

Def: $(x,y) \in \mathbb{R} \times \mathbb{R}$ are ρ -correlated normal variables (or, more precisely, (x,y) is distributed like the bivariate normal $N\left(\begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 & \rho \\ \rho & 1 \end{pmatrix}\right)$ if x is chosen according to $N(0,1)$ and then $y = \rho \cdot x + \sqrt{1-\rho^2} \cdot z$ where z is an independent $N(0,1)$ r.v.

Remark: • y 's marginal is $N(0, \rho^2) + N(0, 1-\rho^2) = N(0,1)$.

In fact, the definition is symmetric

• $E[xy] = E[\rho x^2] + E[\sqrt{1-\rho^2} x \cdot z] = \rho \cdot E[x^2] = \rho$.

Def: $g, h \in \mathbb{R}^n$ are n -dimensional ρ -correlated Gaussians if each coordinate (g_i, h_i) is chosen independently from a ρ -correlated 1-dim Gaussians $N\left(\begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 & \rho \\ \rho & 1 \end{pmatrix}\right)$.

Observation: $E[\langle g, h \rangle] = \sum_{i=1}^n E[g_i h_i] = \rho \cdot n$, and in fact $\langle g, h \rangle$ is concentrated around ρn .

Therefore, the angle between g and h is concentrated on $\arccos \rho$.



Noise Stability

Def: For a function $f: \{0,1\}^n \rightarrow \mathbb{R}$ define its noise stability by $S_\rho(f) = \langle f, T_\rho f \rangle = \sum_{s,t} \rho^{|s|} f(s)^2$.

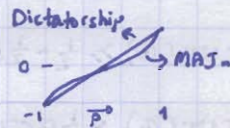
For ± 1 functions, this is $1 - 2 \Pr_{x \sim y} [f(x) \neq f(y)]$ (i.e., $y \sim x + \mu_{\frac{1-\rho}{2}}$).

Remark: $NS_S(f) = \frac{1}{2}(1 - S_{1-2S}(f))$.

Examples: • Constant function $\pm 1: 1$.

• Dictatorship: $S_\rho = \rho$.

Prop: $S_\rho(\text{MAJ}_n) = \frac{2}{\pi} \arcsin \rho + O(\frac{1}{n})$.



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Proof sketch:

$$S_\rho(\text{MAJ}_n) = 1 - 2 \cdot \Pr_{x \sim y} \left[\text{sign}\left(\frac{\sum (-1)^{x_i}}{\sqrt{n}}\right) \neq \text{sign}\left(\frac{\sum (-1)^{y_i}}{\sqrt{n}}\right) \right]$$

By CLT, $\frac{\sum (-1)^{x_i}}{\sqrt{n}}$ is roughly like $N(0,1)$. (In fact, we need more precise estimate known as the Berry-Esseen theorem). Using a generalization of the CLT to

multidimensional distributions, we get that the joint distribution of $\left(\frac{\sum (-1)^{x_i}}{\sqrt{n}}, \frac{\sum (-1)^{y_i}}{\sqrt{n}}\right)$

$\in \mathbb{R} \times \mathbb{R}$ is asymptotically $N\left(\begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 & \rho \\ \rho & 1 \end{pmatrix}\right)$. So, our goal is to compute

$1 - 2 \cdot \Pr[\text{sign}(x) \neq \text{sign}(y)]$ where $(x,y) \sim N\left(\begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 & \rho \\ \rho & 1 \end{pmatrix}\right)$.

$\text{sign}(x) \neq \text{sign}(y) \Leftrightarrow$



This is equal to $1 - 2 \Pr[\text{sign}(x') \neq \text{sign}(\rho x' + \sqrt{1-\rho^2} y')]$ where x', y' are

$N(0,1)$ independent. Since the angle of (x', y') is uniform on $[0, 2\pi)$ we get that

the above is $1 - 2 \cdot \frac{\arccos \rho}{\pi} = \frac{2}{\pi} \arcsin \rho$.



MAJ IS STABLEST

Thm [Mossel O'Donnell Oleszkiewicz '05]

Fix some $0 < p < 1$. Then if $f: \{0,1\}^n \rightarrow [-1,1]$ satisfies $E[f] = 0$ and $\forall i, \text{Inf}_i(f) \leq \epsilon$ (actually enough if $\text{Inf}_i^{(1-1/\log 1/\epsilon)}(f) \leq \epsilon$), then $S_p(f) \leq \frac{2}{\pi} \arcsin p + O\left(\frac{\log \log 1/\epsilon}{\log 1/\epsilon}\right)$.

Cor ("Reverse" majority is stablest)

Fix $-1 < p < 0$. Let $f: \{0,1\}^n \rightarrow [-1,1]$ satisfy $\forall i, \text{Inf}_i^{(1-1/\log 1/\epsilon)}(f) < \epsilon$, then

$S_p(f) \geq \frac{2}{\pi} \arcsin p - O\left(\frac{\log \log 1/\epsilon}{\log 1/\epsilon}\right)$. Remark: We no longer assume $E[f] = 0$.

Proof: Let $f^{\text{odd}}(x) = \frac{f(x) - f(x + (1, \dots, 1))}{2}$. Then $\hat{f}^{\text{odd}}(s) = \hat{f}(s)$ if $|s|$ is odd and 0 o.w.

Then, $\text{Inf}_i^{(1-1/\log 1/\epsilon)}(f^{\text{odd}}) \leq \text{Inf}_i^{(1-1/\log 1/\epsilon)}(f) < \epsilon$. So, by theorem,

$S_{-p}(f^{\text{odd}}) \leq \frac{2}{\pi} \arcsin(-p) + O\left(\frac{\log \log 1/\epsilon}{\log 1/\epsilon}\right) = -\frac{2}{\pi} \arcsin p + O\left(\frac{\log \log 1/\epsilon}{\log 1/\epsilon}\right)$.

So, $S_p(f) = \sum p^{|s|} \hat{f}(s)^2 \geq \sum_{s \text{ odd}} p^{|s|} \hat{f}(s)^2 = -\sum_{s \text{ odd}} (-p)^{|s|} \hat{f}(s)^2 = -S_{-p}(f^{\text{odd}})$. \square

Cor: If $f: \{0,1\}^n \rightarrow \{-1,1\}$ has no coordinate with large influence, then the probability of "outcome of a 3-candidates vote is rational" is $\frac{3}{4} - \frac{3}{4} S_{-1/3}(f) \leq \frac{3}{4} - \frac{3}{4} \cdot \frac{2}{\pi} \arcsin(-1/3) \approx 0.91226\dots$

Theorem [Khot Kindler Mossel O'Donnell '04]

For all $\eta > 0$ and $-1 < p < 0$, it is UG-hard to distinguish given a graph G between

$$\bullet \text{MAXCUT}(G) \geq \frac{1}{2} - \frac{1}{2}p - \eta, \text{ and}$$

$$\bullet \text{MAXCUT}(G) \leq \frac{1}{4} \arccos p + \eta.$$

In particular, this gives UG-hardness of approximating MAX-CUT to better than $\frac{\frac{1}{4} \arccos p}{\frac{1}{2} - \frac{1}{2}p}$, which for $p = -0.689$ gives hardness of $0.878567\dots$ matching exactly the Goemans-Williamson algorithm.

Proof: We construct a dictatorship vs. quasirandomness test of "MAXCUT type":

StableTest_p (for $-1 < p < 0$)

1. Pick $x \in \{0,1\}^n$ uniformly, and y obtained from x by flipping each bit w.p. $\frac{1-p}{2}$.
2. Accept iff $f(x) \neq f(y)$.

Note that $\text{Prob}[\text{test accepts } f] = \frac{1}{2} - \frac{1}{2} \langle f, T_p f \rangle = \frac{1}{2} - \frac{1}{2} S_p(f)$.

Hence, dictators are accepted w.p. $\frac{1}{2} - \frac{1}{2}p$ and (ϵ, δ) -quasirandom then

$\text{Pr}[\text{test accepts } f] \leq \frac{1}{2} - \frac{1}{2} \cdot \frac{2}{\pi} \arcsin p + \alpha(\epsilon, \delta) = \frac{1}{4} \arccos p + \alpha(\delta, \epsilon)$, where $\alpha(\epsilon, \delta) \rightarrow 0$ as $\epsilon, \delta \rightarrow 0$. \square

Proof sketch of MAJ is STABLEST [MOO]

Invariance principle: consider the (multi)linear polynomial $Q_1(x_1, \dots, x_n) = \frac{x_1 + x_2 + \dots + x_n}{\sqrt{n}}$.

If we replace each x_i with an independent $N(0,1)$, we obtain that Q is also $N(0,1)$. If each x_i is ± 1 independently and uniformly, then Q is approximately

$N(0,1)$ by the CLT. What about $Q_2(x_1, \dots, x_n) = x_1^2$? Here we get a different distribution if we put $N(0,1)$ or ± 1 . The "reason" is that x_1 has large influence.

What about higher degree? Take, e.g., $Q_3 = \frac{\sum_{i \neq j} x_i x_j}{n} \approx \left(\frac{\sum x_i}{\sqrt{n}} \right)^2 \leftarrow \chi^2$.

Here we get roughly the same distribution for both $\xrightarrow{N(0,1)} N(0,1)$ and ± 1 .

Thm: (invariance principle, roughly)

If $Q(x_1, \dots, x_n) = \sum_S \alpha_S \prod_{i \in S} x_i$ is a multilinear polynomial (of low degree, i.e.,

$\alpha_S = 0 \forall S$ of size $> d$, with $\sum \alpha_S^2 = 1$, and $\text{Inf}_i(Q) = \sum_{S \ni i} \alpha_S^2$ are all small), then

plugging ± 1 values or $N(0,1)$ values results in similar distributions.

Q: Why multilinear? Otherwise false, e.g., $\sum x_i^4/n$.

Proof: Similar to the Berry-Esseen theorem and uses hypercontractive ineq.

Thm: (MAJ is STABLEST)

Fix $0 < \rho < 1$. Let $f: \{-1,1\}^n \rightarrow [-1,1]$ have $E[f] = 0$ and no large influences. Then,

$$S_\rho(f) = \langle f, T_\rho f \rangle = \sum_S \rho^{|S|} \hat{f}(S)^2 \lesssim \frac{2}{\pi} \arccos \rho.$$

Proof sketch: We can write $f(x_1, \dots, x_n) = \sum_S \hat{f}(S) \prod_{i \in S} x_i$.

Define $\tilde{f}: \mathbb{R}^n \rightarrow \mathbb{R}$, by $\tilde{f}(g_1, \dots, g_n) = \sum_S \hat{f}(S) \prod_{i \in S} g_i$.

By the invariance principle, we know that when g_1, \dots, g_n are chosen from $N(0,1)$

independently then $\tilde{f}(g_1, \dots, g_n)$ is essentially in $[-1,1]$. Moreover, $E[\tilde{f}(g_1, \dots, g_n)] = \hat{f}(\emptyset) = 0$.

Def: For $\tilde{f}: \mathbb{R}^n \rightarrow \mathbb{R}$ define $S_\rho(\tilde{f}) = E_{g,h}[\tilde{f}(g) \cdot \tilde{f}(h)]$, where $g, h \in \mathbb{R}^n$ are ρ -correlated

Gaussians. Then, $S_\rho(\tilde{f}) = \sum_S \sum_T \hat{f}(S) \hat{f}(T) \cdot E_{g,h}[\prod_{i \in S} g_i \cdot \prod_{i \in T} h_i] = \sum_S \rho^{|S|} \hat{f}(S)^2 = S_\rho(f)$.

Thm: [Borell'85] Among all functions $\tilde{f}: \mathbb{R}^n \rightarrow [-1,1]$ with $E_g[\tilde{f}] = 0$, the stability

$S_\rho(f)$ is maximized by the half-space functions $x \mapsto \text{sign}(\langle x, u \rangle)$ for some $u \in \mathbb{R}^n$.

Remark: Because g and h are vectors of length \sqrt{n} and of angle $\sim \arccos \rho$, the

stability of the halfspace function is $1 - \frac{2}{\pi} \arccos \rho = \frac{2}{\pi} \arcsin \rho$.

Ex: Prove this formally.

Proof of Borell: Symmetrization.

1987, Lecture 2, 10:15 - 11:00 AM

Let X_1, \dots, X_n be independent random variables with distributions μ_1, \dots, μ_n . Let $X = (X_1, \dots, X_n)$ be the joint distribution. Let μ be the product measure $\mu_1 \otimes \dots \otimes \mu_n$.

Let $f: \mathbb{R}^n \rightarrow \mathbb{R}$ be a function. Let E_μ be the expectation with respect to μ . Let E_{μ_i} be the expectation with respect to μ_i .

Let f^* be the function $f^*(x) = \max_{y \in \mathbb{R}^n} f(x, y)$. Let $E_\mu f^*$ be the expectation of f^* with respect to μ .

Let $f^{\#}$ be the function $f^{\#}(x) = \max_{y \in \mathbb{R}^n} \min_{z \in \mathbb{R}^n} f(x, y, z)$. Let $E_\mu f^{\#}$ be the expectation of $f^{\#}$ with respect to μ .

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