left|\partial_{z} p_{u}^{a, b}\right| \leqslant \frac{C}{\eta_{z}(1+|z|)}\left(\operatorname{Re} p_{u}^{a, a}+\operatorname{Re} p_{u}^{b, b}\right)$ and use Proposition 4.3 to obtain

$$
\begin{aligned}
& \int_{0}^{t}\left|z_{t-u}\right| \cdot\left|m_{u}\left(z_{t-u}\right)-1\right| \cdot\left|\partial_{z} p_{u}^{a, b}\left(z_{t-u}\right)\right| \mathrm{d} u \leqslant \int_{0}^{t} \frac{\varphi^{8}\left|z_{t-u}\right|}{N \eta_{z_{t-u}}} \cdot \frac{\operatorname{Re} p_{u}^{a, a}\left(z_{t-u}\right)+\operatorname{Re} p_{u}^{b, b}\left(z_{t-u}\right)}{\eta_{z_{t-u}}\left(1+\left|z_{t-u}\right|\right)} \mathrm{d} u \\
& \leqslant \frac{\varphi^{8}}{N \eta_{z}} \cdot\left(\operatorname{Re} p_{0}^{a, a}\left(z_{t}\right)+\operatorname{Re} p_{0}^{b, b}\left(z_{t}\right)\right) \leqslant \frac{\varphi^{8} \eta_{z_{t}}\left(1+\left|z_{t}\right|\right)}{N \eta_{z}} \cdot\left(\frac{1}{\left|z_{t}-z_{a}(0)\right|^{2}}+\frac{1}{\left|z_{t}-z_{b}(0)\right|^{2}}\right) .
\end{aligned}
$$

We have therefore proved, that, for any $D>0$ there exists $N_{0}$ such that for any $N \geqslant N_{0}$, with probability $1-N^{-D}$ we have

$$
\left|p_{t}^{a, b}(z)\right| \leqslant \frac{\varphi^{8} \eta_{z_{t}}\left(1+\left|z_{t}\right|\right)}{\sqrt{N \eta_{z}}} \frac{1}{\left|z_{t}-z_{a}(0)\right| \cdot\left|z_{t}-z_{b}(0)\right|}+\frac{\varphi^{8} \eta_{z_{t}}\left(1+\left|z_{t}\right|\right)}{N \eta_{z}} \cdot\left(\frac{1}{\left|z_{t}-z_{a}(0)\right|^{2}}+\frac{1}{\left|z_{t}-z_{b}(0)\right|^{2}}\right)
$$

for any $\eta_{z}>\varphi^{30} / N$ and $t \in[0, \Delta]$ (uniformity in $z, t$ requires (1) an omitted grid argument identical to the second step in the proof of Proposition 4.2 for $\eta_{z} \in\left[\varphi^{30} / N, 1 / 2\right], t \in[0, \Delta]$, (2) a contour integral argument similar to the end of the proof of Proposition 4.3 to extend to $\eta_{z}>1 / 2$ ).

We now iterate by injecting this estimate in the finite variation term from 4.25. More precisely, consider the following induction hypothesis $\left(\mathrm{P}_{n}\right)$ : For any $D>0$ there exists $N_{0}=N_{0}(n, D)$, such that for any $N \geqslant N_{0}, a, b \in \llbracket 1, N \rrbracket$, the following holds with probability $1-N^{-D}$ : for any $0<t<\Delta$ and $\eta_{z}>\varphi^{30 n} / N$ we have

$$
\left|p_{t}^{a, b}(z)\right| \leqslant \frac{\varphi^{8 n} \eta_{z_{t}}\left(1+\left|z_{t}\right|\right)}{\sqrt{N \eta_{z}}} \frac{1}{\left|z_{t}-z_{a}(0)\right| \cdot\left|z_{t}-z_{b}(0)\right|}+\frac{\varphi^{8 n} \eta_{z_{t}}\left(1+\left|z_{t}\right|\right)}{\left(N \eta_{z}\right)^{n}} \cdot\left(\frac{1}{\left|z_{t}-z_{a}(0)\right|^{2}}+\frac{1}{\left|z_{t}-z_{b}(0)\right|^{2}}\right)
$$

We have just proved $\left(P_{1}\right)$, and to prove that $\left(P_{n}\right)$ implies $\left(P_{n+1}\right)$ we just need to improve on the finite variation term. By Cauchy's formula,

$$
\begin{aligned}
& \int_{0}^{t}\left|z_{t-u}\right| \cdot\left|m_{u}\left(z_{t-u}\right)-1\right| \cdot\left|\partial_{z} p_{u}^{a, b}\left(z_{t-u}\right)\right| \mathrm{d} u \leqslant \int_{0}^{t} \frac{\varphi^{8}\left|z_{t-u}\right|}{N \eta_{z_{t-u}}} \cdot \frac{\max _{\left|w-z_{t-u}\right|=\eta_{z_{t-u} / 10}\left|p_{u}^{a, b}(w)\right|}^{\eta_{z_{t-u}}\left(1+\left|z_{t-u}\right|\right)} \mathrm{d} u}{} \\
\leqslant & \int_{0}^{t} \frac{1}{N \eta_{z_{t-u}}^{2}}\left(\frac{\varphi^{8(n+1)} \eta_{z_{t}}\left(1+\left|z_{t}\right|\right)}{\sqrt{N \eta_{z_{t-u}}}} \frac{1}{\left|z_{t}-z_{a}(0)\right| \cdot\left|z_{t}-z_{b}(0)\right|}+\frac{\varphi^{8(n+1)} \eta_{z_{t}}\left(1+\left|z_{t}\right|\right)}{\left(N \eta_{z_{t-u}}\right)^{n}} \cdot\left(\frac{1}{\left|z_{t}-z_{a}(0)\right|^{2}}+\frac{1}{\left|z_{t}-z_{b}(0)\right|^{2}}\right)\right) \mathrm{d} u \\
\leqslant & \frac{\varphi^{8(n+1)} \eta_{z_{t}}\left(1+\left|z_{t}\right|\right)}{\sqrt{N \eta_{z}}} \frac{1}{\left|z_{t}-z_{a}(0)\right| \cdot\left|z_{t}-z_{b}(0)\right|}+\frac{\varphi^{8(n+1)} \eta_{z_{t}}\left(1+\left|z_{t}\right|\right)}{\left(N \eta_{z}\right)^{n+1}} \cdot\left(\frac{1}{\left|z_{t}-z_{a}(0)\right|^{2}}+\frac{1}{\left|z_{t}-z_{b}(0)\right|^{2}}\right)
\end{aligned}
$$

This completes the induction and the proof of the proposition by choosing $n=100 / \varepsilon$ (now $\eta_{z}>N^{\varepsilon} / N$ ).
4.4 Full rank projections. We now prove the main estimate to reach optimal scales for multi-time loop equations, concerning the following resolvent projection,

$$
\begin{equation*}
\operatorname{Tr}\left(\frac{v+U_{t}}{v-U_{t}} \cdot \frac{w+U_{s}}{w-U_{s}}\right)=\sum_{k} \frac{w+z_{k}(s)}{w-z_{k}(s)}\left\langle u_{k}(s), \frac{v+U_{t}}{v-U_{t}} u_{k}(s)\right\rangle \tag{4.26}
\end{equation*}
$$

If we add the error estimates from Proposition 4.3 on the above right-hand side, for example for $\eta_{w} \sim 1$, the obtained bound is $\sqrt{N / \eta_{v}}$, far worse than the bound $1 / \eta_{v}$ below. The key source of improvement to achieve the optimal result below is Proposition 4.4. The averaged and multi-time local law below seems to be new, including in the context of Hermitian random matrices.

In the following statement, we use the notation $d(v, w)=\max \left(|v-w|,\left|v-\frac{w}{|w|^{2}}\right|\right)$.
Proposition 4.5. For any $D, \varepsilon>0$ there exists $N_{0}$ such that for any $N \geqslant N_{0}$ we have

$$
\mathbb{P}\left(\left.\bigcap_{\substack{s<t<s+\Delta \\ \eta_{w} \in\left[\frac{N^{e}}{N}, \frac{1}{2}\right] \\ \eta_{v} \in\left(0, \frac{1}{2}\right]}}\left\{\left|\operatorname{Tr}\left(\frac{v+U_{t}}{v-U_{t}} \cdot \frac{w+U_{s}}{w-U_{s}}\right)-\operatorname{Tr}\left(\frac{v_{t-s}+U_{s}}{v_{t-s}-U_{s}} \cdot \frac{w+U_{s}}{w-U_{s}}\right)\right| \leqslant \frac{N^{\varepsilon}\left(1+\left|v_{t-s}\right|\right)}{\sqrt{\eta_{v} \min \left(\eta_{w}, \eta_{v}\right)} d\left(w, v_{t-s}\right)}\right\} \right\rvert\, \boldsymbol{\theta}(s) \in \mathscr{G}\right) \geqslant 1-N^{-D}
$$

Proof. We can again assume $s=0$, and first consider the case $|w|,|v| \in\left[1+N^{\varepsilon} / N, 3 / 2\right]$. Lemma 4.1 with $A=\frac{w+U_{0}}{w-U_{0}}$ gives

$$
\begin{align*}
\operatorname{Tr}\left(\frac{v+U_{t}}{v-U_{t}} \cdot A\right)-\operatorname{Tr}\left(\frac{v_{t}+U_{0}}{v_{t}-U_{0}} \cdot A\right)=\int_{0}^{t} v_{t-u} & \left(m_{u}\left(v_{t-u}\right)-1\right) \partial_{v} m_{u, A}\left(v_{t-u}\right) \mathrm{d} u \\
& +2 \int_{0}^{t} v_{t-u} \operatorname{Tr}\left(\frac{1}{v_{t-u}-U_{u}} A \frac{U_{u}}{v_{t-u}-U_{u}} \sqrt{2} \mathrm{~d} B_{u}\right) . \tag{4.27}
\end{align*}
$$

The above stochastic integral can also be written

$$
\frac{\sqrt{2}}{\sqrt{N}} \int_{0}^{t} \sum_{j, k} \frac{v_{t-u}}{v_{t-u}-z_{j}(u)} \frac{z_{k}(t)}{v_{t-u}-z_{k}(u)}\left\langle u_{j}(u), A u_{k}(u)\right\rangle \mathrm{d} \hat{B}_{j k}(u)
$$

where the $\hat{B}_{j k}$ are independent, standard Brownian motions. Abbreviating $\ell=u_{\ell}(0)$ and using the spectral decomposition $A=\sum_{\ell} \frac{w+z_{\ell}(0)}{w-z_{\ell}(0)} \ell^{*} \ell$, the bracket of the above stochastic integral is (we denote, in this proof, $\left.\langle x, y\rangle=x^{*} y\right)$

$$
\begin{align*}
& \left.\frac{C}{N} \int_{0}^{t} \sum_{j, k} \frac{\left|v_{t-u}\right|^{2}}{\left|v_{t-u}-z_{j}(u)\right|^{2}} \frac{1}{\left|v_{t-u}-z_{k}(u)\right|^{2}} \right\rvert\,\left\langle u_{j}(u),\left.A u_{k}(u)\right|^{2} \mathrm{~d} u\right. \\
= & \frac{C}{N} \int_{0}^{t} \sum_{j, k} \frac{\left|v_{t-u}\right|^{2}}{\left|v_{t-u}-z_{j}(u)\right|^{2}} \frac{1}{\left|v_{t-u}-z_{k}(t)\right|^{2}}\left|\sum_{\ell}\left\langle u_{j}(u), \ell\right\rangle\left\langle\ell, u_{k}(u)\right\rangle \frac{w+z_{\ell}(0)}{w-z_{\ell}(0)}\right|^{2} \mathrm{~d} u \\
= & \frac{C}{N} \int_{0}^{t} \sum_{\ell_{1}, \ell_{2}, j, k} \frac{w+z_{\ell_{1}(0)}(0)}{\overline{w-z_{\ell_{1}}(0)} \frac{\overline{w+z_{\ell_{2}}(0)}}{\overline{w-z_{\ell_{2}}(0)}} \frac{\left|v_{t-u}\right|^{2}}{\left|v_{t-u}-z_{j}(u)\right|^{2}} \frac{1}{\left|v_{t-u}-z_{k}(u)\right|^{2}}\left\langle u_{j}(u), \ell_{1}\right\rangle\left\langle\ell_{1}, u_{k}(u)\right\rangle \overline{\left\langle u_{j}(u), \ell_{2}\right\rangle\left\langle\ell_{2}, u_{k}(u)\right\rangle} \mathrm{d} u} \\
= & \frac{C}{N} \int_{0}^{t} \sum_{\ell_{1}, \ell_{2}} \frac{w+z_{\ell_{1}}(0)}{\overline{w-z_{\ell_{1}}(0)} \frac{\overline{w+z_{\ell_{2}}(0)}}{\overline{w-z_{\ell_{2}}(0)}}\left|v_{t-u}\right|^{2}\left|\sum_{j} \frac{\left\langle\ell_{2}, u_{j}(u)\right\rangle\left\langle u_{j}(u), \ell_{1}\right\rangle}{\left|v_{t-u}-z_{j}(u)\right|^{2}}\right|^{2} \mathrm{~d} u} \\
\leqslant & \frac{C}{N} \int_{0}^{t} \frac{1}{\eta_{v_{t-u}}^{2}} \sum_{\ell_{1}, \ell_{2}} \frac{1}{\left|w-z_{\ell_{1}}(0)\right| \cdot\left|w-z_{\ell_{2}}(0)\right|}\left(\operatorname{Re}\left\langle\ell_{2}, \frac{v_{t-u}+U(u)}{v_{t-u}-U(u)} \ell_{1}\right\rangle\right)^{2} \mathrm{~d} u . \tag{4.28}
\end{align*}
$$

From Proposition 4.4, with probability $1-N^{-4 D}$ the contribution from $\ell_{1} \neq \ell_{2}$ in the above sum leads to evaluating

$$
\sum_{\ell_{1}, \ell_{2}} \frac{N^{\varepsilon}}{\left.\left|w-z_{\ell_{1}}(0)\right| \cdot \mid w-z_{\ell_{2}}(0)\right) \mid} \frac{\eta_{v_{t}}^{2}\left(1+\left|v_{t}\right|^{2}\right)}{N \eta_{v_{t-u}}} \frac{1}{\left|v_{t}-z_{\ell_{1}}(0)\right|^{2}} \frac{1}{\left|v_{t}-z_{\ell_{2}}(0)\right|^{2}}=\frac{N^{1+\varepsilon}}{\eta_{v_{t-u}}}\left(\frac{1}{N} \sum_{\ell} \frac{\left(1+\left|v_{t}\right|\right) \eta_{v_{t}}}{\left|w-z_{\ell}(0)\right| \cdot\left|v_{t}-z_{\ell}(0)\right|^{2}}\right)^{2}
$$

As $\min \left(\eta_{v}, \eta_{w}\right)>N^{-1+\varepsilon}$, by Proposition 4.2 the following holds with overwhelming probability:

$$
\begin{equation*}
\frac{1}{N} \sum_{\ell} \frac{\eta_{v_{t}}}{\left|w-z_{\ell}(0)\right| \cdot\left|v_{t}-z_{\ell}(0)\right|^{2}} \leqslant C \int \frac{\eta_{v_{t}}}{|w-\lambda| \cdot\left|v_{t}-\lambda\right|^{2}} \mathrm{~d} \lambda \leqslant \frac{C}{d\left(w, v_{t}\right)} \mathbb{1}_{\eta_{v_{t}}<\eta_{w}}+\frac{C \log N}{d\left(w, v_{t}\right)} \mathbb{1}_{\eta_{v_{t}} \geqslant \eta_{w}} . \tag{4.29}
\end{equation*}
$$

Moreover, the contribution from the diagonal terms in 4.28 leads to a sum evaluated with Proposition 4.3

$$
\sum_{\ell} \frac{1}{\left|w-z_{\ell}(0)\right|^{2}}\left(\operatorname{Re}\left\langle\ell, \frac{v_{t-u}+U(u)}{v_{t-u}-U(u)} \ell\right\rangle\right)^{2} \leqslant \sum_{\ell} \frac{C}{\left|w-z_{\ell}(0)\right|^{2}}\left(\operatorname{Re} \frac{v_{t}+z_{\ell}(0)}{v_{t}-z_{\ell}(0)}\right)^{2} \leqslant \sum_{\ell} \frac{C\left(1+\left|v_{t}\right|^{2}\right) \eta_{v_{t}}^{2}}{\left|w-z_{\ell}(0)\right|^{2} \cdot\left|v_{t}-z_{\ell}(0)\right|^{4}}
$$

and with rigidity from Proposition 4.2 we have

$$
\frac{1}{N} \sum_{\ell} \frac{\eta_{v_{t}}^{2}}{\left|w-z_{\ell}(0)\right|^{2} \cdot\left|v_{t}-z_{\ell}(0)\right|^{4}} \leqslant \int \frac{C \eta_{v_{t}}^{2}}{|w-\lambda|^{2}\left|v_{t}-\lambda\right|^{4}} \mathrm{~d} \lambda \leqslant \frac{C}{\eta_{v_{t}} d\left(w, v_{t}\right)^{2}} \mathbb{1}_{\eta_{v_{t}}<\eta_{w}}+\frac{C}{\eta_{w} d\left(w, v_{t}\right)^{2}} \mathbb{1}_{\eta_{v_{t}} \geqslant \eta_{w}}
$$

Using the previous four estimates in 4.28, with probability $1-N^{-3 D}$ the bracket of 4.27 is bounded with

$$
C N^{\varepsilon} \int_{0}^{t} \frac{1}{\eta_{v_{t-u}}^{2}}\left(\frac{1+\left|v_{t}\right|^{2}}{\eta_{v_{t-u}} d\left(w, v_{t}\right)^{2}}+\frac{1+\left|v_{t}\right|^{2}}{\min \left(\eta_{v_{t}}, \eta_{w}\right) d\left(w, v_{t}\right)^{2}}\right) \mathrm{d} u \leqslant \frac{C N^{\varepsilon}\left(1+\left|v_{t}\right|^{2}\right)}{\eta_{v} \min \left(\eta_{v}, \eta_{w}\right) d\left(w, v_{t}\right)^{2}}
$$

so, with probability $1-N^{-2 D}, 4.27$ is smaller than $\frac{N^{\varepsilon}\left(1+\left|v_{t}\right|\right)}{\sqrt{\eta_{v} \min \left(\eta_{v}, \eta_{w}\right)} d\left(w, v_{t}\right)}$. We now consider the error term due to the finite variation term, based on 4.26):

$$
\begin{aligned}
&\left.\mid \partial_{v} m_{u, A}\left(v_{t-u}\right)\right) \left\lvert\, \leqslant \sum \frac{1}{\left|w-z_{k}(0)\right|} \frac{1}{\eta_{v_{t-u}}\left(1+\left|v_{t-u}\right|\right.} \operatorname{Re}\left\langle k, \frac{v_{t-u}+U_{u}}{v_{t-u}-U_{u}} k\right\rangle\right. \\
& \leqslant \sum \frac{C}{\left|w-z_{k}(0)\right|} \frac{1}{\eta_{v_{t-u}}\left(1+\left|v_{t-u}\right|\right)} \frac{1}{\left|v_{t}-z_{k}(0)\right|} \leqslant \frac{C N^{1+\varepsilon}}{\eta_{v_{t-u}}\left(1+\left|v_{t-u}\right|\right) d\left(w, v_{t}\right)}
\end{aligned}
$$

so

$$
\left.\int_{0}^{t}\left|v_{t-u}\right| \cdot\left|m_{u}\left(v_{t-u}\right)-1\right| \cdot \mid \partial_{v} m_{u, A}\left(v_{t-u}\right)\right) \left\lvert\, \mathrm{d} u \leqslant \frac{N^{\varepsilon}}{\eta_{v} d\left(w, v_{t}\right)}\right.
$$

This concludes the proof of the proposition for $|w|,|v| \in\left[1+N^{\varepsilon} / N, 3 / 2\right]$. The proof for $|w|$ or $|v|$ in $\left[1 / 2,1-N^{\varepsilon} / N\right]$ is strictly similar, and uniformity in $v, w$ and $t \in[0, \Delta]$ follows from the same grid argument as in the second step in the proof of Proposition 4.2 .

We now consider the case $|v| \in\left[1,1+N^{\varepsilon} / N\right]$ and $|w|>1+N^{\varepsilon} / N$ (in particular, from now $\eta_{v}<\eta_{w}$ ), relying on the following analogue of (4.14), where we now denote $v^{\prime}$ with the same argument as $v$ such that $\eta_{v^{\prime}}=N^{-1+\varepsilon}$ :

$$
\begin{equation*}
\operatorname{Re}\left\langle q, \frac{v+U_{t}}{v-U_{t}} q\right\rangle \leqslant C \frac{\eta_{v^{\prime}}}{\eta_{v}} \operatorname{Re}\left\langle q \frac{v^{\prime}+U_{t}}{v^{\prime}-U_{t}} q\right\rangle \tag{4.30}
\end{equation*}
$$

In the sequence below we start with 4.26, use 4.30 and proceed similarly to 4.15 to bound the contribution from $\operatorname{Im}\left\langle q, \frac{v+U_{t}}{v-U_{t}} q\right\rangle$, denoting $v_{k}$ with the same argument as $v$ such that $\eta_{v_{k}}=e^{k} \eta_{v}$ :

$$
\begin{aligned}
\left|\operatorname{Tr}\left(\frac{v+U_{t}}{v-U_{t}} \cdot \frac{w+U_{0}}{w-U_{0}}\right)\right| & \leqslant \sum_{k} \frac{C}{\left|w-z_{k}(0)\right|}\left(\operatorname{Re}\left\langle u_{k}(0), \frac{v+U_{t}}{v-U_{t}} u_{k}(0)\right\rangle+\left|\operatorname{Im}\left\langle u_{k}(0), \frac{v+U_{t}}{v-U_{t}} u_{k}(0)\right\rangle\right|\right) \\
& \leqslant \sum_{k} \frac{C}{\left|w-z_{k}(0)\right|}\left(\frac{N^{\varepsilon}}{N \eta_{v}} \operatorname{Re}\left\langle u_{k}(0), \frac{v^{\prime}+U_{t}}{v^{\prime}-U_{t}} u_{k}(0)\right\rangle+\sum_{N^{\varepsilon} / N \leqslant e^{k} \eta_{v} \leqslant 1} \operatorname{Re}\left\langle u_{k}(0), \frac{v_{k}+U_{t}}{v_{k}-U_{t}} u_{k}(0)\right\rangle\right) \\
& \leqslant \sum_{k} \frac{C}{\left|w-z_{k}(0)\right|}\left(\frac{N^{\varepsilon}}{N \eta_{v}} \operatorname{Re}\left\langle u_{k}(0), \frac{v_{t}^{\prime}+U_{0}}{v_{t}^{\prime}-U_{0}} u_{k}(0)\right\rangle+\sum_{N^{\varepsilon} / N \leqslant e^{k} \eta_{v} \leqslant 1} \operatorname{Re}\left\langle u_{k}(0), \frac{\left(v_{k}\right)_{t}+U_{0}}{\left(v_{k}\right)_{t}-U_{0}} u_{k}(0)\right\rangle\right) \\
& =\sum_{k} \frac{C}{\left|w-z_{k}(0)\right|}\left(\frac{N^{\varepsilon}}{N \eta_{v}} \operatorname{Re} \frac{v_{t}^{\prime}+z_{k}(0)}{v_{t}^{\prime}-z_{k}(0)}+\sum_{N^{\varepsilon} / N \leqslant e^{k} \eta_{v} \leqslant 1} \operatorname{Re} \frac{\left(v_{k}\right)_{t}+z_{k}(0)}{\left(v_{k}\right)_{t}-z_{k}(0)}\right) \\
& \leqslant \sum_{k} \frac{C}{\left|w-z_{k}(0)\right|}\left(\frac{N^{\varepsilon}}{N \eta_{v}} \frac{\eta_{v_{t}^{\prime}}\left(1+\left|v_{t}^{\prime}\right|\right)}{\left|v_{t}^{\prime}-z_{k}(0)\right|^{2}}+\sum_{N^{\varepsilon} / N \leqslant e^{k} \eta_{v} \leqslant 1} \frac{\left.\eta_{\left(v_{k}\right)_{t}\left(1+\left|\left(v_{k}\right)_{t}\right|\right)}^{\left|\left(v_{k}\right)_{t}-z_{k}(0)\right|^{2}}\right) .}{}\right)
\end{aligned}
$$

As in 4.29, we have

$$
\sum_{k} \frac{\eta_{v_{t}^{\prime}}}{\left|w-z_{k}(0)\right| \cdot\left|v_{t}^{\prime}-z_{k}(0)\right|^{2}} \leqslant \frac{N^{1+\varepsilon}}{d\left(w, v_{t}^{\prime}\right)}
$$

and similarly for the terms involving $\left(v_{k}\right)_{t}$, which gives, as $v_{t}^{\prime}$ is close to $v_{t}$,

$$
\begin{equation*}
\left|\operatorname{Tr}\left(\frac{v+U_{t}}{v-U_{t}} \cdot \frac{w+U_{0}}{w-U_{0}}\right)\right| \leqslant \frac{N^{\varepsilon}\left(1+\left|v_{t}\right|\right)}{\eta_{v} d\left(w, v_{t}\right)} . \tag{4.31}
\end{equation*}
$$

The analogous estimate with $U_{t}$ replaced with $U_{0}$, and $v$ replaced with $v_{t}$ gives

$$
\begin{equation*}
\left|\operatorname{Tr}\left(\frac{v_{t}+U_{0}}{v_{t}-U_{0}} \cdot \frac{w+U_{0}}{w-U_{0}}\right)\right| \leqslant \frac{N^{\varepsilon}\left(1+\left|v_{t}\right|\right)}{\eta_{v_{t}} d\left(w, v_{t}\right)} \tag{4.32}
\end{equation*}
$$

This concludes the proof for $|v| \in\left[1,1+N^{\varepsilon} / N\right]$ and $|w|>1+N^{\varepsilon} / N$. The proof for cases $|v| \in\left[1-N^{\varepsilon} / N, 1\right]$, $|w|>1+N^{\varepsilon} / N$, etc follow from the same arguments.

## 5 LOOP EQUATIONS VIA STOCHASTIC ANALYSIS ON THE UNITARY GROUP

Integration by parts at the level of matrix process (and not at the level of the two-dimensional interacting particle systems constituted by its eigenvalues) has a particularly simple form in the case of the Dyson dynamics for the Gaussian Unitary Ensemble: $M(t)$ is distributed according to $e^{-t} M(0)+\sqrt{1-e^{-2 t}} G$ where $G$ is a GUE matrix of size $N$, whose density is proportional to $e^{-N \operatorname{Tr}\left(H^{2}\right)} D H$, and $G$ is independent of $M(0)$, the initial condition. Here, $D H$ is the Lebesgue measure on Hermitian matrices. The explicit potential in $e^{-N \operatorname{Tr}\left(H^{2}\right)} D H$ makes integration by parts tractable and this has been used for instance in [37, Lemma 4.1] in the context of mesoscopic equilibrium for linear statistics in the GUE Dyson's Brownian motion. However, this very nice structure does not extend to the unitary Brownian motion and we use instead stochastic calculus on this Lie group, in particular Girsanov theorem and exact solutions of some matrix SDEs that characterize Fréchet derivatives as an alternative (Section 5.1 below).

Such integration by parts often carry the name loop equations in random matrix theory [58, where they traditionally relate correlation functions of particle systems (see [46, 53, 88]), i.e. only eigenvalues in the context of random matrices. In our multitime and singular setting, the integration by parts formula (see Proposition 5.3 encodes information/correlations about eigenvalues but also eigenvectors.
5.1 Fréchet derivatives as explicit solutions of matrix SDEs. As in the previous sections, the Brownian motion $\left(U_{t}\right)$ on the unitary group is defined through 2.6), i.e.

$$
\mathrm{d} U_{t}=\sqrt{2} U_{t} \mathrm{~d} B_{t}-U_{t} \mathrm{~d} t
$$

where $\left(B_{t}\right)$ is a Brownian motion on the space of skew Hermitian matrices. Note that if $M$ is Hermitian and $N$ is skew-Hermitian, then $\langle M, N\rangle_{\mathfrak{R}}:=\operatorname{Re}\left(\operatorname{Tr}\left(\bar{M}^{T} N\right)\right)=0$.

Lemma 5.1 (Representation of UBM derivatives). Consider a predictable bounded and continuous skew Hermitian valued process $\left(f_{s}\right)$ and set $F_{t}:=\int_{0}^{t} f_{s} d s$. Then in $L^{2}(\mathbb{P})$ and almost surely,

$$
\begin{equation*}
D_{F} U_{t}:=\lim _{\varepsilon \rightarrow 0} \varepsilon^{-1}\left(U(B+\varepsilon F)_{t}-U(B)_{t}\right)=\sqrt{2}\left(\int_{0}^{t} U_{s} f_{s} U_{s}^{-1} \mathrm{~d} s\right) U_{t} \tag{5.1}
\end{equation*}
$$

Proof. First, we show that $V_{t}:=D_{F} U_{t}$ exists and solves, in integral form,

$$
V_{0}=0, \quad \mathrm{~d} V_{t}=\sqrt{2} V_{t} \mathrm{~d} B_{t}-V_{t} \mathrm{~d} t+\sqrt{2} U_{t} f_{t} \mathrm{~d} t
$$

Indeed, with $U^{(\varepsilon)}:=U(B+\varepsilon F)$ which solves

$$
\mathrm{d} U_{t}^{(\varepsilon)}=\sqrt{2} U_{t}^{(\varepsilon)} \mathrm{d}\left(B_{t}+\varepsilon F_{t}\right)-U_{t}^{(\varepsilon)} \mathrm{d} t=\sqrt{2} U_{t}^{(\varepsilon)} \mathrm{d} B_{t}-U_{t}^{(\varepsilon)} \mathrm{d} t+\varepsilon \sqrt{2} U_{t}^{(\varepsilon)} f_{t} \mathrm{~d} t
$$

and $V^{(\varepsilon)}:=\varepsilon^{-1}\left(U^{(\varepsilon)}-U\right)$, which satisfies $V_{0}^{(\varepsilon)}=0$ and

$$
\mathrm{d} V_{t}^{(\varepsilon)}=\sqrt{2} V_{t}^{(\varepsilon)} \mathrm{d} B_{t}-V_{t}^{(\varepsilon)} \mathrm{d} t+\sqrt{2}\left(U_{t}^{(\varepsilon)}-U_{t}\right) f_{t} \mathrm{~d} t+\sqrt{2} U_{t} f_{t} \mathrm{~d} t
$$

we obtain (by an $L^{2}$ estimate, Gronwall lemma and a continuity estimate), when $\varepsilon \downarrow 0$,

$$
\begin{equation*}
\mathrm{d} V_{t}=\sqrt{2} V_{t} \mathrm{~d} B_{t}-V_{t} \mathrm{~d} t+\sqrt{2} U_{t} f_{t} \mathrm{~d} t \tag{5.2}
\end{equation*}
$$

Most importantly, this equation has an explicit solution. Recalling that $\mathrm{d} U_{t}=\sqrt{2} U_{t} \mathrm{~d} B_{t}-U_{t} \mathrm{~d} t$, taking the conjugate transpose and using that $\mathrm{d} B_{t}$ is skew Hermitian, we have

$$
\mathrm{d} U_{t}^{-1}=-\sqrt{2} \mathrm{~d} B_{t} U_{t}^{-1}-U_{t}^{-1} \mathrm{~d} t
$$

An application of Itô's formula gives

$$
\begin{aligned}
\mathrm{d} V_{t} U_{t}^{-1} & =\left(\sqrt{2} V_{t} \mathrm{~d} B_{t}-V_{t} \mathrm{~d} t+\sqrt{2} U_{t} f_{t} \mathrm{~d} t\right) U_{t}^{-1}+V_{t}\left(-\sqrt{2} \mathrm{~d} B_{t} U_{t}^{-1}-U_{t}^{-1} \mathrm{~d} t\right)+2 V_{t} \mathrm{~d} B_{t}\left(-\mathrm{d} B_{t} U_{t}^{-1}\right) \\
& =\sqrt{2} U_{t} f_{t} U_{t}^{-1} \mathrm{~d} t
\end{aligned}
$$

where we used $\mathrm{d} B_{t} \mathrm{~d} B_{t}=-I$ to obtain the second equality, hence (5.1).
In the case of 1d Brownian motion, the Cameron-Martin's formula implies, for deterministic shift $\left(f_{t}\right)$

$$
\begin{aligned}
\mathbb{E}\left(\int_{0}^{1} f_{s} \mathrm{~d} B_{s} \cdot \Phi(B)\right) & =\left.\frac{\mathrm{d}}{\mathrm{~d} \varepsilon}\right|_{\varepsilon=0} \mathbb{E}\left(e^{\varepsilon \int_{0}^{1} f_{s} \mathrm{~d} B_{s}-\frac{\varepsilon^{2}}{2} \int f_{s}^{2} \mathrm{~d} s} \Phi(B)\right) \\
& =\left.\frac{\mathrm{d}}{\mathrm{~d} \varepsilon}\right|_{\mid \varepsilon=0} \int \Phi(B) e^{-\frac{1}{2} \int_{0}^{1} \mathrm{~d}\left(B_{s}-\varepsilon F_{s}\right) \mathrm{d}\left(B_{s}-\varepsilon F_{s}\right)} D B \\
& =\left.\frac{\mathrm{d}}{\mathrm{~d} \varepsilon}\right|_{\varepsilon=0} \mathbb{E}\left(\Phi\left(B+\varepsilon \int_{0} f_{s} \mathrm{~d} s\right)\right)=\mathbb{E}\left(D_{F} \Phi(B)\right)
\end{aligned}
$$

where $F=\int_{0}^{*} f_{s} \mathrm{~d} s$. The calculation above is formal but can be made rigorous ( $D B$ stands for the "Lebesgue measure" on the space of continuous paths, which does not exist). The generalization to the Brownian motion on skew Hermitian matrices is straightforward and we have,

$$
\begin{align*}
\int D_{F} \Phi(B) e^{-\frac{N}{2} \int_{0}^{1}\left\|\mathrm{~d} B_{s}\right\|_{\mathfrak{R}}^{2}} \mathcal{D} B & =-\int \Phi(B) D_{F}\left(e^{-\frac{N}{2} \int_{0}^{1}\left\|\mathrm{~d} B_{s}\right\|_{\mathfrak{\Re}}^{2}}\right) \mathcal{D} B \\
& =N \int \Phi(B) \int_{0}^{1}\left\langle f_{s}, \mathrm{~d} B_{s}\right\rangle_{\mathfrak{R}} e^{-\frac{N}{2} \int_{0}^{1}\left\|\mathrm{~d} B_{s}\right\|_{\mathfrak{R}}^{2} \mathcal{D} B} \tag{5.3}
\end{align*}
$$

where $\mathcal{D} B$ formally stands for the Lebesgue measure on skew Hermitian valued continuous paths. The necessity of $N=\sigma^{-2}$ in the potential $V(B)=\frac{1}{2 \sigma^{2}} \int_{0}^{1}\left\|\mathrm{~d} B_{s}\right\|_{\mathfrak{R}}^{2}$ can be checked by computing, with $F_{t}=\mathrm{i} t I$ and recalling (2.3),

$$
\sigma^{2} N t=\sigma^{2} \int_{0}^{t}\left\|F_{s}^{\prime}\right\|_{\mathfrak{R}}^{2} \mathrm{~d} s=\operatorname{Var} \int_{0}^{t}\left\langle\mathrm{~d} F_{s}, \mathrm{~d} B_{s}\right\rangle_{\mathfrak{R}}=\operatorname{Var} \int_{0}^{t} \operatorname{Re}\left(\operatorname{Tr}\left(\overline{\mathrm{I} I} \mathrm{~d} B_{s}\right)\right)=t
$$

The Girsanov theorem gives an extension to predictable processes.
Lemma 5.2 (Integration by parts for $\left(B_{t}\right)$ ). Consider a predictable bounded and continuous skew Hermitian valued process $\left(f_{s}\right)$ and set $F_{t}:=\int_{0}^{t} f_{s} \mathrm{~d}$ s. Suppose that $\Phi(B) \in L^{2}(\mathbb{P})$ is measurable with respect to $B$ and that $D_{F} \Phi(B)$ exists almost surely and in $L^{2}(\mathbb{P})$. Then,

$$
\mathbb{E}\left[D_{F} \Phi(B)\right]=N \mathbb{E}\left[\Phi(B) \int_{0}^{t}\left\langle f_{s}, \mathrm{~d} B_{s}\right\rangle_{\mathfrak{R}}\right]
$$

Proposition 5.3 (Integration by parts for $\left(U_{t}\right)$ ). With $F=\int_{0}^{*} f_{s} d s$ and $\Phi$ as above, we have

$$
\begin{equation*}
\mathbb{E}\left[\Phi(B) \int_{0}^{t}\left\langle f_{s}, \mathrm{~d} B_{s}\right\rangle_{\mathfrak{R}}\right]=\frac{1}{N} \mathbb{E}\left[D_{F} \Phi(B)\right], \quad \text { and } \quad D_{F} U_{t}=\sqrt{2}\left(\int_{0}^{t} U_{s} f_{s} U_{s}^{-1} \mathrm{~d} s\right) U_{t} \tag{5.4}
\end{equation*}
$$

Furthermore, for a matrix valued bounded and continuous predictable process ( $h_{s}$ ) (not necessarily skew Hermitian), and with a finite number of positive times $t_{j}$ and $\mathscr{C}^{1}$ functions $g_{j}$ on the unit circle, we have

$$
\mathbb{E}\left[\int_{0}^{t} \operatorname{Tr}\left(h_{s} \mathrm{~d} B_{s}\right) \prod_{i} e^{\operatorname{Tr} g_{i}\left(U_{t_{i}}\right)}\right]=-\frac{\sqrt{2}}{N} \sum_{j} \mathbb{E}\left[\operatorname{Tr}\left(g_{j}^{\prime}\left(U_{t_{j}}\right) U_{t_{j}} \int_{0}^{\min \left(t, t_{j}\right)} U_{s} h_{s} U_{s}^{-1} \mathrm{~d} s\right) \prod_{i} e^{\operatorname{Tr} g_{i}\left(U_{t_{i}}\right)}\right]
$$

Proof. The first statement is immediate from the lemmas 5.2 and 5.1 . For the second statement, we denote by $p_{S}\left(\right.$ resp. $\left.p_{H}\right)$ the projection on skew Hermitian (resp. Hermitian) matrices. Since these spaces are orthogonal for $\langle\cdot, \cdot\rangle_{\Re}$ and $d B$ is skew Hermitian,

$$
\operatorname{Re}(\operatorname{Tr}(h d B))=-\operatorname{Re}\left(\operatorname{Tr}\left(p_{S}(h)^{*} d B\right)\right)+\operatorname{Re} \operatorname{Tr}\left(p_{H}(h) d B\right)=-\left\langle p_{S}(h), d B\right\rangle_{\mathfrak{R}}+0
$$

Given that i : $M \mapsto \mathrm{i} M$ maps Hermitian matrices to skew Hermitian ones, and skew Hermitian matrices to Hermitian ones, we have

$$
\operatorname{Im}(\operatorname{Tr}(h d B))=\operatorname{Re}(-\mathrm{i} \operatorname{Tr}(h d B))=\operatorname{Re}\left(\operatorname{Tr}\left(-\mathrm{i} p_{S}(h) d B\right)\right)+\operatorname{Re}\left(\operatorname{Tr}\left(-\mathrm{i} p_{H}(h) d B\right)\right)=0+\left\langle\mathrm{i} p_{H}(h), d B\right\rangle_{\mathfrak{R}}
$$

We suppose that the product $\prod_{i}$ reduces to one term since the generalization is straightforward. We have

$$
\begin{aligned}
& \mathbb{E} \int_{0}^{t} \operatorname{Tr}\left(h_{s} \mathrm{~d} B_{s}\right) e^{\operatorname{Tr} g\left(U_{t}\right)}=\mathbb{E} \int_{0}^{t}\left\langle-p_{S}\left(h_{s}\right), \mathrm{d} B_{s}\right\rangle_{\mathfrak{R}} e^{\operatorname{Tr} g\left(U_{t}\right)}+\mathrm{i} \mathbb{E} \int_{0}^{t}\left\langle\mathrm{i} p_{H}\left(h_{s}\right), \mathrm{d} B_{s}\right\rangle_{\mathfrak{R}} e^{\operatorname{Tr} g\left(U_{t}\right)} \\
&= \frac{\sqrt{2}}{N} \mathbb{E} \operatorname{Tr}\left(g^{\prime}\left(U_{t}\right) U_{t} \int_{0}^{t} U_{s}\left(-p_{S}\left(h_{s}\right)\right) U_{s}^{-1} \mathrm{~d} s\right) e^{\operatorname{Tr} g\left(U_{t}\right)}+ \\
&+\frac{\sqrt{2}}{N} \mathrm{i} \mathbb{E} \operatorname{Tr}\left(g^{\prime}\left(U_{t}\right) U_{t} \int_{0}^{t} U_{s} \mathrm{i} p_{H}\left(h_{s}\right) U_{s}^{-1} \mathrm{~d} s\right) e^{\operatorname{Tr} g\left(U_{t}\right)} \\
&=-\frac{\sqrt{2}}{N} \mathbb{E} \operatorname{Tr}\left(g^{\prime}\left(U_{t}\right) U_{t} \int_{0}^{t} U_{s} h_{s} U_{s}^{-1} \mathrm{~d} s e^{\operatorname{Tr} g\left(U_{t}\right)}\right)
\end{aligned}
$$

In the second equality, we used 5.4 and the third equality follows from $-p_{S}(h)+\mathrm{i}^{2} p_{H}(h)=-h$.
5.2 Biased measures and error terms. In this section, we will use the following a priori estimate by Johansson as an input.

Lemma 5.4 ([59, Lemma 2.9]). If $f$ is real and $\|f\|_{\mathrm{H}}<\infty$, then

$$
\mathbb{E}\left[e^{\operatorname{Tr} f(U)}\right] \leqslant e^{N \hat{f}_{0}+\frac{1}{2}\|f\|_{\mathrm{H}}^{2}}
$$

An immediate consequence with $f$ chosen as $g$ below 4.16) is $\mathbb{P}(\boldsymbol{\theta}(s) \in \mathscr{G})>1-N^{-100}$, where $\mathscr{G}$ is defined at the beginning of Section 4.2.

From now on, we consider the subpolynomial scale

$$
\begin{equation*}
\iota=e^{-(\log N)^{2}}, \tag{5.5}
\end{equation*}
$$

and, $\ell^{h}$ be a regularization of $\log$ (around the singularity $h$ ) on scale $\iota$, which satisfies $\ell^{h}(z)=\log \left|z-e^{\mathrm{i} h}\right|$ if $\left|z-e^{\mathrm{i} h}\right|>2 \iota, \log |\iota|$ if $\left|z-e^{\mathrm{i} h}\right|<\iota,\left\|\left(\ell^{h}\right)^{(k)}\right\|_{\infty} \leqslant C_{k}|\log \iota| \iota^{-k}$ for $0 \leqslant k \leqslant 3$, and $\ell^{h} \geqslant \log \left|\cdot-e^{\mathrm{i} h}\right|$. Let

$$
\begin{equation*}
\mathcal{D}=\mathcal{D}_{J, \delta, C} \tag{5.6}
\end{equation*}
$$

denote the family of laws biased by $e^{\sum_{1 \leqslant j \leqslant J} \operatorname{Tr} f_{j}\left(U_{t_{j}}\right)}$ where $J$ is fixed, $f_{j}$ is either an element in $\mathscr{S}_{\delta, C}$ (see Definition 2.1) or $f_{j}=\lambda \ell^{h}$ for some $0 \leqslant \lambda \leqslant C$ and $h \in[0,2 \pi), t_{j} \in[0, C]$.

For any $\mathbb{P}$ in $\mathcal{D}$ we denote by $\mathbb{E}$ the expected value under $\mathbb{P}$, and the dependence in $\mathbf{f}, \mathbf{t}$ will sometimes be emphasized trough $\mathbb{P}_{\mathbf{f}}, \mathbb{E}_{\mathbf{f}}$.

We will also use the following a priori estimates without systematically referencing them, either when transferring an estimate for a biased measure from the Haar measure, or when using a truncation with an event with superpolynomially small probability: under the Haar measure there exists $C^{\prime}$ such that, uniformly in $f \in \mathscr{S}_{\delta, C}$ and $0 \leqslant \lambda \leqslant C$, we have

$$
\begin{equation*}
\mathbb{E}\left[e^{\operatorname{Tr} f-\mathbb{E}(\operatorname{Tr} f)}\right] \leqslant N^{C^{\prime}}, \mathbb{E}\left[e^{\lambda \operatorname{Tr} \ell^{\mathrm{h}}}\right] \leqslant N^{C^{\prime}} \tag{5.7}
\end{equation*}
$$

The first inequality follows from Lemma 5.4 and our assumption $\|f\|_{\mathrm{H}}^{2} \leqslant C \log N$ from $f \in \mathscr{S}_{\delta, C}$. The second follows from the inequality $\ell^{h}(z) \leqslant \log ^{(N)}\left(e^{\mathrm{i} h}-z\right)$ for some regularization $\log ^{(N)}$ of $\log |\cdot|$ on scale $1 / N$, and again Lemma 5.4 with a calculation giving $\left\|\log ^{(N)}\right\|_{\mathrm{H}}^{2} \leqslant C^{\prime} \log N$. For instance, a direct application with the consequence of Lemma 5.4. Hölder and Jensen inequalities imply $\mathbb{P}_{\mathbf{f}}(\boldsymbol{\theta}(s) \in \mathscr{G})>1-N^{-100}$.

For the following lemma, we recall the notation $d(v, w)=\max \left(|v-w|,\left|v-\frac{w}{|w|^{2}}\right|\right)$ and $R=(\log N)^{1+c}$.

Lemma 5.5 (Application of the rigidity). Uniformly in $\eta_{v} \in[0,1 / 2], \eta_{w} \in\left[\varphi^{10} / N, 1 / 2\right], \mathbb{P}_{\mathbf{f}} \in \mathcal{D},-R \leqslant s \leqslant$ C, we have

$$
\begin{equation*}
\frac{1}{N} \mathbb{E}_{\mathbf{f}}\left[\operatorname{Tr}\left(\frac{v+U_{s}}{v-U_{s}} \cdot \frac{U_{s}}{w-U_{s}}\right)\right]=a(v, w)+\mathrm{O}\left(\frac{\varphi^{10}(1+|v|)}{N d(v, w) \min \left(\eta_{v}, \eta_{w}\right)}\right) \tag{5.8}
\end{equation*}
$$

where

$$
a(v, w)=-\mathbb{1}_{|v|<1,|w|<1}+\frac{v+w}{v-w} \mathbb{1}_{|v|>1,|w|<1}+\frac{2 v}{w-v} \mathbb{1}_{|v|<1,|w|>1}
$$

In particular, we have

$$
\frac{1}{N} \mathbb{E}_{\mathbf{f}}\left[\operatorname{Tr}\left(\frac{v+U_{s}}{v-U_{s}} \cdot \frac{U_{s}}{\left(w-U_{s}\right)^{2}}\right)\right]=b(v, w)+\mathrm{O}\left(\frac{\varphi^{10}(1+|v|)}{N d(v, w) \eta_{w} \min \left(\eta_{v}, \eta_{w}\right)}\right)
$$

where

$$
\begin{equation*}
b(v, w)=\delta(v, w) \frac{2 v}{(w-v)^{2}}\left(\mathbb{1}_{|v|>1}-\mathbb{1}_{|v|<1}\right), \quad \delta(v, w)=\mathbb{1}_{|v|>1,|w|<1}+\mathbb{1}_{|v|<1,|w|>1} \tag{5.9}
\end{equation*}
$$

Proof. Note that

$$
\begin{equation*}
\frac{1}{2 \pi} \int_{0}^{2 \pi} \frac{v+e^{\mathrm{i} \theta}}{v-e^{\mathrm{i} \theta}} \frac{e^{\mathrm{i} \theta}}{w-e^{\mathrm{i} \theta}} \mathrm{~d} \theta=\frac{1}{2 \pi \mathrm{i}} \int \frac{v+z}{v-z} \frac{z}{w-z} \frac{\mathrm{~d} z}{z}=\frac{1}{2 \pi \mathrm{i}} \int \frac{v+z}{v-z} \frac{1}{w-z} \mathrm{~d} z=a(v, w) \tag{5.10}
\end{equation*}
$$

where the last equality follows from the residue theorem. Moreover, we clearly have

$$
\begin{align*}
\left\lvert\, \frac{1}{N} \sum_{j=1}^{N} \frac{v+e^{\mathrm{i} \gamma_{j}}}{v-e^{\mathrm{i} \gamma_{j}}}\right. & \left.\cdot \frac{e^{\mathrm{i} \gamma_{j}}}{w-e^{\mathrm{i} \gamma_{j}}}-\frac{1}{2 \pi} \int_{0}^{2 \pi} \frac{v+e^{\mathrm{i} \theta}}{v-e^{\mathrm{i} \theta}} \frac{e^{\mathrm{i} \theta}}{w-e^{\mathrm{i} \theta}} \mathrm{~d} \theta\left|\leqslant \frac{C}{N} \int\right| \partial_{\theta} \frac{v+e^{\mathrm{i} \theta}}{v-e^{\mathrm{i} \theta}} \frac{e^{\mathrm{i} \theta}}{w-e^{\mathrm{i} \theta}} \right\rvert\, \mathrm{d} \theta \\
& \leqslant \frac{C}{N} \int\left(\frac{1+|v|}{\left|\left(v-e^{\mathrm{i} \theta}\right)\left(w-e^{\mathrm{i} \theta}\right)^{2}\right|}+\frac{1+|v|}{\left|\left(v-e^{\mathrm{i} \theta}\right)^{2}\left(w-e^{\mathrm{i} \theta}\right)\right|}\right) \mathrm{d} \theta \leqslant \frac{C(1+|v|)}{N d(v, w) \min \left(\eta_{v}, \eta_{w}\right)}, \tag{5.11}
\end{align*}
$$

and similarly, for $\boldsymbol{\theta}(s) \in \mathscr{G}$,

$$
\begin{equation*}
\left|\frac{1}{N} \sum_{j=1}^{N} \frac{v+e^{\mathrm{i} \theta_{j}(s)}}{v-e^{\mathrm{i} \theta_{j}(s)}} \cdot \frac{e^{\mathrm{i} \theta_{j}(s)}}{w-e^{\mathrm{i} \theta_{j}(s)}}-\frac{1}{N} \sum_{j=1}^{N} \frac{v+e^{\mathrm{i} \gamma_{j}}}{v-e^{\mathrm{i} \gamma_{j}}} \cdot \frac{e^{\mathrm{i} \gamma_{j}}}{w-e^{\mathrm{i} \gamma_{j}}}\right| \leqslant \frac{C \varphi^{7}(1+|v|)}{N d(v, w) \min \left(\eta_{v}, \eta_{w}\right)} \tag{5.12}
\end{equation*}
$$

From $\mathbb{P}(\boldsymbol{\theta}(s) \in \mathscr{G})>1-N^{-100}$, the trivial estimate $\operatorname{Tr}\left(\frac{v+U_{s}}{v-U_{s}} \cdot \frac{U_{s}}{w-U_{s}}\right) \leqslant N^{5} / \eta_{v}$ when $\eta_{w}>\varphi^{10} / N$, and equations 5.10, 5.11, (5.12), the result 5.8 follows. Then $\partial_{w}$ gives the second estimates by the Cauchy formula. The proof for $\mathbb{P}_{\mathbf{f}}$ is the same because rigidity holds also for these measures: $\mathbb{P}_{\mathbf{f}}(\boldsymbol{\theta}(s) \in \mathscr{G})>$ $1-N^{-100}$, as explained before the statement of the lemma.

Lemma 5.6 (Application of the full rank projection estimate). Let $\varepsilon \in(0,1)$ be arbitrary. Uniformly in $\eta_{v} \in[0,1 / 2], \eta_{w} \in\left[N^{\varepsilon} / N, 1 / 2\right], \mathbb{P}_{\mathbf{f}} \in \mathcal{D},-R \leqslant s \leqslant C$ and $\max (0, s) \leqslant t \leqslant C$, we have

$$
\frac{1}{N} \mathbb{E}_{\mathbf{f}}\left[\operatorname{Tr}\left(\frac{v+U_{t}}{v-U_{t}} \frac{w U_{s}}{\left(w-U_{s}\right)^{2}}\right)\right]=w b\left(v_{t-s}, w\right)+\mathrm{O}\left(\frac{N^{\varepsilon}\left(1+\left|v_{t-s}\right|\right)}{N \sqrt{\eta_{v} \min \left(\eta_{v}, \eta_{w}\right)} \eta_{w} d\left(v_{t-s}, w\right)}\right)
$$

Proof. First, we explain why the result holds for $\mathbb{P}$ the Haar measure. On the event $E$ of Proposition 4.5 . we have trivially

$$
\left|\frac{1}{N} \mathbb{E}\left[\left.\mathbb{1}_{E} \operatorname{Tr}\left(\frac{v+U_{t}}{v-U_{t}} \frac{w U_{s}}{\left(w-U_{s}\right)^{2}}\right)-\mathbb{1}_{E} \operatorname{Tr}\left(\frac{v_{t-s}+U_{s}}{v_{t-s}-U_{s}} \frac{w U_{s}}{\left(w-U_{s}\right)^{2}}\right) \right\rvert\, \boldsymbol{\theta}(s) \in \mathscr{G}\right]\right|=\mathrm{O}\left(\frac{N^{\varepsilon}\left(1+\left|v_{t-s}\right|\right)}{N d\left(v_{t-s}, w\right) \eta_{w} \sqrt{\eta_{v} \min \left(\eta_{v}, \eta_{w}\right)}}\right) .
$$

Furthermore, the same result holds without $\mathbb{1}_{E}$ nor the conditioning, by using as in the previous lemma a truncation on $\{\boldsymbol{\theta}(s) \in \mathscr{G}\}$ with a priori estimates (e.g. $N^{6} / \eta_{v}$ because $\left.\eta_{w}>1 / N\right), \mathbb{P}(\boldsymbol{\theta}(s) \in \mathscr{G})>1-N^{-100}$ and the isotropic law from Proposition 4.5 on $\mathbb{P}(E \mid \boldsymbol{\theta}(s) \in \mathscr{G})$. Then, by Lemma 5.5.

$$
\mathbb{E}\left[\frac{1}{N} \operatorname{Tr}\left(\frac{v_{t-s}+U_{s}}{v_{t-s}-U_{s}} \frac{w U_{s}}{\left(w-U_{s}\right)^{2}}\right)\right]=w b\left(v_{t-s}, w\right)+\mathrm{O}\left(\frac{N^{\varepsilon}\left(1+\left|v_{t-s}\right|\right)}{N d\left(v_{t-s}, w\right) \eta_{w} \min \left(\eta_{v}, \eta_{w}\right)}\right)
$$

and this completes the proof for the equilibrium measure.
For $\mathbb{P}_{\mathbf{f}} \in \mathcal{D}$, as the statement of Lemma 5.5 covers this case, only the first part of the proof needs to be modified. On the event $E$, the same estimates hold and the changes concern $\mathbb{P}_{\mathbf{f}}(\boldsymbol{\theta}(s) \in \mathscr{G})$ and $\mathbb{P}_{\mathbf{f}}(E \mid \boldsymbol{\theta}(s) \in \mathscr{G})$, but these estimates can be obtained as explained before the statement of the lemma.
5.3 Asymptotics of the loop equations. The following Lemma will be the main tool for the "gluing" operation mentioned in subsection 1.2 , It relies on the integration by parts formula from Proposition 5.3 , the consequences of the local law and rigidity estimates for biased measures Lemma 5.6, Lemma 5.8 below to express our result in terms of Fourier coefficients, and various smoothings.
Lemma 5.7. Let $\delta \in(0,1)$ be arbitrary. Consider $h \in \mathscr{S}_{\delta, C}$ (see Definition 2.1) and, in this lemma, $\mathbb{P}_{\mathbf{f}}$ denotes the law of the unitary Brownian motion at equilibrium biased by $e^{\sum_{1 \leqslant j \leqslant J} \operatorname{tr} f_{j}\left(U_{t_{j}}\right)}$ where $J$ is fixed, $f_{j}$ is either an element in $\mathscr{S}_{\delta, C}$ or $f_{j}(z)=\lambda \log \left|z-e^{\mathrm{i} h}\right|$ for some $0 \leqslant \lambda \leqslant C$ and $h \in[0,2 \pi)$, and $t_{j} \in[0, C]$.

For $0 \leqslant r \leqslant C$, for any small $\xi>0$

$$
\begin{equation*}
\mathbb{E}_{\mathbf{f}}\left(\operatorname{Tr} h\left(U_{r}\right)\right)-N f h=\sum_{1 \leqslant j \leqslant J} \sum_{k \in \mathbb{Z}} e^{-|k|\left|t_{j}-r\right|}|k|\left(\hat{f}_{j}\right)_{-k} \hat{h}_{k}+\mathrm{O}_{\delta, C, J}\left(N^{-\delta+\xi}\right) \tag{5.13}
\end{equation*}
$$

Proof. First step: tiny smoothing of logarithms. Recall the subpolynomial scale (5.5) and the regularized log denoted by $\ell^{h}$. Denote $\mathbf{f}^{\iota}$ the collection of functions and times coinciding with $\mathbf{f}$, except that any $\log \left|z-e^{\mathrm{i} h}\right|$ is replaced by $\ell^{h}(z)$. We first prove that we only need to prove the lemma for $\mathbb{E}_{\mathbf{f}^{\iota}}$ instead of $\mathbb{E}_{\mathbf{f}}$.

Note that, using Cauchy-Schwarz and $\log \leqslant \ell^{h}$, we have

$$
\mathbb{E}\left[\left(e^{\lambda \operatorname{Tr} \ell^{h}}-e^{\lambda \operatorname{Tr} \log }\right)^{2}\right] \leqslant \mathbb{E}\left[\left(e^{\lambda \operatorname{Tr} \ell^{h}}-e^{\lambda \operatorname{Tr} \log }\right)^{2} \mathbb{1}_{\exists\left|z_{i}-e^{\mathrm{i} h}\right|<\iota}\right] \leqslant \mathbb{E}\left[e^{4 \lambda \operatorname{Tr} \ell^{h}}\right]^{1 / 2} \mathbb{P}\left[\exists\left|z_{i}-e^{\mathrm{i} h}\right|<\iota\right]^{1 / 2} \leqslant \iota^{1 / 10}
$$

where we have used a polynomial bound on $\mathbb{E}\left[e^{4 \lambda \operatorname{Tr} \ell^{h}}\right]$ thanks to 5.7 and a union bound. The above estimate easily implies (by Cauchy-Schwarz) that

$$
\mathbb{E}_{\mathbf{f}}\left(\operatorname{Tr} h\left(U_{r}\right)\right)=\mathbb{E}_{\mathbf{f}^{\iota}}\left(\operatorname{Tr} h\left(U_{r}\right)\right)+\mathrm{O}\left(\iota^{1 / 100}\right)
$$

We have reduced the Lemma to proving that we have

$$
\begin{equation*}
\mathbb{E}_{\mathbf{f}^{\iota}}\left(\operatorname{Tr} h\left(U_{r}\right)\right)-N f h=\sum_{1 \leqslant j \leqslant N} \sum_{k \in \mathbb{Z}} e^{-|k|\left|t_{j}-r\right|}|k|\left(\hat{f}_{j}\right)_{-k} \hat{h}_{k}+\mathrm{O}_{\delta, C, J}\left(N^{-\delta+\xi}\right) . \tag{5.14}
\end{equation*}
$$

Second step: smoothing of $h$. We have $h \in \mathscr{S}_{\delta, C}$, so it can be written $h=\sum h_{i}$ where the sum is over $\log N$ terms, and $h_{i} \in \mathrm{~A}_{\alpha, C}$ for some $\alpha \geqslant \delta$. By linearity in $h$ of the estimate (5.13), without loss of generality we assume $h$ coincides with one such $h_{i}$ and we omit the subscript in the following. For this $h=h_{i} \in \mathrm{~A}_{\alpha, C}$, we denote $\varepsilon=N^{-1+\alpha}$.

From the Helffer Sjőstrand formula 2.23 we have (remember we denote $s(z)=\mathbb{1}_{|z|>1}-\mathbb{1}_{|z|<1}$ )

$$
\mathbb{E}_{\mathbf{f}^{\iota}}\left(\operatorname{Tr} h\left(U_{r}\right)\right)-N f h=-\frac{N}{2 \pi} \int_{\mathbb{C}} \partial_{\bar{w}} \tilde{h}(w) \cdot \mathbb{E}_{\mathbf{f}^{\iota}}\left[m_{r}(w)-s(w)\right] \frac{\mathrm{d} m(w)}{w}
$$

For further error estimates it will be pertinent to choose $c=\varepsilon$ for $\chi_{c}$ in the definition of the above $\tilde{h}$. We first show that the contribution from $\eta_{w}<x:=N^{-1+\xi}$ in the above integral is negligible. From (2.19), we have

$$
\left|\partial_{\bar{w}} \tilde{h}\right| \leqslant\left(|h|+\eta_{w}|h|^{\prime}\right) \cdot\left|\chi^{\prime}\right|+\left|h^{\prime \prime}\right| \eta_{w} \cdot|\chi| .
$$

Together with 4.16 this gives

$$
N \int_{\eta_{w}<x}\left|h^{\prime \prime}\right| \eta_{w} \cdot \frac{\varphi^{5}}{N \eta_{w}} \mathrm{~d} m(w) \leqslant \varphi^{5} \frac{x}{\varepsilon} \leqslant N^{-\delta+\xi} .
$$

Third step: injecting the integration by parts formula. Remember that from 4.5 we have

$$
m_{r}(w)=m_{-R}\left(w_{r+R}\right)+\int_{-R}^{r} \frac{2 \sqrt{2}}{N} \operatorname{Tr}\left(\frac{w_{r-s} U_{s}}{\left(w_{r-s}-U_{s}\right)^{2}} \mathrm{~d} B(s)\right)+\int_{-R}^{r}\left(m_{s}\left(w_{r-s}\right)-s(w)\right) w_{r-s} \partial_{z} m_{s}\left(w_{r-s}\right) \mathrm{d} s
$$

This implies, with the $\mathrm{O}\left(N^{-\delta+\xi}\right)$ error term from Step 2,

$$
\left.\begin{array}{rl}
\mathbb{E}_{\mathbf{f}^{\iota}}\left(\operatorname{Tr} h\left(U_{r}\right)\right)-N f & h
\end{array}=-\frac{N}{2 \pi} \int_{\eta_{w}>x} \partial_{\bar{w}} \tilde{h}(w) \cdot \mathbb{E}_{\mathbf{f}^{\iota}}\left[m_{-R}\left(w_{r+R}\right)-s(w)\right] \frac{\mathrm{d} m(w)}{w}+\mathrm{O}\left(N^{-\delta+\xi}\right),{ }^{r} \mathbb{E}_{\mathbf{f}^{\iota}}\left[\left(m_{s}\left(w_{r-s}\right)-s(w)\right) w_{r-s} \partial_{z} m_{s}\left(w_{r-s}\right)\right] \mathrm{d} s \frac{\mathrm{~d} m(w)}{w}\right)
$$

The first term 5.15 above is easily shown to be subpolynomial in $N$ because $w_{r+R}$ is either superpolynomially large or close to 0 , and (5.16) is also negligible by the rigidity estimates under the biased measure.

More importantly, to evaluate (5.17) we rely on the integration by parts formula from Proposition 5.3 .

$$
\begin{equation*}
\mathbb{E}_{\mathbf{f}^{\iota}}\left[\int_{-R}^{r} \operatorname{Tr}\left(\frac{w_{r-s} U_{s}}{\left(w_{r-s}-U_{s}\right)^{2}} \mathrm{~d} B(s)\right)\right]=-\frac{1}{N} \sum_{j} \mathbb{E}_{\mathbf{f}^{\iota}}\left[\operatorname{Tr}\left(f_{j}^{\iota \prime}\left(U_{t_{j}}\right) V_{r}^{t_{j}}(w)\right)\right] \tag{5.18}
\end{equation*}
$$

where, for $1 \leqslant j \leqslant N$,

$$
V_{r}^{t_{j}}=\sqrt{2} \int_{-R}^{t_{j} \wedge r} U_{s} \frac{w_{r-s} U_{s}}{\left(w_{r-s}-U_{s}\right)^{2}} U_{s}^{-1} \cdot U_{u}=\sqrt{2} \int_{-R}^{t_{j} \wedge r} \frac{w_{r-s} U_{s}}{\left(w_{r-s}-U_{s}\right)^{2}} \mathrm{~d} s \cdot U_{t_{j}}
$$

Remember that thanks to the first step, we can write any $f_{j}^{\iota}=g_{s}+g_{r}$ where $g_{s}$ is possibly 0 or of type $g_{s}=\lambda \ell^{h}(0 \leqslant \lambda \leqslant C)$ and $g_{r}$ is regular in the sense $g_{r} \in \mathscr{S}_{\delta, C}$. We therefore can write $f_{j}^{\iota}=\sum g_{m}$ where the sum is over $\mathrm{O}(\Delta)$ terms and $g_{m}$ supported on an arc of radius $1 /\left(N e^{m}\right),-\log N \leqslant m \leqslant \Delta$, $\sum_{k=0}^{3}\left(N e^{m}\right)^{k}\left\|g_{m}^{(k)}\right\|_{\infty} \leqslant C \log N$. The number of considered $g_{m}$ 's is finite thanks to the initial smoothing.

We therefore can now assume without loss of generality that $f_{j}^{\iota}$ coincides with such a $g_{m}$, and we define $\tilde{\varepsilon}=e^{-m} / N$. From $2.23\left(|z|=1\right.$ in $z f_{j}^{\iota^{\prime}}(z)$ below) we can write

$$
\begin{aligned}
\left.\frac{1}{N} \mathbb{E}_{\mathbf{f}^{\iota}}\left[\operatorname{Tr}\left(f_{j}^{\iota \prime}\left(U_{t_{j}}\right) V_{r}^{t_{j}}(w)\right)\right)\right] & =\frac{\sqrt{2}}{N} \mathbb{E}_{\mathbf{f}^{\iota}}\left[\operatorname{Tr}\left(U_{t_{j}} f_{j}^{\iota^{\prime}}\left(U_{t_{j}}\right) \int_{-R}^{t_{j} \wedge r} \frac{w_{r-s} U_{s}}{\left(w_{r-s}-U_{s}\right)^{2}} \mathrm{~d} s\right)\right] \\
& =-\frac{\sqrt{2}}{2 \pi N} \int_{\mathbb{C}} \int_{-R}^{t_{j} \wedge r} \mathbb{E}_{\mathbf{f}_{\iota}} \operatorname{Tr}\left(\frac{v+U_{t_{j}}}{v-U_{t_{j}}} \frac{w_{r-s} U_{s}}{\left(w_{r-s}-U_{s}\right)^{2}}\right) \mathrm{d} s \partial_{\bar{v}} z f_{j}^{\iota^{\prime}}(v) \frac{\mathrm{d} m(v)}{v}
\end{aligned}
$$

where for further error estimates it will be pertinent to choose $c=\tilde{\varepsilon}$ for $\chi_{c}$ in the definition of the above $\widetilde{z f_{j}^{\prime \prime}}$.
Fourth step: injecting resolvent estimates. By Lemma 5.6, the above $s$-integral is

$$
\begin{aligned}
& \frac{1}{N} \int_{-R}^{r \wedge t_{j}} \mathbb{E}_{\mathbf{f}_{\iota}} \operatorname{Tr}\left(\frac{v+U_{t_{j}}}{v-U_{t_{j}}} \frac{w_{r-s} U_{s}}{\left(w_{r-s}-U_{s}\right)^{2}}\right) \mathrm{d} s \\
& \quad=\int_{-R}^{r \wedge t_{j}} w_{r-s} b\left(v_{t_{j}-s}, w_{r-s}\right) d s+\mathrm{O}\left(\int_{-R}^{r \wedge t_{j}} \frac{N^{\xi}\left(1+\left|v_{t_{j}-s}\right|\right)}{\left.N d\left(v_{t_{j}-s}, w_{r-s}\right) \eta_{w_{r-s}} \sqrt{\eta_{v_{t_{j}-s} \min \left(\eta_{\left.v_{t_{j}-s}, \eta_{w_{r-s}}\right)}\right.}} \mathrm{d} s\right)}\right.
\end{aligned}
$$

The first $\int_{-R}^{r \wedge t_{j}}$ above can be calculated: by using $\frac{d}{d t} \frac{v_{t}}{w_{t}-v_{t}}=\left(\mathbb{1}_{|v|>1,|w|<1}-\mathbb{1}_{|v|<1,|w|>1}\right) \frac{2 v_{t} w_{t}}{\left(w_{t}-v_{t}\right)^{2}}$, we obtain $\int_{-R}^{r \wedge t_{j}} w_{r-s} b\left(v_{t_{j}-s}, w_{r-s}\right) d s=\delta(v, w)\left(\frac{v_{t_{j}-r \wedge t_{j}}}{v_{t_{j}-r \wedge t_{j}}-w_{r-r \wedge t_{j}}}-\frac{v_{t_{j}+R}}{v_{t_{j}+R}-w_{r+R}}\right)$. For the error term, we can estimate

$$
\begin{gathered}
\int_{-R}^{r \wedge t_{j}} \frac{\left(1+\left|v_{t_{j}-s}\right|\right) \mathrm{d} s}{N d\left(v_{t_{j}-s}, w_{r-s}\right) \eta_{w_{r-s}} \sqrt{\eta_{v_{t_{j}-s}} \min \left(\eta_{v_{t_{j}-s}}, \eta_{w_{r-s}}\right)}} \leqslant \int_{0}^{\infty} \frac{\left(1+\left|v_{t_{j}-r \wedge t_{j}+s}\right|\right) \mathrm{d} s}{N d\left(v_{t_{j}-r \wedge t_{j}+s}, w_{s}\right) \eta_{w_{s}} \sqrt{\eta_{v_{t_{j}-r \wedge t_{j}+s}} \min \left(\eta_{v_{t_{j}-r \wedge t_{j}+s}}, \eta_{w_{s}}\right)}} \\
\leqslant \frac{\left(1+\left|v_{t_{j}-r \wedge t_{j}}\right|\right)\left(1+\mid \log \eta_{v_{t_{j}-r \wedge t_{j}}}\right) \mid}{N \sqrt{\eta_{w} \max \left(\eta_{v_{t_{j}-r \wedge t_{j}}} \eta_{w}\right)} d\left(v_{t_{j}-r \wedge t_{j}}, w\right)} \leqslant \frac{\left(1+\left|v_{t_{j}-r \wedge t_{j}}\right|\right)\left(1+\left|\log \eta_{v_{t_{j}-r \wedge t_{j}}}\right|\right)}{N \eta_{w} d\left(v_{t_{j}-r \wedge t_{j}}, w\right)} .
\end{gathered}
$$

We have therefore proved,

$$
\begin{align*}
\frac{1}{N} \mathbb{E}_{\mathbf{f}^{\iota}}\left[\operatorname{Tr}\left(f_{j}^{\iota \prime}\left(U_{t_{j}}\right) V_{r}^{t_{j}}(w)\right)\right]= & -\frac{\sqrt{2}}{2 \pi} \int_{\mathbb{C}} \delta(v, w)\left(\frac{v_{t_{j}-r \wedge t_{j}}}{v_{t_{j}-r \wedge t_{j}}-w_{r-r \wedge t_{j}}}-\frac{v_{t_{j}+R}}{v_{t_{j}+R}-w_{r+R}}\right) \partial_{\bar{v}} \widetilde{z f_{j}^{\iota \prime}}(v) \frac{\mathrm{d} m(v)}{v} \\
& +\int_{\mathbb{C}} \frac{\left(1+\left|v_{t_{j}-r \wedge t_{j}}\right|\right)\left(1+\left|\log \eta_{v_{t_{j}-r \wedge t_{j}}}\right|\right)}{N \eta_{w} d\left(v_{t_{j}-r \wedge t_{j}}, w\right)}\left|\widetilde{\partial_{\bar{v}}} \widetilde{z f_{j}^{\prime \prime}}(v)\right| \frac{\mathrm{d} m(v)}{|v|} \cdot \mathrm{O}\left(N^{\xi}\right) . \tag{5.19}
\end{align*}
$$

Thanks to the the formulas 5.18 , 5.19, equation 5.15 becomes

$$
\begin{equation*}
\mathbb{E}_{\mathbf{f}^{\iota}}\left(\operatorname{Tr} h\left(U_{r}\right)\right)=N f h+\sum_{j} A_{j}^{x}+\sum_{j} \mathcal{E}_{j} \cdot \mathrm{O}\left(N^{\xi}\right) \tag{5.20}
\end{equation*}
$$

where

$$
\begin{aligned}
A_{j}^{x} & =\frac{-4}{(2 \pi)^{2}} \int_{\mathbb{C} \times\left\{\eta_{w}>x\right\}} \delta(v, w)\left[\left(\frac{v_{t_{j}-r \wedge t_{j}}}{v_{t_{j}-r \wedge t_{j}}-w_{r-r \wedge t_{j}}}-\frac{v_{t_{j}+R}}{v_{t_{j}+R}-w_{r+R}}\right) \partial_{\bar{w}} \tilde{h}(w) \partial_{\bar{v}} \widetilde{v f_{j}^{\iota^{\prime}}}(v) \frac{\mathrm{d} m(v)}{v} \frac{\mathrm{~d} m(w)}{w}\right. \\
\mathcal{E}_{j} & \left.=\int_{\mathbb{C} \times\left\{\eta_{w}>x\right\}} \frac{\left(1+\left|v_{t_{j}-r \wedge t_{j}}\right|\right)\left(1+\mid \log \eta_{v_{t_{j}-r \wedge t_{j}}}\right) \mid}{N \eta_{w} d\left(v_{t_{j}-r \wedge t_{j}}, w\right)}\left|\partial_{\bar{w}} \tilde{h}(w)\right| \cdot \right\rvert\, \partial_{\bar{v}} \widetilde{z f_{j}^{\iota^{\prime}}}(v) \mathrm{d} m(v) \mathrm{d} m(w)
\end{aligned}
$$

By using Lemma 5.8 and the identities $\frac{v_{t}}{v_{t}-w_{r}}=\frac{v_{(t+r) / 2}}{v_{(t+r) / 2}-w_{(t+r) / 2}}$ when $\delta(v, w)=1$ and $\left(t_{j}+r-2 r \wedge t_{j}\right) / 2=$ $\left|t_{j}-r\right| / 2$, we note that the term $A_{j}^{0}$ has the explicit expression

$$
\begin{equation*}
A_{j}^{0}=\sum_{k \in \mathbb{Z}} e^{-|k|\left|t_{j}-r\right|}|k|\left(\hat{f}_{j}^{\iota}\right)_{-k} \hat{h}_{k}=\sum_{k \in \mathbb{Z}} e^{-|k|\left|t_{j}-r\right|}|k|\left(\hat{f}_{j}\right)_{-k} \hat{h}_{k}+\mathrm{O}\left(\iota^{1 / 100}\right) \tag{5.21}
\end{equation*}
$$

Then, recalling $x=N^{-1+\xi}$, the difference $\left|A_{j}^{x}-A_{j}^{0}\right|$ is $\mathrm{O}\left(N^{-1+\xi}\right)$ by a volume estimate.
We now estimate the error term $\mathcal{E}_{j}$, reminding from 2.19) that

$$
\left|\partial_{\bar{w}} \tilde{h}\right| \leqslant\left(|h|+\eta_{w}|h|^{\prime}\right) \cdot\left|\chi^{\prime}\right|+\left|h^{\prime \prime}\right| \eta_{w} \cdot|\chi| .
$$

As $\chi$ is supported on $\exp ([-2 \varepsilon, 2 \varepsilon])$, constant equal to 1 on $\exp ([-\varepsilon, \varepsilon])$, we obtain (for some points $a, b$ on the unit circle) that $\left|\partial_{\bar{w}} \tilde{h}\right| \leqslant \eta_{w} \varepsilon^{-2} \mathbb{1}_{|w-a|<4 \varepsilon}$, and similarly $\left|\partial_{\bar{v}} \widetilde{z f_{j}^{\prime \prime}}\right| \leqslant \eta_{v} \tilde{\varepsilon}^{-3} \mathbb{1}_{|v-b|<4 \tilde{\varepsilon}}$. Assume first that $\varepsilon>\tilde{\varepsilon}$. The error term $\mathcal{E}_{1}$ is maximized when $a=b$ and $t=r$, so it is bounded from above by

$$
\begin{gathered}
\int_{\mathbb{C}^{2}} \frac{1+\left|\log \eta_{v}\right|}{N \eta_{w} d(v, w)}\left|\partial_{\bar{w}} \tilde{h}(w)\right| \cdot\left|\partial_{\bar{v}} \widetilde{z f_{j}^{\iota^{\prime}}}(v)\right| \mathrm{d} m(v) \mathrm{d} m(w) \leqslant \int_{\substack{|w|-1 \in[0, \varepsilon], \arg w \in[0, \varepsilon] \\
|v|-1 \in[-\tilde{\varepsilon}, 0], \arg v \in[0, \tilde{\varepsilon}]}}\left(\varepsilon^{-2} \eta_{w}\right)\left(\tilde{\varepsilon}^{-3} \eta_{v}\right) \frac{\mathrm{d} m(v) \mathrm{d} m(w)}{N \eta_{w}|v-w|} \\
\leqslant \frac{\log N}{N \varepsilon^{2}} \int_{\substack{\theta \in[0, \varepsilon] \\
|v|-1 \in[-\tilde{\varepsilon}, 0], \arg v \in[0, \tilde{\varepsilon}]}}\left(\tilde{\varepsilon}^{-3} \eta_{v}\right) \mathrm{d} m(v) \mathrm{d} \theta \leqslant \frac{\log N}{N \varepsilon} \int_{v-1 \in[-\tilde{\varepsilon}, 0]+\mathrm{i}[0, \varepsilon]} \tilde{\varepsilon}^{-3} \eta_{v} \mathrm{~d} m(v) \leqslant \frac{\log N}{N \varepsilon} .
\end{gathered}
$$

If $\varepsilon \leqslant \tilde{\varepsilon}$, the above reasoning actually gives the same estimate, of order $(N \varepsilon)^{-1}$; it could probably be improved to $(N \tilde{\varepsilon})^{-1}$ but we won't need it. Summing the above estimate over the terms in the decomposition $h$ and $f_{j}^{\iota}$ gives

$$
\mathcal{E}_{1}=\mathrm{O}\left(N^{-\delta+\xi}\right)
$$

Combining (5.20) and the estimates for the terms $A_{j}^{x}$ and $\mathcal{E}_{j}$ concludes the proof of 5.14 , and the lemma.
Lemma 5.8. For $t>0$, under the same assumptions as Lemma 5.7 for the functions $g$ (in place of a $f_{j}$ ) and $h$, we have

$$
\frac{1}{(2 \pi)^{2}} \iint_{|w|>1,|v|<1}\left(\frac{v_{t}}{w_{t}-v_{t}}-\frac{v}{w-v}\right) \partial_{\bar{v}} \widetilde{z g^{\prime}}(v) \partial_{\bar{w}} \tilde{h}(w) \frac{\mathrm{d} m(v)}{v} \frac{\mathrm{~d} m(w)}{w}=-\frac{1}{4} \sum_{k \geqslant 1}\left(1-e^{-2 k t}\right) k \hat{g}_{-k} \hat{h}_{k}
$$

Furthermore, integrating over $|w|<1,|v|>1$ gives the same formula with $\hat{h}_{-k} \hat{g}_{k}$ instead of $\hat{g}_{-k} \hat{h}_{k}$.
Proof. First, we note that $\frac{v_{t}}{w_{t}-v_{t}}-\frac{v}{w-v}=\frac{w_{t}}{w_{t}-v_{t}}-\frac{w}{w-v}=\frac{1}{2}\left(\frac{w_{t}+v_{t}}{w_{t}-v_{t}}-\frac{w+v}{w-v}\right)$, so to calculate the above integral in $w$, we use when $|v|<1$,

$$
\begin{aligned}
\frac{1}{2} \int_{|w|>1}\left(\frac{w_{t}+v_{t}}{w_{t}-v_{t}}-\frac{w+v}{w-v}\right) \partial_{\bar{w}} \tilde{h}(w) \frac{\mathrm{d} m(w)}{w} & =\frac{1}{2} \int_{|w|>1}\left(\frac{w+v e^{-2 t}}{w-v e^{-2 t}}-\frac{w+v}{w-v}\right) \partial_{\bar{w}} \tilde{h}(w) \frac{\mathrm{d} m(w)}{w} \\
& =\frac{1}{4} \int_{0}^{2 \pi} h\left(e^{\mathrm{i} \theta}\right)\left(\frac{v e^{-2 t}+e^{\mathrm{i} \theta}}{v e^{-2 t}-e^{\mathrm{i} \theta}}-\frac{v+e^{\mathrm{i} \theta}}{v-e^{\mathrm{i} \theta}}\right) \mathrm{d} \theta
\end{aligned}
$$

where we used 2.21. Integrating in $v$ requires calculating

$$
\frac{1}{4} \int_{|v|<1} \partial_{\bar{v}} \widetilde{z g^{\prime}}(v)\left(\frac{v+e^{\mathrm{i} \theta+2 t}}{v-e^{\mathrm{i} \theta+2 t}}-\frac{v+e^{\mathrm{i} \theta}}{v-e^{\mathrm{i} \theta}}\right) \frac{\mathrm{d} m(v)}{v}=\frac{1}{8} \int_{0}^{2 \pi} e^{\mathrm{i} \phi} g^{\prime}\left(e^{\mathrm{i} \phi}\right)\left(\frac{e^{\mathrm{i} \phi}+e^{\mathrm{i} \theta+2 t}}{e^{\mathrm{i} \phi}-e^{\mathrm{i} \theta+2 t}}-\frac{e^{\mathrm{i} \phi}+e^{\mathrm{i} \theta}}{e^{\mathrm{i} \phi}-e^{\mathrm{i} \theta}}\right) \mathrm{d} \phi
$$

Finally, with $T g(z)=z g^{\prime}(z)$, we calculate

$$
\begin{aligned}
-\frac{1}{8} \int T g\left(e^{\mathrm{i} \phi}\right) h\left(e^{\mathrm{i} \theta}\right)\left(\frac{1+e^{\mathrm{i}(\phi-\theta)-2 t}}{1-e^{\mathrm{i}(\phi-\theta)-2 t}}-\frac{1+e^{\mathrm{i}(\phi-\theta)}}{1-e^{\mathrm{i}(\phi-\theta)}}\right) \mathrm{d} \theta \mathrm{~d} \phi & =-\frac{1}{4} \sum_{k \geqslant 1}\left(e^{-2 k t}-1\right) \int T g\left(e^{\mathrm{i} \phi}\right) h\left(e^{\mathrm{i} \theta}\right) e^{\mathrm{i} k(\phi-\theta)} \mathrm{d} \theta \mathrm{~d} \phi \\
& =-\frac{(2 \pi)^{2}}{4} \sum_{k \geqslant 1}\left(e^{-2 k t}-1\right) \widehat{T g}{ }_{-k} \hat{h}_{k},
\end{aligned}
$$

hence the result follows from $\widehat{T g}_{-k}=-k \hat{g}_{-k}$. Replacing the domain of integration by $|w|<1,|v|>1$, we pick a minus sign due to the fractional term and another one when we replace $\left(\widehat{v g^{\prime}(v)}\right)_{-k}$ by $\hat{h}_{-k}$.

## 6 Proof of THE THEOREMS

6.1 Theorem 1.2. The local decoupling (Section 3) and the asymptotics of the loop equations (Section 55) allow to prove Theorem 1.2 through the following surgery, with the Selberg integration formula as a base point.

Lemma 6.1 (One singularity). For any $\theta \in[0,2 \pi]$, as $N \rightarrow \infty$,

$$
\mathbb{E}\left(\left|\operatorname{det}\left(U_{0}-e^{\mathrm{i} \theta}\right)\right|^{\gamma}\right)=N^{\frac{\gamma^{2}}{4}} \frac{\mathrm{G}\left(1+\frac{\gamma}{2}\right)^{2}}{\mathrm{G}(1+\gamma)}(1+\mathrm{O}(1 / N))
$$

Proof. We use the exact expression of the expected value of powers of the characteristic polynomials derived by Keating and Snaith [68, (6)] (and based on Weyl's and Selberg's formulas) to calculate

$$
\begin{aligned}
\lim _{N \rightarrow \infty} N^{-\frac{\gamma^{2}}{4}} \mathbb{E}\left|\operatorname{det}\left(U_{0}-e^{\mathrm{i} \theta}\right)\right|^{\gamma} & =\lim _{N \rightarrow \infty} N^{-\frac{\gamma^{2}}{4}} \prod_{j=1}^{N} \frac{\Gamma(j) \Gamma(j+\gamma)}{\Gamma\left(j+\frac{\gamma}{2}\right)^{2}} \\
& =\lim _{N \rightarrow \infty} N^{-\frac{\gamma^{2}}{4}} \frac{\mathrm{G}(N+1) \mathrm{G}(N+1+\gamma)}{\mathrm{G}\left(N+1+\frac{\gamma}{2}\right)^{2}} \frac{\mathrm{G}\left(1+\frac{\gamma}{2}\right)^{2}}{\mathrm{G}(1) \mathrm{G}(1+\gamma)}=\frac{\mathrm{G}\left(1+\frac{\gamma}{2}\right)^{2}}{\mathrm{G}(1+\gamma)}
\end{aligned}
$$

The second equality followed from the relation $\mathrm{G}(z+1)=\Gamma(z) \mathrm{G}(z)$ and the last one from $\mathrm{G}(1)=1$ and the following asymptotics (see, e.g., Barnes' original paper on the G function [9, page 269]):

$$
\log \mathrm{G}(z+1)=\frac{z^{2}}{2} \log z-\frac{3 z^{2}}{4}+\frac{z}{2} \log 2 \pi-\frac{1}{12} \log z+C+\mathrm{O}_{z \rightarrow \infty}\left(\frac{1}{z}\right)
$$

Indeed, it gives $\log \mathrm{G}(N+\gamma+1)=\log \mathrm{G}(N+1)+\gamma N \log N-\gamma N+\frac{\gamma^{2}}{2} \log N+\mathrm{O}\left(\frac{1}{N}\right)$ hence only the quadratic term in $\gamma$ contributes to $\log \frac{\mathrm{G}(N+1) \mathrm{G}(N+1+\gamma)}{\mathrm{G}\left(N+1+\frac{\gamma}{2}\right)^{2}}=\frac{\gamma^{2}}{4} \log N+\mathrm{O}\left(\frac{1}{N}\right)$.

In what follows, we use the notations $f_{t}$ to denote the pair $(f, t)$ where $f$ is a function and $t$ a real number and we set for any $s, t$,

$$
\begin{equation*}
\mathscr{C}\left(f_{s}, g_{t}\right):=\lim _{N \rightarrow \infty} \operatorname{Cov}\left(\operatorname{Tr} f\left(U_{s}\right), \operatorname{Tr} g\left(U_{t}\right)\right)=\sum_{k \in \mathbb{Z}}|k| \hat{f}_{k} \hat{g}_{-k} e^{-|k||t-s|}=\left(f, P_{|t-s|} g\right)_{\mathrm{H}} \tag{6.1}
\end{equation*}
$$

We extend it to finite linear combination, $\mathscr{C}\left(f_{s}, \lambda g_{t}+h_{r}\right)=\lambda \mathscr{C}\left(f_{s}, g_{t}\right)+\mathscr{C}\left(f_{s}, h_{r}\right)$ and set $\mathscr{C}\left(f_{s}\right):=\mathscr{C}\left(f_{s}, f_{s}\right)$, which does not depend on $s$. With $L^{x}:=\gamma_{x} \log \left|e^{\mathrm{i} x}-\cdot\right|$ and $t>0$, we record the following identities, obtained by using $\widehat{\left(f_{x}\right)_{k}}=-\frac{e^{-\mathrm{i} k x}}{2|k|}$ where $f_{x}(\theta)=\log \left|e^{\mathrm{i} x}-e^{\mathrm{i} \theta}\right|$,

$$
\begin{align*}
& \mathscr{C}\left(f_{0}, L_{t}^{x}\right)=\gamma_{x} \sum_{k \neq 0}|k| \hat{f}_{k} \cdot\left(-\frac{e^{\mathrm{i} k x}}{2|k|} 1_{k \neq 0}\right) e^{-|k||t|}=-\frac{\gamma_{x}}{2}\left(\mathrm{P}_{t} f\left(e^{\mathrm{i} x}\right)-f f\right)=-\frac{\gamma_{x}}{2}\left(\mathrm{P}_{t}-\mathrm{P}_{\infty}\right) f\left(e^{\mathrm{i} x}\right),  \tag{6.2}\\
& \mathscr{C}\left(L_{0}^{x}, L_{t}^{y}\right)=\gamma_{x} \gamma_{y} \sum_{k \neq 0}|k| \frac{e^{\mathrm{i} k x}}{2|k|} \frac{e^{-\mathrm{i} k y}}{2|k|} e^{-|k| t}=\frac{\gamma_{x} \gamma_{y}}{2} \sum_{k \geqslant 1} \frac{\cos (k(x-y))}{k} e^{-k t}=\gamma_{x} \gamma_{y} \mathrm{P}_{t} C(x-y) . \tag{6.3}
\end{align*}
$$

where the function $C$ is defined in 2.17 .

Lemma 6.2 (One singularity \& one smooth function). For $\kappa>0, t \geqslant 0$ and $f \in \mathscr{S}_{\delta, C}$ for $\delta \in(0,1)$,

$$
\mathbb{E}\left(\left|\operatorname{det}\left(U_{t}-e^{\mathrm{i} x}\right)\right|^{\gamma_{x}} e^{\operatorname{Tr} f\left(U_{0}\right)}\right)=N^{\frac{\gamma_{x}^{2}}{4}} \frac{\mathrm{G}\left(1+\frac{\gamma_{x}}{2}\right)^{2}}{\mathrm{G}\left(1+\gamma_{x}\right)} e^{\mathscr{C}\left(f_{0}, L_{t}^{x}\right)} e^{N f f_{0}+\frac{1}{2} \mathscr{C}\left(f_{0}\right)}\left(1+\mathrm{O}\left(N^{-\delta+\kappa}\right)\right)
$$

Proof. Without loss of generality, we suppose $f f=0$, and we apply Lemma 5.7

$$
\begin{aligned}
\mathbb{E}\left(\left|\operatorname{det}\left(U_{t}-e^{\mathrm{i} x}\right)\right|^{\gamma_{x}} e^{\operatorname{Tr} f\left(U_{0}\right)}\right) & =\mathbb{E}\left(\left|\operatorname{det}\left(U_{t}-e^{\mathrm{i} x}\right)\right|^{\gamma_{x}}\right) \exp \left(\int_{0}^{1} \frac{\mathrm{~d}}{\mathrm{~d} \nu} \log \mathbb{E}\left(e^{\operatorname{Tr} L^{x}\left(U_{t}\right)+\nu \operatorname{Tr} f\left(U_{0}\right)}\right) \mathrm{d} \nu\right) \\
& =N^{\frac{\gamma_{x}^{2}}{4}} \frac{\mathrm{G}\left(1+\frac{\gamma_{x}}{2}\right)^{2}}{\mathrm{G}\left(1+\gamma_{x}\right)} \exp \left(\int_{0}^{1} \mathscr{C}\left(f_{0}, L_{t}^{x}+\nu f_{0}\right) \mathrm{d} \nu\right)\left(1+\mathrm{O}\left(N^{-\delta+\kappa}\right)\right)
\end{aligned}
$$

and the result follows from $\left.\int_{0}^{1} \mathscr{C}\left(f_{0}, L_{t}^{x}+\nu f_{0}\right) d \nu=\mathscr{C}\left(f_{0}, L_{t}^{x}\right)+\frac{1}{2} \mathscr{C}\left(f_{0}, f_{0}\right)\right)$.
Now, we introduce the notation $L^{x, \lambda}$ for the centered truncated singularity on scale $\lambda / N$ (as in (3.13), i.e., $\left.L^{E_{i}, \lambda}(x)=\log f_{i}(x)-f \log f_{i}\right)$ and set $L^{x}=L^{x, \lambda}+L^{x, r}$. An application of the lemma above gives, since $-\mathscr{C}\left(L_{t}^{x, r}, L_{t}^{x}\right)+\frac{1}{2} \mathscr{C}\left(L_{t}^{x, r}\right)=-\frac{1}{2}\left(\mathscr{C}\left(L_{t}^{x}\right)-\mathscr{C}\left(L_{t}^{x, \lambda}\right)\right)$, we have

$$
\begin{equation*}
\mathbb{E}\left(e^{\operatorname{Tr} L^{x, \lambda}\left(U_{t}\right)}\right)=N^{\frac{\gamma_{x}^{2}}{4}} \frac{\mathrm{G}\left(1+\frac{\gamma_{x}}{2}\right)^{2}}{\mathrm{G}\left(1+\gamma_{x}\right)} e^{-\frac{1}{2}\left(\mathscr{C}\left(L_{t}^{x}\right)-\mathscr{C}\left(L_{t}^{x, \lambda}\right)\right)}\left(1+\mathrm{O}\left(N^{-\delta+\kappa}\right)\right) . \tag{6.4}
\end{equation*}
$$

We are now ready to prove our main theorem.
Proof of Theorem 1.2. We denote by $\mathcal{L}=\mathcal{L}_{\text {loc }}+\mathcal{L}_{\text {reg }}$ the decomposition of the sum of log-singularities into localized singularities and non-singular parts, and by $\mathcal{S}$ the sum of smooth functions. Below, $\varepsilon$ may be smaller from line to line. We suppose without loss of generality that the smooth functions are centered. Our starting point is the identity

$$
\mathbb{E}\left(e^{\mathcal{S}+\mathcal{L}}\right)=\mathbb{E}\left(e^{\mathcal{L}_{\mathrm{loc}}}\right) \exp \left(\int_{0}^{1} \frac{\mathrm{~d}}{\mathrm{~d} \nu} \log \mathbb{E}\left(e^{\nu\left(\mathcal{S}+\mathcal{L}_{\mathrm{reg}}\right)+\mathcal{L}_{\mathrm{loc}}}\right) \mathrm{d} \nu\right)
$$

Then, by Proposition 3.4 denoting $d=N \min _{i \neq j}\left(\left|\left(e^{\mathrm{i} x_{i}}, t_{i}\right)-\left(e^{\mathrm{i} x_{j}}, t_{j}\right)\right| \geqslant N^{\delta}\right.$ we have

$$
\begin{aligned}
\mathbb{E}\left(e^{\mathcal{L}_{\mathrm{loc}}}\right) & =\prod_{j} \mathbb{E}\left(e^{\operatorname{Tr} L^{x_{j}, \lambda}\left(U_{t_{j}}\right)}\right) \cdot\left(1+\mathrm{O}\left(N^{-\varepsilon}\right)\right) \\
& =\prod_{x} N^{\frac{\gamma_{x}^{2}}{4}} \frac{\mathrm{G}\left(1+\frac{\gamma_{x}}{2}\right)^{2}}{\mathrm{G}\left(1+\gamma_{x}\right)} e^{-\frac{1}{2}\left(\mathscr{C}\left(L_{t}^{x}\right)-\mathscr{C}\left(L_{t}^{x, \lambda}\right)\right)}\left(1+\mathrm{O}\left(N^{-\varepsilon}\right)\right)
\end{aligned}
$$

where the second equality follows from (6.4). Furthermore, by Lemma 5.7.

$$
\begin{aligned}
\int_{0}^{1} \frac{\mathrm{~d}}{\mathrm{~d} \nu} \log \mathbb{E}\left(e^{\left.\nu\left(\mathcal{S}+\mathcal{L}_{\mathrm{reg}}\right)+\mathcal{L}_{\mathrm{loc}}\right) \mathrm{d} \nu}\right. & \left.=\int_{0}^{1} \mathscr{C}\left(\mathcal{S}+\mathcal{L}_{\mathrm{reg}}, \nu\left(\mathcal{S}+\mathcal{L}_{\mathrm{reg}}\right)+\mathcal{L}_{\mathrm{loc}}\right) \mathrm{d} \nu+\mathrm{O}\left(\mathrm{~N}^{\kappa} / \lambda\right)\right) \\
& \left.=\mathscr{C}\left(\mathcal{S}+\mathcal{L}_{\mathrm{reg}}, \mathcal{L}_{\mathrm{loc}}\right)+\frac{1}{2} \mathscr{C}\left(\mathcal{S}+\mathcal{L}_{\mathrm{reg}}\right)+\mathrm{O}\left(N^{\kappa} / \lambda\right)\right) \\
& \left.=\frac{1}{2} \mathscr{C}(\mathcal{S})+\mathscr{C}(\mathcal{S}, \mathcal{L})+\frac{1}{2} \mathscr{C}(\mathcal{L})-\frac{1}{2} \mathscr{C}\left(\mathcal{L}_{\mathrm{loc}}\right)+\mathrm{O}\left(N^{\kappa} / \lambda\right)\right)
\end{aligned}
$$

Altogether, we obtain

$$
\mathbb{E}\left(e^{\mathcal{S}+\mathcal{L}}\right)=e^{\frac{1}{2} \mathscr{C}(\mathcal{S})} e^{\mathscr{C}(\mathcal{S}, \mathcal{L})} \prod_{\mathscr{A}} N^{\frac{\gamma_{z}^{2}}{4}} \frac{\mathrm{G}\left(1+\frac{\gamma_{z}}{2}\right)^{2}}{\mathrm{G}\left(1+\gamma_{z}\right)} e^{\frac{1}{2} \mathscr{C}(\mathcal{L})-\frac{1}{2} \sum_{x \in \mathscr{A}} \mathscr{C}\left(L_{t}^{x}\right)} e^{-\frac{1}{2} \mathscr{C}\left(\mathcal{L}_{\mathrm{loc}}\right)+\frac{1}{2} \sum_{x \in \mathscr{A}} \mathscr{C}\left(L_{t}^{x, \lambda}\right)}\left(1+\mathrm{O}\left(N^{-\varepsilon}\right)\right)
$$

To conclude, we use (6.1), 6.2, 6.3 combined with (2.16), and we prove that for any pair of distinct singularities,

$$
\mathscr{C}\left(L_{0}^{x, \lambda}, L_{t}^{y, \lambda}\right)=\mathrm{O}\left(N^{-\delta+\kappa}\right)
$$

Indeed, since $\langle f, g\rangle_{L^{2}\left(\frac{\lambda}{2 \pi}\right)}=\sum_{k} \hat{f}_{k} \hat{g}_{-k}, \frac{d}{d t}\left\langle\mathrm{P}_{t} f, g\right\rangle_{L^{2}\left(\frac{\lambda}{2 \pi}\right)}=-\left\langle\mathrm{P}_{t} f, g\right\rangle_{\mathrm{H}}$. Note that

$$
\int_{\mathbb{U}} \mathrm{P}_{t} f(w) g(w) \lambda(d w)=\int_{\mathbb{U}^{2}} g(w) \frac{1}{2 \pi} \operatorname{Re}\left(\frac{w^{\prime}+w e^{-t}}{w^{\prime}-w e^{-t}}\right) f\left(w^{\prime}\right) \lambda(\mathrm{d} w) \lambda\left(\mathrm{d} w^{\prime}\right)
$$

and $\frac{\mathrm{d}}{\mathrm{d} t} \frac{w^{\prime}+w e^{-t}}{w^{\prime}-w e^{-t}}=\frac{\mathrm{d}}{\mathrm{d} t} \frac{2 w^{\prime}}{w^{\prime}-w e^{-t}}=-2 \frac{w^{\prime} w e^{-t}}{\left(w^{\prime}-w e^{-t}\right)^{2}}$, so, we bound from above

$$
\begin{equation*}
\left|\mathscr{C}\left(L_{0}^{x, \lambda}, L_{t}^{y, \lambda}\right)\right| \leqslant C(\lambda / N)^{2} \cdot \log (\lambda / N)^{2} \max \left(1, \min \left(t^{-2},\left|e^{\mathrm{i} x}-e^{\mathrm{i} y}\right|^{-2}\right)\right) \leqslant N^{\kappa} \lambda^{2} / d^{2} \tag{6.5}
\end{equation*}
$$

by using $\sup _{\left|w^{\prime}-e^{\mathrm{i} x}\right|<\lambda / N,\left|w-e^{\mathrm{i} y}\right|<\lambda / N} \frac{1}{\left|w^{\prime}-w e^{-t}\right|^{2}} \leqslant C \max \left(1, \min \left(t^{-2},\left|e^{\mathrm{i} x}-e^{\mathrm{i} y}\right|^{-2}\right)\right)$. This concludes the proof.
6.2 Theorem 1.1. In this proof, we prefer simplicity/brevity to generality and present only the details for the $L^{2}$ phase (namely $\gamma \in(0,2)$ ). The parameter $\gamma$ is fixed throughout the proof so we drop it from the notation. In the Gaussian setup, 13 gave an elementary approach for the convergence of GMC measures for a natural class of approximations, including the $L^{1}$ phase (corresponding here to $\gamma \in[2,2 \sqrt{2}$ ) using barrier estimates. In random matrix theory, the works [71] and 79 , Section 3] explain how barrier estimates and in particular the convergence in the $L^{1}$ phase follow from Theorem 1.2

Let $\mu_{N}^{(\varepsilon)}$ be the $2 d$ GMC measure with parameter $\gamma$ associated to the field $h_{N}^{(\varepsilon)}(t, \cdot):=\mathrm{P}_{\varepsilon} h_{N}(t, \cdot)$. For any continuous function $f$ on $[0,1] \times \mathbb{U}$, the $L^{2}$ norm of $\int_{[0,1] \times \mathbb{U}} f\left(\mathrm{~d} \mu_{N}^{(\varepsilon)}-\mathrm{d} \mu_{N}\right)$ vanishes when taking $N \rightarrow \infty$ and then $\varepsilon \rightarrow 0$ (details on this are given below). Furthermore, $h_{N}^{(\varepsilon)}$ converges to a smooth Gaussian field $h^{(\varepsilon)}$ whose covariance kernel is given by $\mathbb{E}\left(\mathrm{P}_{\varepsilon} h(s, x) \mathrm{P}_{\varepsilon} h(t, y)\right)=\frac{1}{2} \sum_{k \geqslant 1} \frac{\cos (k(x-y))}{k} e^{-|k||t-s|} e^{-2 \varepsilon|k|}=$ $\mathrm{P}_{2 \varepsilon+|t-s|} C(x-y)$ where $C(x-y)=\mathbb{E}\left(h_{0}(x) h_{0}(y)\right)$. Finally, the GMC $e^{\gamma h^{(\varepsilon)}}$ converges to the GMC $e^{\gamma h}$ by 89, Theorems 3, 25]. Altogether, this concludes the proof of Theorem 1.1 for $\gamma \in(0,2)$.

Now, we provide some details on the $L^{2}$ estimates. Three terms arise:

$$
\frac{\mathbb{E}\left(e^{\gamma h_{N}^{(\varepsilon)}(s, x)} e^{\gamma h_{N}^{(\varepsilon)}(t, y)}\right)}{\mathbb{E}\left(e^{\gamma h_{N}^{(\varepsilon)}(s, x)}\right) \mathbb{E}\left(e^{\gamma h_{N}^{(\varepsilon)}(t, y)}\right)}, \quad \frac{\mathbb{E}\left(e^{\gamma h_{N}^{(\varepsilon)}(s, x)} e^{\gamma h_{N}(t, y)}\right)}{\mathbb{E}\left(e^{\gamma h_{N}^{(\varepsilon)}(s, x)}\right) \mathbb{E}\left(e^{\gamma h_{N}(t, y)}\right)}, \quad \text { and } \quad \frac{\mathbb{E}\left(e^{\gamma h_{N}(s, x)} e^{\gamma h_{N}(t, y)}\right)}{\mathbb{E}\left(e^{\gamma h_{N}(s, x)}\right) \mathbb{E}\left(e^{\gamma h_{N}(t, y)}\right)}
$$

Set $f_{x}=\log \left|e^{\mathrm{i} \cdot}-e^{\mathrm{i} x}\right|$ and $f_{x}^{(\varepsilon)}=\mathrm{P}_{\varepsilon} f_{x}$. By applying Theorem 1.2 (with one singularity or one smooth function), we obtain the asymptotics of the normalizing constants: $\lim _{N \rightarrow \infty} \mathbb{E}\left(e^{\gamma h_{N}^{(\varepsilon)}(s, x)}\right)=e^{\frac{\gamma^{2}}{2}\left\|f_{x}^{(\varepsilon)}\right\|_{\mathrm{H}}^{2}}$ and $\lim _{N \rightarrow \infty} N^{-\frac{\gamma^{2}}{4}} \mathbb{E}\left(e^{\gamma h_{N}(s, x)}\right)=\frac{\mathrm{G}(1+\gamma / 2)^{2}}{\mathrm{G}(1+\gamma)}$. Still with Theorem 1.2 (and this time only pairwise terms contribute), we obtain the 2-point asymptotics

$$
\begin{aligned}
& \lim _{N \rightarrow \infty} \frac{\mathbb{E}\left(e^{\gamma h_{N}^{(\varepsilon)}(s, x)} e^{\gamma h_{N}^{(\varepsilon)}(t, y)}\right)}{\mathbb{E}\left(e^{\gamma h_{N}^{(\varepsilon)}(s, x)}\right) \mathbb{E}\left(e^{\gamma h_{N}^{(\varepsilon)}(t, y)}\right)}=e^{\frac{\gamma^{2}}{2} \times 2\left(f_{x}^{(\varepsilon)}, \mathrm{P}_{|t-s|} f_{y}^{(\varepsilon)}\right)_{H}}=e^{\gamma^{2} \mathrm{P}_{|t-s|+2 \varepsilon} C(x-y)} \\
& \lim _{N \rightarrow \infty} \frac{\mathbb{E}\left(e^{\gamma h_{N}^{(\varepsilon)}(s, x)} e^{\gamma h_{N}(t, y)}\right)}{\mathbb{E}\left(e^{\gamma h_{N}^{(\varepsilon)}(s, x)}\right) \mathbb{E}\left(e^{\gamma h_{N}(t, y)}\right)}=e^{-\left.\frac{\gamma^{2}}{2} \mathrm{P}_{|t-s|}\right|_{x} ^{(\varepsilon)}\left(e^{i y}\right)}=e^{\gamma^{2} \mathrm{P}_{|t-s|+\varepsilon} C(x-y)} \\
& \lim _{N \rightarrow \infty} \frac{\mathbb{E}\left(e^{\gamma h_{N}(s, x)} e^{\gamma h_{N}(t, y)}\right)}{\mathbb{E}\left(e^{\gamma h_{N}(s, x)}\right) \mathbb{E}\left(e^{\gamma h_{N}(t, y)}\right)}=\left(e^{2 \mathrm{P}_{|t-s|} C(x-y)}\right)^{\frac{\gamma^{2}}{4} \times 2}
\end{aligned}
$$

where we used 2.16) for the last equality. With $f_{x}(y)=-\sum_{k \geqslant 1} \frac{1}{2 k}\left(e^{\mathrm{i} k(x-y)}+e^{-\mathrm{i} k(x-y)}\right)$, we find $\left(f_{x}, f_{y}\right)_{\mathrm{H}}=$ $\frac{1}{2} \sum_{k \geqslant 1} \frac{\cos (k(x-y))}{k}$ and $\left(f_{x}^{(\varepsilon)}, \mathrm{P}_{|t-s|} f_{y}^{(\varepsilon)}\right)_{H}=\frac{1}{2} \sum_{k \geqslant 1} \frac{\cos (k(x-y))}{k} e^{-|t-s| k} e^{-2 \varepsilon k}$.

For small mesoscopic contributions, we use the Cauchy-Schwarz inequality and obtain (again from 1.3) but with a $2 \gamma$ singularity) as $N \rightarrow \infty$,

$$
\frac{\mathbb{E}\left(e^{2 \gamma h_{M}^{(\varepsilon)}(0,0)}\right)}{\mathbb{E}\left(e^{\gamma h_{M}^{(\varepsilon)}(0,0)}\right)^{2}} \asymp \frac{N^{\frac{(2 \gamma)^{2}}{4}}}{N^{\frac{\gamma^{2}}{2} \times 2}}=N^{\frac{\gamma^{2}}{2}}
$$

so, for $\varepsilon$ small enough, the contributions to the $L^{2}$ norm of the points $z, w \in[0,1] \times \mathbb{U}$ with $|z-w|<N^{-1+\varepsilon}$ vanishes. Therefore, $\lim _{\varepsilon \rightarrow 0} \lim _{N \rightarrow \infty} \mathbb{E}\left(\int_{[0,1] \times \mathbb{U}} f\left(\mathrm{~d} \mu_{N}^{(\varepsilon)}-\mathrm{d} \mu_{N}\right)\right)^{2}$ is equal to

$$
\lim _{\varepsilon \rightarrow 0} \int_{([0,1] \times \mathbb{U})^{2}} f(s, x) f(t, y)\left(e^{\gamma^{2} \mathrm{P}_{|t-s|+2 \varepsilon} C(x-y)}-2 e^{\gamma^{2} \mathrm{P}_{|t-s|+\varepsilon} C(x-y)}+e^{\gamma^{2} \mathrm{P}_{|t-s|} C(x-y)}\right)=0
$$

hence the aforementioned $L^{2}$ estimate.
This paper is focused on the measures as in our framework the limiting $2 d$ LQG measure is connected with many topics of $2 d$ random geometry, as outlined above. However, Theorem 1.2 has other direct consequences which we list below.

Remark 6.3. Theorem 1.2 implies directly the pointwise convergence of $h_{N}(z)=\log \left|\operatorname{det}\left(e^{\mathrm{i} \theta}-U_{t}\right)\right|$ (where $z=t+\mathrm{i} \theta)$ to a Gaussian logarithmically-correlated field: $\left(\frac{1}{2} \log N\right)^{-1 / 2}\left(h_{N}(z), h_{N}\left(z^{\prime}\right)\right)$ converges in distribution to $\left(\mathscr{N}_{z}, \mathscr{N}_{z^{\prime}}\right)$ where these standard Gaussians have asymptotic covariance $-\log \left|z-z^{\prime}\right| / \log N$ for $\left|z-z^{\prime}\right|$ on mesoscopic scale.

Remark 6.4. For $\Omega$ any fixed compact set in $\mathbb{R} \times \mathbb{U}$ with non-empty interior, yet another corollary is the asymptotics

$$
(\log N)^{-1} \max _{z \in \Omega}\left|h_{N}(z)\right| \rightarrow \sqrt{2}
$$

in probability, i.e. the space-time analogue of the main result in 4]. For fixed time this maximum is known up to second order [82, tightness [25] and distribution [83]; it is an interesting question whether Theorem 1.2 can help to approach this precision on $\Omega$, or if our $2 d$ framework is useful to study fine properties of the maximum of the $1 d$ restriction of the field.

In the same vein as equation (1.4), Theorem 1.2 (more precisely its natural analogue for $\operatorname{Im} \log$ ) also captures the maximum deviation of the eigenvalues along trajectories. Indeed, ordering the initial eigenangles at equilibrium $0 \leqslant \theta_{1}(0) \leqslant \ldots \leqslant \theta_{N}(0) \leqslant 2 \pi$, and denoting $\gamma_{k}=\frac{2 \pi k}{N}, t=N^{-1+\rho}(0 \leqslant \rho \leqslant 1)$, we have (in probability),

$$
\begin{equation*}
\frac{N}{\log N} \max _{0 \leqslant s \leqslant t, 1 \leqslant k \leqslant N}\left|\theta_{k}(s)-\gamma_{k}\right| \rightarrow 2 \sqrt{1+\rho} \tag{6.6}
\end{equation*}
$$

Finally, we note two interesting questions related to our results. First, in the context of random tilings, (6.6) is the analogue of the maximal deviation of the height function from the hydrodynamic limit. Asymptotics of this maximum and convergence to LQG are not known in this context. Moreover, instead of considering an infinite volume surface, the unitary Brownian bridge with same (Haar-distributed) starting $(t=0)$ and ending point $(t=1)$ provides a natural framework in Random Matrix Theory to generate the LQG measure on a finite volume surface without boundary, the torus $\mathbb{R} / 2 \pi \mathbb{Z} \times \mathbb{R} / \mathbb{Z}$. The general surgery and some methods developed in this work may apply to these problems.

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