1 Introduction

In a series of papers we develop a generalized Fredholm theory and demonstrate its applicability to a variety of problems including Floer theory, Gromov-Witten theory, contact homology, and symplectic field theory. Here are some of the basic common features:

- The moduli spaces are solutions of elliptic PDE’s showing serious non-compactness phenomena having well-known names like bubbling-off, stretching the neck, blow-up, breaking of trajectories. These drastic names are a manifestation of the fact that one is confronted with analytical limiting phenomena where the classical analytical descriptions break down.
• When the moduli spaces are not compact, they admit nontrivial compactifications like the Gromov compactification, [6], of the space of pseudoholomorphic curves in Gromov-Witten theory or the compactification of the moduli spaces in symplectic field theory (SFT) as described in [2].

• In many problems like in Floer theory, contact homology or symplectic field theory the algebraic structures of interest are precisely those created by the “violent analytical behavior” and its “taming” by suitable compactifications. In fact, the algebra is created by the complicated interactions of many different moduli spaces.

In the abstract theory we shall introduce a new class of spaces called polyfolds which in applications are the ambient spaces of the compactified moduli spaces. We introduce bundles \( p: Y \to X \) over polyfolds which, as well as the underlying polyfolds, can have varying dimensions. We define the notion of a Fredholm section \( \eta \) of the bundles \( p \) whose zero sets \( \eta^{-1}(0) \subset X \) are in our applications precisely the compactified moduli spaces one is interested in. The normal “Fredholm package” will be constructed consisting of an abstract perturbation and transversality theory. In the case of transversality the solution spaces are smooth manifolds, smooth orbifolds, or smooth weighted branched manifolds (in the sense of McDuff, [18]), depending on the generality of the situation.

The usefulness of this theory will be illustrated by our ‘Application Series’. The applications include Gromov-Witten theory, Floer theory and SFT, see [13, 14]. It is, however, clear that the theory applies to many more nonlinear problems showing a lack of compactness.

The current paper is the first in the ‘Theory Series’ and deals with a generalization of differential geometry which is based on new local models. These local models are open sets in splicing cores. Splicing cores are smooth spaces with tangent spaces having in general locally varying dimension. These spaces are associated to splicings which is the basic concept in this paper. The so obtained local models for a new kind of smooth spaces are needed to deal with the functional analytical descriptions of situations in which serious compactness problems arise. We would also like to note that the applications of the concepts in this paper can be viewed as a generalization of [5] to a situation where we have varying domains and targets.

The second paper, [10], develops the implicit function theorems in this general context and extends the usual Fredholm theory.
The third paper, [11], develops the Fredholm theory in polyfolds, which could be viewed as a theory of Fredholm functors in a version of Lie groupoids with object and morphism spaces build on the new local models (see [20], [21] for the groupoid concepts in a manifold world). The Fredholm theory in this generalization is sufficient to deal with the problems mentioned above.

On purpose we have not included any applications in this series since we did not want to dilute the ideas. The conceptual framework should apply to many more situations. We refer the reader to [8, 9, 13, 14] for applications on different depth levels. An overview is given in [7].

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2 Sc-Calculus in Banach Spaces

In order to develop the generalized nonlinear Fredholm theory needed for the symplectic field theory, we start with calculus issues. In a first step we equip Banach spaces with the structure of a scale, called sc-structure. Scales are a well-known concept from interpolation theory, see for example [25]. We give a new interpretation of a scale as a generalization of a smooth structure. Then we introduce the appropriate class of smooth maps. Having developed the notion of an sc-smooth structure on an open subset of a Banach space as well as that of a smooth map, the validity of the chain rule allows then, in principle, to develop an “sc-differential geometry” by simply imitating the classical constructions. However, new objects are possible, with the most important one being that of a general splicing. The main purpose of this paper is to introduce them and to show how they define local models for a new class of smooth spaces, which are crucial for the afore-mentioned applications.

2.1 sc-Structures

We begin by introducing the notion of an sc-smooth structure on a Banach space and on its open subsets.

Definition 2.1. Let $E$ be a Banach space. An sc-structure on $E$ is
given by a nested sequence

\[ E = E_0 \supseteq E_1 \supseteq E_2 \supseteq \cdots \supseteq \bigcap_{m \geq 0} E_m =: E_\infty \]

of Banach spaces \( E_m, m \in \mathbb{N} = \{0, 1, 2, \cdots\} \), having the following properties.

- If \( m < n \), the inclusion \( E_n \hookrightarrow E_m \) is a compact operator.
- The vector space \( E_\infty \) is dense in \( E_m \) for every \( m \geq 0 \).

In the following we shall sometimes talk about an sc-smooth structure on a Banach spaces rather than an sc-structure to emphasize the smoothness aspect. From the definition of an sc-structure it follows, in particular, that \( E_n \subseteq E_m \) is dense if \( m < n \) and the embedding is continuous. We note that \( E_\infty \) has the structure of a Frechet space. In the case \( \dim(E) < \infty \) the only possible sc-structure is the constant structure with \( E_m = E \).

If \( U \subset E \) is an open subset we define the **induced sc-smooth structure** on \( U \) to be the nested sequence \( U_m = U \cap E_m \). Given an sc-smooth structure on \( U \) we observe that \( U_m \) inherits the sc-smooth structure defined by \( (U_m)_k = U_{m+k} \). We will write \( E^m \) to emphasize that we are dealing with the Banach space \( E_m \) equipped with the sc-structure \( (E^m)_k := E_{m+k} \) for all \( k \geq 0 \). Similarly we will distinguish between \( U_m \) and \( U^m \).

**Remark 2.2.** The compactness requirement is crucial for applications. It is possible to develop a theory without this requirement, but it is not applicable to the theories we are interested in. This alternative theory would in the case of the constant sequence \( E_m = E \) recover the standard smooth structure on \( E \). However, the notion of a smooth map would be more restrictive. Both theories, the one described in this paper and the one just alluded to, intersect therefore only in the standard finite-dimensional theory. See Remark 2.17 for further details.

If \( E \) and \( F \) are equipped with sc-structures, the Banach space \( E \oplus F \) carries the sc-structure defined by \( (E \oplus F)_m = E_m \oplus F_m \).

**Definition 2.3.** Let \( U \) and \( V \) be open subsets of sc-smooth Banach spaces. A continuous map \( \varphi : U \to V \) is said to be of **class sc**\(^0\) or simply **sc**\(^0\) if \( \varphi(U_m) \subseteq V_m \) and the induced maps

\[ \varphi : U_m \to V_m \]
are all continuous.

Next we define the tangent bundle.

**Definition 2.4.** Let $U$ be an open subset in an sc-smooth Banach space $E$ equipped with the induced sc-structure. Then the **tangent bundle** $TU$ of $U$ is defined by $TU = U^1 \oplus E$. Hence the induced sc-smooth structure is defined by the nested sequence

$$(TU)_m = U_{m+1} \oplus E_m$$

together with the $sc^0$-projection

$$p : TU \to U^1.$$ 

Note that the tangent bundle is not defined on $U$ but merely on the smaller, but dense, subset $U_1$. We shall refer to the points in $U_m$ sometimes as the points in $U$ on level $m$.

### 2.2 Linear Sc-Theory

We begin by developing some of the linear theory needed in the sc-calculus.

**Definition 2.5.** Consider $E$ equipped with an sc-smooth structure.

- An **sc-subspace** $F$ of $E$ consists of a closed linear subspace $F \subseteq E$, so that $F_m = F \cap E_m$ defines an sc-structure for $F$.

- An sc-subspace $F$ of $E$ **splits** if there exists another sc-subspace $G$ so that on every level we have the topological direct sum

$$E_m = F_m \oplus G_m.$$ 

We shall use the notation $E = F \oplus_{sc} G$ or $E = F \oplus G$ if there is no possibility of confusion.

Next we introduce the relevant linear operators in the sc-context.

**Definition 2.6.** Let $E$ and $F$ be sc-smooth Banach spaces.

- An **sc-operator** $T : E \to F$ is a bounded linear operator which in addition is $sc^0$, i.e. it induces bounded linear operators $T : E_m \to F_m$ on all levels.
• An sc-isomorphism is a bijective sc-operator $T : E \to F$ such that $T^{-1} : F \to E$ is also an sc-operator.

An interesting class of sc-operators is the class of sc-projections, i.e. sc-operators $P$ with $P^2 = P$.

**Proposition 2.7.** Let $E$ be an sc-smooth Banach space and $K$ a finite-dimensional subspace of $E_\infty$. Then $K$ splits the sc-space $E$.

Note that a finite-dimensional subspace $K$ of $E$ which splits the sc-smooth space $E$ is necessarily a subspace of $E_\infty$.

**Proof.** Take a basis $e_1, ..., e_n$ for $K$ and fix the associated dual basis. By Hahn Banach this dual basis can be extended to continuous linear functionals $\lambda_1, ..., \lambda_n$ on $E$. Now $P(h) = \sum_{i=1}^n \lambda_i(h)e_i$ defines a continuous projection on $E$ with image in $K \subset E_\infty$. Hence $P$ induces continuous maps $E_m \to E_m$. Therefore $P$ is an sc-projection. Define $Y_m = (Id - P)(E_m)$. Setting $Y = Y_0$ we have $E = K \oplus Y$. By construction, $Y_m \subset E_m \cap Y_0$. An element $x \in E_m \cap Y_0$ has the form $x = e - P(e)$ with $e \in E_0$. Since $P(e) \in E_\infty$ we see that $e \in E_m$, implying $Y_m = E_m \cap Y_0$. Finally, $Y_\infty = \bigcap_{m \geq 0} Y_m$ is dense in $Y_m$ for every $m \geq 0$. Indeed, if $x \in Y_m$, we can choose $x_k \in E_\infty$ satisfying $x_k \to x$ in $E_m$. Then $(Id - P)x_k \in Y_\infty$ and $(Id - P)x_k \to (Id - P)x = x$ in $Y_m$. 

We can introduce the notion of a linear Fredholm operator in the sc-setting.

**Definition 2.8.** Let $E$ and $F$ be sc-smooth Banach spaces. An sc-operator $T : E \to F$ is called **Fredholm** provided there exist sc-splittings $E = K \oplus_{sc} X$ and $F = Y \oplus_{sc} C$ having the following properties.

• $K = \text{kernel } (T)$ is finite-dimensional.

• $C$ is finite-dimensional.

• $Y = T(X)$ and $T : X \to Y$ defines a linear sc-isomorphism.

The above definition implies that $T(X_m) = Y_m$, the kernel of $T : E_m \to F_m$ is equal to $K$ and $C$ spans its cokernel, so that

$$E_m = K \oplus X_m \quad \text{and} \quad F_m = C \oplus T(E_m)$$
for all \( m \geq 0 \). It is an easily established fact that the composition of two sc-Fredholm operators \( T \) and \( S \) is sc-Fredholm. From the index additivity of classical Fredholm operators we obtain the same in our set-up

\[
i(TS) = i(T) + i(S).
\]

The following observation, called the regularizing property, should look familiar.

**Proposition 2.9.** Assume \( T : E \to F \) is sc-Fredholm and \( T(e) \in F_m \) for some \( e \in E_0 \). Then \( e \in E_m \).

**Proof.** Since \( F_m = T(E_m) \oplus C \), the element \( f = T(e) \in F_m \) has the representation

\[
f = T(x) + c
\]

for some \( x \in X_m \) and \( c \in C \). Similarly, \( e \) has the representation

\[
e = k + x_0,
\]

with \( k \in K = \ker T \) and \( x_0 \in X_0 \) because \( E_0 = K \oplus X_0 \). From \( T(e) = f = T(x) + c \) and \( T(x) = T(x_0) \) one concludes \( T(x_0 - x) = c \). Hence \( c = 0 \) because \( T(E_0) \cap C = \{0\} \). Consequently, \( x_0 - x \in K \). Since \( e - x = k + (x_0 - x) \in K \) and \( x \in E_m \) and \( K \subseteq E_m \), one concludes \( e \in E_m \) as claimed. \( \blacksquare \)

We end this subsection with the important definition of an sc\(^+\)-operator and an stability result for Fredholm maps.

**Definition 2.10.** Let \( E \) and \( F \) be sc-Banach spaces. An sc-operator \( R : E \to F \) is said to be an **sc\(^+\)-operator** if \( R(E_m) \subset F_{m+1} \) for every \( m \geq 0 \) and if \( R \) induces an sc\(^0\)-operator \( E \to F^1 \).

Let us note that due to the (level-wise) compact embedding \( F^1 \to F \) an sc\(^+\)-operator induces on every level a compact operator. This follows immediately from the factorization

\[
R : E \to F^1 \to F.
\]

The stability result is the following statement.
Proposition 2.11. Let $E$ and $F$ be sc-Banach spaces. If $T : E \to F$ is an sc-Fredholm operator and $R : E \to F$ an sc$^+$-operator, then $T + R$ is also an sc-Fredholm operator.

Proof. Since $R : E_m \to F_m$ is compact for every level we see that $T + R : E_m \to F_m$ is Fredholm for every $m$. Let $K_m$ be the kernel of $T + R : E_m \to F_m$. We claim that $K_m = K_{m+1}$ for every $m \geq 0$. Clearly, $K_{m+1} \subseteq K_m$. To see that $K_m \subseteq K_{m+1}$, take $x \in K_m$. Then $Tx = -Rx \in F_{m+1}$ and, in view of Proposition 2.9, $x \in E_{m+1}$. Hence $x \in K_{m+1}$ implying $K_m \subseteq K_{m+1}$.

Set $K = K_0$. By Proposition 2.7, $K$ splits the sc-space $E$ since it is a finite dimensional subset of $E_\infty$. Hence we have the sc-splitting $E = K \oplus X$ for a suitable sc-subspace $X$. Next define $Y_m = (T + R)(E_m)$. This defines an sc-structure on $Y = Y_0$. Let us show that $F$ induces an sc-structure on $Y$ and that this is the one given by $Y_m$. For this it suffices to show that

\[ Y \cap F_m = Y_m. \tag{1} \]

Clearly,

\[ Y_m = (T + R)(E_m) = F_m \cap (T + R)(E_m) \subseteq F_m \cap (T + R)(E_0) = Y \cap F_m. \]

Next assume that $y \in Y \cap F_m$. Then there exists $x \in E_0$ with $Tx + Rx = y$. Since $R$ is an sc$^+$-section it follows that $y - Rx \in F_1$ implying that $x \in E_1$. Inductively we find that $x \in E_m$ implying that $y \in Y_m$ and (1) is proved. Observe that we also have

\[ F_\infty \cap Y = \bigcap_{m \in \mathbb{N}} F_m \cap Y = \bigcap_{m \in \mathbb{N}} (F_m \cap Y) = \bigcap_{m \in \mathbb{N}} Y_m = Y_\infty. \]

In view of Lemma 2.12 below, there exists a finite dimensional subspace $C \subseteq F_\infty$ satisfying $F_0 = C \oplus Y$. From this it follows that $F_m = C \oplus Y_m$. Indeed, since $C \cap Y_m \subseteq C \cap Y$, we have $C \cap Y_m = \{0\}$. If $f \in F_m$, then $f = c + y$ for some $c \in C$ and $y \in Y$ since $F_m \subseteq Y$ and $F_0 = C \oplus Y$. Hence $y = f - c \in F_m$ and using Proposition 2.9 we conclude $y \in F_m$. This implies, in view of (1), that $F_m = C \oplus Y_m$. We also have $F_\infty = C \oplus (F_\infty \cap Y) = C \oplus Y_\infty$. It remains to show that $Y_\infty$ is dense in $Y_m$ for every $m \geq 0$. Take $y \in Y_m$. Then $y = (T + R)(x)$ for some $x \in E_m$. The space $E_\infty$ is dense in $E_m$ so that there exists a sequence $(x_n) \subseteq E_\infty$ converging to $x$ in $E_m$. The operator $T + R$ is sc$^0$-continuous and so the sequence $y_n := (T + R)(x_n) \in F_m$ converges to $y = (T + R)(x) \in F_m$. Now, in view of Proposition 2.9 and Definition 2.10.
the points \(y_n\) belong to \(Y_\infty\) and our claim is proved. Consequently, we have the sc-splitting
\[
F = Y \oplus_{sc} C
\]
and, up to the Lemma 2.12 below, the proof of the proposition is complete. ■

**Lemma 2.12.** Assume \(F\) is a Banach space and \(F = D \oplus Y\) with \(D\) of finite-dimension and \(Y\) a closed subspace of \(F\). Assume, in addition, that \(F_\infty\) is a dense subspace of \(F\). Then there exists a finite dimensional subspace \(C \subset F_\infty\) such that \(F = C \oplus Y\).

*Proof.\* The quotient \(F/Y\) is a finite-dimensional Banach space and we have a continuous projection operator
\[
p : F \to F/Y
\]
Since \(F_\infty\) is a dense linear subspace of \(F\) we find that
\[
p(F_\infty) = F/Y.
\]
Take any basis for \(F/Y\) and pick representatives for these vectors in \(F_\infty\). Their span \(C\) has the desired property. ■

### 2.3 Sc-Smooth Maps

In this subsection we introduce the notion of an \(sc^1\)-map.

**Definition 2.13.** Let \(E\) and \(F\) be sc-smooth Banach spaces and let \(U \subset E\) be an open subset. An \(sc^0\)-map \(f : U \to F\) is said to be \(sc^1\) or of class \(sc^1\) if the following conditions hold true.

1. For every \(x \in U_1\) there exists a linear map \(Df(x) \in \mathcal{L}(E_0, F_0)\) satisfying for \(h \in E_1\), with \(x + h \in U_1\),
   \[
   \frac{1}{\|h\|_1} \|f(x + h) - f(x) - Df(x)h\|_0 \to 0 \quad \text{as} \quad \|h\|_1 \to 0
   \]
2. The tangent map \(Tf : TU \to TF\), defined by
   \[
   Tf(x, h) = (f(x), Df(x)h)
   \]
   is an \(sc^0\)-map.
The linear map $Df(x)$ will in the following often be called the linearization of $f$ at the point $x$. If the sc-continuous map $f : U \subset E \to F$ is of class sc$^1$, then its tangent map

$$Tf : TU \to TF$$

is an sc$^0$-map. If now $Tf$ is of class sc$^1$, then $f : U \to F$ is called of class sc$^2$.

Proceeding inductively, the map $f : U \to F$ is called of class sc$^k$ if the sc$^0$-map $T^{k-1}f : T^{k-1}U \to T^{k-1}F$ is of class sc$^1$. Its tangent map $T(T^{k-1}f)$ is then denoted by $T^k f$. It is an sc$^0$-map $T^k U \to T^k F$. A map which is of class sc$^k$ for every $k$ is called sc-smooth or of class sc$^\infty$.

Here are two useful observations which are proved in [8].

**Proposition 2.14.** If $f : U \subset E \to F$ is of class sc$^k$, then

$$f : U_{m+k} \to F_m$$

is of class $C^k$ for every $m \geq 0$.

If we denote the usual derivative of a map $f$ by $df$ we have for $x, h \in U_{m+1}$ the equality $df(x)(h) = Df(x)h$. In fact $Df(x)$ can be viewed as the (unique) continuous extension of $df(x) : E_{m+1} \to F_m$ to an operator $E \to F$, which satisfies $Df(x)(E_m) \subset F_m$ for every $m \geq 0$ and induces continuous operators on these levels. It exists for every $x \in U_1$ due to the definition of the class sc$^1$.

The second result is the following.

**Proposition 2.15.** Let $E$ and $F$ be sc-Banach spaces and let $U \subset E$ be open. Assume that the map $f : U \to F$ is sc$^0$ and that the induced map $f : U_{m+k} \to F_m$ is $C^{k+1}$ for every $m, k \geq 0$. Then $f : U \to E$ is sc-smooth.

Reflecting on the notion of class sc$^1$ one could expect for the composition $g \circ f$ of two such maps, that the target level would have to drop by 2 in order to obtain a $C^1$-map. In view of Proposition 2.14 one might think that therefore the composition needs not to be of class sc$^1$. However, this is not the case, as the next result, the important chain rule shows.

**Theorem 2.16 (Chain Rule).** Assume that $E$, $F$ and $G$ are sc-smooth Banach spaces and $U \subset E$ and $V \subset F$ are open sets. Assume that $f :
$U \to F$, $g : V \to G$ are of class $sc^1$ and $f(U) \subset V$. Then the composition $g \circ f : U \to G$ is of class $sc^1$ and the tangent maps satisfy

$$T(g \circ f) = Tg \circ Tf.$$ 

Proof. We shall verify the properties (1) and (2) in Definition 2.13 for $g \circ f$. The functions $g : V_1 \to G$ and $f : U_1 \to F$ are of class $C^1$. Moreover, $Dg(f(x)) \circ Df(x) \in \mathcal{L}(E, G)$ if $x \in U_1$. Fix $x \in U_1$ and choose $h \in E_1$ sufficiently small so that $f(x+h) \in V_1$. Then, using the postulated properties of $f$ and $g$,

$$g(f(x+h)) - g(f(x)) = Dg(f(x)) \circ Df(x)h$$

$$= \int_0^1 Dg(tf(x+h) + (1-t)f(x)) [f(x+h) - f(x) - Df(x)h] dt$$

(2) $$+ \int_0^1 ([Dg(tf(x+h) + (1-t)f(x)) - Dg(f(x))] \circ Df(x)h) dt.$$ 

Divide the first integral by the norm $\|h\|_1$, then

$$\frac{1}{\|h\|_1} \int_0^1 Dg(tf(x+h) + (1-t)f(x))[f(x+h) - f(x) - Df(x)h] dt$$

$$= \int_0^1 Dg(tf(x+h) + (1-t)f(x)) \cdot \frac{1}{\|h\|_1} [f(x+h) - f(x) - Df(x)h] dt.$$ 

(3)

If $h \in E_1$, the maps $[0, 1] \to F_1$ defined by $t \to tf(x+h) + (1-t)f(x)$ are continuous and converge in $C^0([0,1], F_1)$ to the constant map $t \to f(x)$ as $\|h\|_1 \to 0$. Moreover, since $f$ is of class $sc^1$,

$$a(h) := \frac{1}{\|h\|_1} [f(x+h) - f(x) - Df(x)h]$$

converges to 0 in $F_0$ as $\|h\|_1 \to 0$. Therefore, by the continuity assumption (2) in Definition 2.13, the map

$$(t, h) \to Dg(tf(x+h) + (1-t)f(x))a(h)$$

as a map from $[0,1] \times E_1$ into $G_0$ converges to 0 as $h \to 0$, uniformly in $t$. Therefore, the expression in (3) converges to 0 in $G_0$ as $h \to 0$ in $E_1$. Next consider the integral

$$\int_0^1 [Dg(tf(x+h) + (1-t)f(x)) - Dg(f(x))] \circ Df(x) \frac{h}{\|h\|_1} dt.$$ 

(4)
In view of Definition 2.1 the set of all \( \frac{h}{\|h\|_1} \in E_1 \) has a compact closure in \( E_0 \). Therefore, since \( Df(x) \in \mathcal{L}(E_0, F_0) \) is a continuous map by Definition 2.13, the closure of the set of all

\[
Df(x) \frac{h}{\|h\|_1}
\]

is compact in \( F_0 \). Consequently, again by Definition 2.1, every sequence \( h_n \) converging to 0 in \( E_1 \) possesses a subsequence having the property that the integrand of the integral in (4) converges to 0 in \( G_0 \) uniformly in \( t \). Hence the integral (4) also converges to 0 in \( G_0 \) as \( h \to 0 \) in \( E_1 \). We have proved that

\[
\frac{1}{\|h\|_1} \|g(f(x + h)) - g(f(x)) - Dg(f(x)) \circ Df(x)h\|_0 \to 0
\]
as \( h \to 0 \) in \( E_1 \). Consequently, condition (1) of Definition 2.13 is satisfied for the linear operator

\[
D(g \circ f)(x) = Dg(f(x)) \circ Df(x) \in \mathcal{L}(E_0, G_0),
\]
where \( x \in U_1 \). We conclude that the tangent map \( T(g \circ f) : TU \to TG \),

\[
(x, h) \mapsto (g \circ f(x), D(g \circ f)(x)h)
\]
is sc-continuous and, moreover, \( T(g \circ f) = Tg \circ Tf \). The proof of Theorem 2.16 is complete.

The reader should realize that in the previous proof all conditions on sc\(^1\) maps have been used, i.e. it just works. From Theorem 2.16 one concludes by induction that the composition of two sc\(^\infty\)-maps is also of class sc\(^\infty\) and, for every \( k \geq 1 \),

\[
T^k(g \circ f) = T^k g \circ T^k f.
\]

An sc-diffeomorphism \( f : U \to V \), between open subsets \( U \) and \( V \) of sc-spaces \( E \) and \( F \) equipped with the induced sc-structure, is by definition a homeomorphism \( U \to V \) so that \( f \) and \( f^{-1} \) are sc-smooth.

The following remark is a continuation of Remark 2.2.

**Remark 2.17.** There are other possibilities for defining new concepts of smoothness. For example, we can drop the requirement of compactness of
the embedding operator $E_n \rightarrow E_m$ for $n > m$. Then it is necessary to change the definition of smoothness in order to get the chain rule. One needs to replace the second condition in the definition of being $sc^1$ by the requirement that $Df(x)$ induces a continuous linear operator $Df(x) : E_{m-1} \rightarrow F_{m-1}$ for $x \in U_m$ and that the map $Df : U_m \rightarrow \mathcal{L}(E_{m-1}, F_{m-1})$ for $m \geq 1$ is continuous. For this theory the $sc$-smooth structure on $E$ given by $E_m = E$ recovers the usual $C^k$-theory. However, this modified theory is not applicable to the Gromov-Witten theory, Floer theory, or SFT.

### 2.4 Sc-Manifolds

Using the results so far, we can define $sc$-manifolds. This concept will not yet be sufficient to describe the spaces arising in the SFT.

**Definition 2.18.** Let $X$ be a second countable Hausdorff space. An sc-chart of $X$ consists of a triple $(U, \varphi, E)$, where $U$ is an open subset of $X$, $E$ a Banach space with an $sc$-smooth structure and $\varphi : U \rightarrow E$ is a homeomorphism onto an open subset $V$ of $E$. Two such charts are $sc$-smoothly compatible provided the transition maps are $sc$-smooth. An sc-smooth atlas consists of a family of charts whose domains cover $X$ so that any two charts are $sc$-smoothly compatible. A maximal sc-smooth atlas is called an sc-smooth structure on $X$. The space $X$ equipped with a maximal sc-smooth atlas is called an sc-manifold.

Let us observe that a second countable Hausdorff space which admits an sc-smooth atlas is metrizable and paracompact since it is locally homeomorphic to open subsets of Banach spaces.

Assume that the space $X$ has an sc-smooth structure. Then it possesses the filtration $X_m$ for all $m \geq 0$ which is induced from the filtration of the charts. Moreover, every $X_m$ inherits the sc-smooth structure $(X_m)_k = X_{m+k}$ for all $k \geq 0$, denoted by $X^m$.

Next we shall define the tangent bundle $p : TX \rightarrow X^1$ in a natural way so that the tangent projection $p$ is $sc$-smooth. In order to do so, we use a modification of the definition found, for example, in Lang’s book [16]. Namely, consider multiplets $(U, \varphi, E, x, h)$ where $(U, \varphi, E)$ is an sc-smooth chart, $x \in U_1$ and $h \in E$. Call two such tuples equivalent if $x = x'$ and $D(\varphi' \circ \varphi^{-1})(\varphi(x))h = h'$. An equivalence class $[U, \varphi, E, x, h]$ is called a tangent vector at the point $x \in X_1$. The collection of all tangent vectors of
$X$ is denoted by $TX$. The canonical projection is denoted by $p : TX \to X^1$. If $U \subset X$ is open we introduce the subset $TU \subset TX$ by $TU = p^{-1}(U \cap X^1)$. For a chart $(U, \varphi, E)$ we introduce the map

$$T\varphi : TU \to E^1 \oplus E$$

defined by

$$T\varphi([U, \varphi, E, x, h]) = (x, h).$$

One easily checks that the collection of all triples $(TU, T\varphi, E^1 \oplus E)$ defines an sc-smooth atlas for $TX$ for which the projection $p : TX \to X^1$ is an sc-smooth map. The tangent space $T_xX$ at $x \in X_1$ is the set of equivalence classes

$$T_xX = \{[U, \varphi, E, x, h] | h \in E\}$$

which inherits from $E$ the structure of a Banach space. If $x \in X_{m+1}$, then $T_xX$ possesses the partial filtration inherited from $E_k$, $0 \leq k \leq m$. In particular, if $x \in X_\infty$, then $T_xX$ possesses an sc-smooth structure.

There is another class of bundles which can be defined in the present context. These are the so-called strong (vector) bundles. They may be viewed as a special case of strong M-polyfold bundles which will be introduced in Section 4. For this reason we shall not introduce them separately and refer the reader to Remark 4.3.

## 3 Splicing-Based Differential Geometry

In this section we introduce a “splicing-based differential geometry”. The fundamental concepts are splicings and splicing cores. The splicing cores have locally varying dimensions but admit at the same time tangent spaces. Open subsets of the splicing cores will serve as the local models of the new global spaces called M-polyfolds. The letter M should remind of a manifold type space obtained by gluing together in an sc-smooth way the local models. The M-polyfolds are equipped with substitutes for tangent bundles, so that one is able to linearize sc-smooth maps between M-polyfolds. In one of the follow-up papers we go further and introduce the notion of a polyfold which is a generalization of an orbifold and which is on the level of generalization needed for our applications.
3.1 Quadrants and Splicings

Let us call a subset $C$ of an sc-Banach space $W$ a **partial quadrant** if there is an sc-Banach space $Q$ and a linear sc-isomorphism $T : W \rightarrow \mathbb{R}^n \oplus Q$ mapping $C$ onto $[0, \infty)^n \oplus Q$. If $Q = \{0\}$, then $C$ is called a **quadrant**. Observe that if $C$ and $C'$ are partial quadrants so is $C \oplus C'$.

**Definition 3.1.** Assume $V$ is an open subset of a partial quadrant $C \subset W$. Let $E$ be an sc-Banach space and let $\pi_v : E \rightarrow E$ with $v \in V$, be a family of projections (i.e. $\pi_v \in \mathcal{L}(E)$ and $\pi_v \circ \pi_v = \pi_v$) so that the induced map

$$\Phi : V \oplus E \rightarrow E$$

$$\Phi(v, e) = \pi_v(e)$$

is sc-smooth. Then the triple $S = (\pi, E, V)$ is called an **sc-smooth splicing**.

The extension of the sc-smoothness definition of a map $f : V \rightarrow F$ from an open subset of a sc-Banach space to relatively open subsets $V \subset C \subset W$ of a partial quadrant $C$ in an sc-Banach space, which is used in Definition 3.1, is straightforward. One first observes that the sc-structure of $W$ induces a filtration on $V$. Now, the notion of the map $f$ to be an sc$^0$-map is well-defined. Then one defines an sc$^0$-map $f : V \rightarrow F$ to be of class sc$^1$ as in the Definition 2.13 by replacing in there $U_1$ by $V_1$ and requiring the existence of the limit for $x \in V_1$ and all $h \in W_1$ satisfying $x + h \in V_1$, with a linear map $Df(x) \in \mathcal{L}(W_0, F_0)$. Moreover, the tangent bundle $TV$ of the set $V$ is defined as usual by $TV = V^1 \oplus W$ together with the sc$^0$-projection map $TV \rightarrow V^1$.

Every splicing $S = (\pi, E, V)$ is accompanied by the **complementary splicing** $S^c = (1 - \pi, E, V)$ where $1 - \pi$ stands for the family of projections $(1 - \pi_v)(e) = e - \pi_v(e)$ for $(v, e) \in V \oplus E$. This way the splicing decomposes the set $V \oplus E$ naturally into a fibered sum over the parameter set $V$. Indeed, $(v, e) \in V \oplus E$ can be decomposed as

$$(v, e) = (v, e_v + e_v^c)$$

where $\pi_v(e) = e_v$ and $(1 - \pi_v)(e) = e_v^c$. The splicing cores $K^S$ and $K^{S^c}$ can be viewed as bundles over $V$ (with linear Banach space fibers, which however change dimensions). Their Whitney sum over $V$

$$K^S \oplus_V K^{S^c} = \{(v, a, b) \in V \oplus E \oplus E \mid \pi_v(a) = a, \pi_v(b) = 0\}$$
is naturally diffeomorphic to \( V \oplus E \). The name splicing comes from the fact that it defines a decomposition of \( V \oplus E \to V \), by ‘splicing’ it along \( V \).

We should point out that the sc-smoothness of the mapping \( (v, e) \mapsto \pi_v(e) \) is a rather weak requirement allowing the dimension of the images of the projections \( \pi_v \) to vary locally in the parameter \( v \in V \). The reader can find illustrations and examples are found in [8].

Since \( \pi_v \) is a projection,
\[
\Phi(v, \Phi(v, e)) = \Phi(v, e). \tag{5}
\]

The left-hand side is the composition of \( \Phi \) with the sc-smooth map \( (v, e) \to (v, \Phi(v, e)) \). For fixed \( (v, \delta v) \in TV \) we introduce the map
\[
P_{(v, \delta v)} : TE \to TE \\
(e, \delta e) \to (\Phi(v, e), D\Phi(v, e)(\delta v, \delta e)). \tag{6}
\]

It has the property that the induced map
\[
TV \oplus TE \to TE : (a, b) \to P_a(b)
\]
is sc-smooth because, modulo the identification \( TV \oplus TE = T(V \oplus E) \), it is equal to the tangent map of \( \Phi \). From [9] one obtains by means of the chain rule (Theorem 2.16) at the points \( (v, e) \in (V \oplus E)_1 \), the formula
\[
D\Phi(v, \Phi(v, e))(\delta v, D\Phi(v, e)(\delta v, \delta e)) = D\Phi(v, e)(\delta v, \delta e)
\]
and, together with the definition of \( P \), one computes
\[
P_{(v, \delta v)} \circ P_{(v, \delta v)}(e, \delta e) = P_{(v, \delta v)}(\pi_v(e), D\Phi(v, e)(\delta v, \delta e)) \\
= (\pi_v(e), D\Phi(v, \pi_v(e))(\delta v, D\Phi(v, e)(\delta v, \delta e))) \\
= (\pi_v(e), D\Phi(v, e)(\delta v, \delta e)) = P_{(v, \delta v)}(e, \delta e).
\]

Consequently, \( P_{(v, \delta v)} \) is a projection, which of course can be identified with the tangent \( T\pi \) of the map \( \pi : V \oplus E \to E \), defined by \( \pi(v, e) = \pi_v(e) \), via
\[
P_{(v, \delta v)}(e, \delta e) = T\pi((v, e), (\delta v, \delta e)).
\]

In the following we shall write \( (T\pi)_{(v, \delta v)} \) instead of \( P_{(v, \delta v)} \). Hence the triple
\[
TS = (T\pi, TE, TV)
\]
is an sc-smooth splicing, called the tangent splicing of \( S \).
Definition 3.2 (Splicing Core). If $S = (\pi, E, V)$ is an sc-smooth splicing, then the associated splicing core is the image bundle of the projection $\pi$ over $V$, i.e., it is the subset $K^S \subset V \oplus E$ defined by

$$K^S := \{(v, e) \in V \oplus E| \pi_v(e) = e\}. \quad (7)$$

If the dimension of $E$ is finite, the images of the projections $\pi_v$ have all the same rank so that the splicing core is a smooth vector bundle over $V$. If, however, the dimension of $E$ is infinite, then the ranks of the fibers can change with the parameter $v$ thanks to the definition of sc-smoothness. This truly infinite dimensional phenomenon is crucial for our purposes.

The splicing core of the tangent splicing $TS$ is the set

$$K^{TS} = \{(v, \delta v, e, \delta e) \in TV \oplus TE| (T\pi)_{(v, \delta v)}(e, \delta e) = (e, \delta e)\}. \quad (8)$$

The mapping

$$K^{TS} \rightarrow (K^S)^1 : (v, \delta v, e, \delta e) \mapsto (v, e) \in V_1 \oplus E_1$$

is the canonical projection. The fiber over every point $(v, e) \in (K^S)^1$ is a subspace $K^{TS}_{(v, e)}$ of the Banach space $W \oplus E$. If $(v, e)$ is on level $m + 1$, then $K^{TS}_{(v, e)}$ has well defined levels $k \leq m$. The tangent splicing $K^{TS}$ has well defined bi-levels $(m, k)$ with $k \leq m$. Indeed, assuming for simplicity that $W = \mathbb{R}^n \oplus Q$, then $V \subset C \subset W$ and $TV = V^1 \oplus W$ and we can define for $0 \leq k \leq m$,

$$(K^{TS})_{m,k} = \{(v, \delta v, e, \delta e) \in V_{m+1} \oplus W_k \oplus E_{m+1} \oplus E_k| (T\pi)_{(v, \delta v)}(e, \delta e) = (e, \delta e)\}.$$

The projection $K^{TS} \rightarrow (K^S)^1 : (v, \delta v, e, \delta e) \mapsto (v, e)$ maps level $(m, k)$ points to level $m$ points. We may view $k$ as the fiber regularity and $m$ as the base regularity. Note that a point $e$ of $E^j$ of regularity $m$ has regularity $m + j$ as a point in $E$. The following is one of our main definitions.

Definition 3.3. A local M-polyfold model consists of a pair $(O, S)$ where $O$ is an open subset of the splicing core $K^S \subset V \oplus E$ associated with the sc-smooth splicing $S = (\pi, E, V)$. The tangent of the local M-polyfold model $(O, S)$ is the object defined by

$$T(O, S) = (K^{TS}|O^1, TS)$$
where $K^T_S|O^1$ denotes the collection of all points in $K^T_S$ which project under the canonical projection $K^T_S \to (K^S)\hat{1}$ onto the points in $O^1$.

There is the natural projection

$$K^T_S|O^1 \to O^1 : (v, \delta v, e, \delta e) \to (v, e).$$

In the following we shall simply write $O$ instead of $(O, S)$, but keep in mind that $S$ is part of the structure. With this notation the tangent $TO = T(O, S)$ of the open subset $O$ of the splicing core $K^S$ is the set

$$TO = K^T_S|O^1. \quad (9)$$

Note that on an open subset $O$ of a splicing core there is an induced filtration. Hence we may talk about $sc^0$-maps. We will see in the next section that there is also a well-defined notion of a $sc^1$-map in this setting. We shall see in the applications presented in [8, 9, 13, 14] that analytical limiting phenomena occurring in symplectic field theory, Gromov-Witten theory and Floer Theory, like bubbling-off, are smooth within the splicing world.

### 3.2 Smooth Maps between Splicing Cores

The aim of this section is to introduce the concept of an $sc^1$-map between local M-polyfold models. We will construct the tangent functor and show the validity of the chain rule. At that point we will have established all the ingredients for building the “splicing-differential geometry” mentioned in the introduction.

Consider two open subsets $O \subset K^S \subset V \oplus E$ and $O' \subset K^{S'} \subset V' \oplus E'$ of splicing cores belonging to the splicings $S = (\pi, E, V)$ and $S' = (\pi', E', V')$. The open subsets $V$ and $V'$ of partial quadrants are contained in the $sc$-Banach spaces $W$ resp. $W'$. Consider an $sc^0$-map

$$f : O \to O'.$$

If $O$ is an open subset of the splicing core $K^S \subset V \oplus E$ we define the subset $\hat{O}$ of $V \oplus E$ by

$$\hat{O} = \{(v, e) \in V \oplus E | (v, \pi_v(e)) \in O\}.$$

Clearly, $\hat{O}$ is open in $V \oplus E$ and can be viewed as a bundle $\hat{O} \to O$ over $O$. This bundle will be important in subsection 4.2 where the crucial notion of a filler is being introduced.
Definition 3.4. The $sc^0$-continuous map $f: O \to O'$ between open subsets of splicing cores is called of class $sc^1$ if the map
\[
\hat{f} : \hat{O} \subset V \oplus E \to W' \oplus E'
\]
\[
\hat{f}(v, e) = f(v, \pi_v(e))
\]
is of class $sc^1$.

According to the splitting of the image space we set
\[
\hat{f}(v, e) = (\hat{f}_1(v, e), \hat{f}_2(v, e)) \in K^{S'} \subset W' \oplus E'.
\]
The tangent map $T\hat{f}$ associated with the $sc^1$-map $\hat{f}$ is defined as
\[
T\hat{f}(v, \delta v, e, \delta e) := (T\hat{f}_1(v, \delta v, e, \delta e), T\hat{f}_2(v, \delta v, e, \delta e)).
\]
The map $T\hat{f}$ is of class $sc^0$.

Lemma 3.5. The tangent map $T\hat{f}$ satisfies $T\hat{f}(K^{TS}|O^1) \subset K^{TS'}|O^1$ and hence induces a map
\[
K^{TS}|O^1 \to K^{TS'}|O^1
\]
which we denote by $Tf$. In the simplified notation of (8), we have
\[
Tf : TO \to TO'.
\]

Proof. Denote by $\pi'_v$ the family of projections associated with the splicing $S'$. Since $f : O \to O'$, we have by definition of the splicing core $K^{S'}$ the formula
\[
\pi'_{\hat{f}_1(v, e)}(\hat{f}_2(v, e)) = \hat{f}_2(v, e).
\]
Differentiating this identity in the variable $(v, e)$ we obtain
\[
D\hat{f}_2(v, e)(\delta v, \delta e) = D_v\pi'_{\hat{f}_1(v, e)}(\hat{f}_2(v, e)) \circ D\hat{f}_1(v, e)(\delta v, \delta e)
\]
\[
+ \pi'_{\hat{f}_1(v, e)} \circ D\hat{f}_2(v, e)(\delta v, \delta e).
\]
Set
\[
v' = \hat{f}_1(v, e), \quad e' = \hat{f}_2(v, e), \quad \delta v' = D\hat{f}_1(v, e)(\delta v, \delta e), \quad \delta e' = D\hat{f}_2(v, e)(\delta v, \delta e).
\]
Then (11) implies using the definition (6) of the projection $(T\pi')(\delta v', \delta e')$ associated with the splicing $TS'$ that
\[
(T\pi')(\delta v', \delta e')(e', \delta e') = (e', \delta e').
\]
So, indeed $Tf(v, \delta v, e, \delta e) = (v', \delta v', e', \delta e') \in K^{TS'}$ as was claimed. ■
Note that the order of the terms in the tangent map $Tf$ resp. $T\hat{f}$ of an $sc^1$-map $f : O \to O'$ is different from the order of terms in the classical notation. Writing $f = (f_1, f_2)$ according to the splitting of the image space into the distinguished splicing parameter part and the standard part, the classical notation for the tangent map would be $Tf = ((f_1, f_2), (Df_1, Df_2))$ whereas our convention is $Tf = ((f_1, Df_1), (f_2, Df_2))$. This rather unorthodox ordering of the data has been chosen so that the tangent of a splicing is again a splicing.

The reader could work out as an example the situation where the splicings have the constant projection $Id$.

Theorem 3.6 (Chain Rule). Let $O, O', O''$ be open subsets of splicing cores and let the the maps $f : O \to O'$ and $g : O' \to O''$ be of class $sc^1$. Then the composition $g \circ f$ is also of class $sc^1$ and the tangent map satisfies

$$T(g \circ f) = Tg \circ Tf.$$ 

Proof. This is a consequence of the $sc$-chain rule (Theorem 2.16), the definition of the tangent map and the fact that our reordering of the terms in our definition (10) of the tangent map is consistent. Indeed, from Definition (10) we deduce

$$T(g \circ f)(v, \delta v, e, \delta e) = (T(\hat{g}_1 \circ \hat{f})(v, e, \delta v, \delta e), T(\hat{g}_2 \circ \hat{f})(v, e, \delta v, \delta e))$$

$$= ((T\hat{g}_1) \circ (T\hat{f})(v, e, \delta v, \delta e), (T\hat{g}_2) \circ (T\hat{f})(v, e, \delta v, \delta e))$$

$$= (Tg)(T\hat{f}_1(v, e, \delta v, \delta e), T\hat{f}_2(v, e, \delta v, \delta e))$$

$$= (Tg) \circ (Tf)(v, \delta v, e, \delta e)$$

and the proof is complete. ■

Given an $sc^1$-map $f : O \to O'$ between open sets of splicing cores we obtain, in view of Lemma 3.5 an induced tangent map $Tf : TO \to TO'$. Since $TO$ and $TO'$ are again open sets in the splicing cores $K^{TS}$ and $K^{TS'}$ we can iteratively define the notion of $f$ to be of class $sc^k$ and of $f$ to be $sc$-smooth.

Definition 3.7. Let $O$ be an open subset of a splicing core $K^S$ and $(v, e) \in O_1$. The tangent space to $O$ at the point $(v, e)$ is the Banach space
\[ T_{(v,e)}O = \{ (\delta v, \delta e) \in W \oplus E \mid (v, \delta v, e, \delta e) \in TO \}. \]  

(12)

We then have

\[ TO = \bigcup_{(v,e) \in O_1} T_{(v,e)}O. \]

If \( f : O \to O' \) is a homeomorphism so that \( f \) and \( f^{-1} \) are sc-smooth, our tangent map \( Tf \) defined in (10) induces the linear isomorphism

\[ Tf(v,e) : T_{(v,e)}O \to T_{f(v,e)}O'. \]

We recall from Section 3.1 that the space \( TO \) has a bi-filtration \((TO)_{(m,k)}\) for \( 0 \leq k \leq m \), so that the natural projection

\[ TO \to O_1 \]

maps level \((m,k)\) points to level \( m \) points and is sc-smooth. The projection map \( TO \to O_1 \) is sc-smooth.

### 3.3 M-Polyfolds

Now we are able to introduce the notion of an M-polyfold. The “M” indicates the “manifold flavor” of the polyfold. A general polyfold will be a generalization of an orbifold.

**Definition 3.8.** Let \( X \) be a second countable Hausdorff space. An M-polyfold chart for \( X \) is a triple \((U, \varphi, S)\), in which \( U \) is an open subset of \( X \), \( S = (\pi, E, V) \) an sc-smooth splicing and \( \varphi : U \to K^S \) a homeomorphism onto an open subset \( O \) of the splicing core \( K^S \) of \( S \). Two charts are called compatible if the transition maps between open subsets of splicing cores are sc-smooth in the sense of Definition 3.4. A maximal atlas of sc-smoothly compatible M-polyfold charts is called an M-polyfold structure on \( X \).

An M-polyfold is necessarily metrizable by an argument similar to the one used already for sc-manifolds. Each splicing core \( K^S \) carries the structure of an M-polyfold with the global chart being the identity.

The concept of a map \( f : X \to X' \) between M-polyfolds to be of class \( sc^0 \) or \( sc^k \) or to be sc-smooth is, as usual, defined by means of local charts.
Definition 3.9. The mapping \( f : X \to X' \) between two \( M \)-polyfolds is called of \textbf{class sc}^0 \ resp. \textbf{sc}^k \ or called \textbf{sc-smooth} \ if for every point \( x \in X \) there exists a chart \((U, \varphi, S)\) around \( x \) and a chart \((U', \varphi', S')\) around \( f(x) \) so that \( f(U) \subset U' \) and

\[
\varphi' \circ f \circ \varphi^{-1} : \varphi(U) \to \varphi'(U')
\]

is of class \textbf{sc}^0 \ resp. \textbf{sc}^k \ or \textbf{sc-smooth.}

In order to define the \textbf{tangent space} \( T_x X \) of the \( M \)-polyfold \( X \) at the point \( x \in X_1 \), we proceed as in the case of sc-manifolds in section 3.3. This time we consider equivalence classes of multiplets \((U, \varphi, S, x, h)\) in which \((U, \varphi, S)\) is an \( M \)-polyfold chart, \( x \) is a point in \( U_1 \) and \( h \in T_{\varphi(x)} O \), where \( O = \varphi(U) \subset K^S \) is the open set of the splicing core. The above multiplet is equivalent to \((U', \varphi', S', x', h')\) if \( x = x' \) and if \( T(\varphi' \circ \varphi^{-1})(\varphi(x)) h = h' \), where the tangent map

\[
T(\varphi' \circ \varphi^{-1})(\varphi(x)) : T_{\varphi(x)} O \to T_{\varphi'(x)} O'
\]

is defined in section 3.2. The tangent space is now defined as the set of equivalence classes

\[
T_x X = \{ [U, \varphi, S, x, h] | h \in T_{\varphi(x)} O \}.
\]

It inherits the structure of a Banach space from the tangent space \( T_{\varphi(x)} O \). If \( x \in X_{m+1} \), then \( T_x X \) possesses a partial filtration for \( 0 \leq k \leq m \) induced from the partial filtration of \( T_{\varphi(x)} O \). The tangent space at a smooth point \( x \in X_\infty \) possesses an \textbf{sc-smooth} structure.

Let now \( f : X \to X' \) be a map between \( M \)-polyfolds of class \textbf{sc}^k \ for \( k \geq 1 \). In two \( M \)-polyfold charts \((U, \varphi, S)\) and \((U', \varphi', S')\) around the points \( x \in U_1 \) and \( f(x) \in U'_1 \), the map \( f \) is represented by the \textbf{sc}^k-map \( \psi : \varphi' \circ f \circ \varphi^{-1} : O \to O' \) between open sets of splicing cores. The tangent map

\[
T\psi(x) : T_{\varphi(x)} O \to T_{\psi(x)} O'
\]

defines a unique continuous linear map

\[
T_x f : T_x X \to T_{f(x)} X'
\]

between the tangent spaces, called the \textbf{tangent map} of \( f \) at the point \( x \), mapping the equivalence class \([U, \varphi, S, x, h]\) into the class \([U', \varphi', S', f(x), h']\) in which

\[
h' = T(\varphi' \circ f \circ \varphi^{-1})(\varphi(x)) \cdot h.
\]
If $x$ is a smooth point of $X$ and if $f$ is an sc-smooth map, then the tangent map $T_x f$ is an sc-operator as defined in section 2.2.

Let us note the following useful result about sc-smooth partitions of unity.

**Theorem 3.10.** Let $X$ be an $M$-polyfold with local models being splicing cores build on sc-Hilbert spaces (An sc-Hilbert space consists of a Hilbert space equipped with an sc-structure. It is not required that the Banach spaces $E_m$ for $m \geq 1$ are Hilbert spaces.). Assume that $(U_\lambda)_{\lambda \in \Lambda}$ is an open covering of $X$. Then there exists a subordinate sc-smooth partition of unity $(\beta_\lambda)_{\lambda \in \Lambda}$.

The statement follows along the lines of a proof for Hilbert manifolds in [16]. The product $X \times Y$ of two $M$-polyfolds is in a natural way an $M$-polyfold. Indeed, if $(U, \phi, S)$ and $(W, \psi, T)$ are $M$-polyfold charts for $X$ and $Y$ respectively, one obtains the product chart $(U \times W, \phi \times \psi, S \times T)$ for $X \times Y$, with the **product splicing**

$$S \times T = (\pi, E, V) \times (\rho, F, V')$$

$$= (\sigma, E \oplus F, V \oplus V')$$

where $\sigma_{(v,v')} = \pi_v \oplus \rho_{v'}$ is the family of projections. There are several possible notions of sub-polyfolds (we suppress the $M$ in the notation). We shall describe one of them in Section 3.5 below and refer the reader to [8] for a comprehensive treatment.

### 3.4 Corners and Boundary Points

In this section we will prove the extremely important fact that sc-smooth maps are able to recognize corners. This will be crucial for the SFT because most of its algebraic structure is a consequence of the corner structure.

Let $X$ be a $M$-polyfold. Around a point $x \in X$ we take a $M$-polyfold chart $\varphi : U \rightarrow K^S$ where $K^S$ is the splicing core associated with the splicing $S = (\pi, E, V)$. Here $V$ is an open subset of a partial quadrant $C$ contained in the sc-Banach space $W$. By definition there exists a linear isomorphism from $W$ to $\mathbb{R}^n \oplus Q$ mapping $C$ onto $[0, \infty)^n \oplus Q$. Identifying the partial quadrant $C$ with $[0, \infty)^n \oplus Q$ we shall use the notation $\varphi = (\varphi_1, \varphi_2) \in [0, \infty)^n \oplus (Q \oplus E)$ according to the splitting of the target space of $\varphi$. We associate with the point $x \in U$ the integer $d(x)$ defined by

$$d(x) = \sharp\{\text{coordinates of } \varphi_1(x) \text{ which are equal to } 0\}.$$  (13)
Theorem 3.11. The map $d : X \to \mathbb{N}$ is well-defined and does not depend on the choice of the $M$-polyfold chart $\varphi : U \to K^S$. Moreover, every point $x \in X$ has an open neighborhood $U'$ satisfying

$$d(y) \leq d(x) \text{ for all } y \in U'.$$

Definition 3.12. The map $d : X \to \mathbb{N}$ is called the degeneracy index of $X$.

The map $d$ will play an important role in our Fredholm theory with operations presented in [12]. A point $x \in X$ satisfying $d(x) = 0$ is called an interior point. A point satisfying $d(x) = 1$ is called a good boundary point. A point with $d(x) \geq 2$ is called a corner. In general, the integer $d(x)$ is the order of the corner.

Proof of Theorem 3.11. Consider two $M$-polyfold charts $\varphi : \hat{U} \subset X \to K^S$ and $\varphi' : \hat{U}' \subset X \to K^{S'}$ such that $x \in \hat{U} \cap \hat{U}'$. Introducing the open subsets $U = \varphi(\hat{U} \cap \hat{U}')$ and $U' = \varphi'(\hat{U} \cap \hat{U}')$ of $K^S$ and $K^{S'}$ resp., and setting $\varphi(x) = (r, a)$ and $\varphi'(x) = (r', a')$ we define the sc-diffeomorphism $\Phi : U \to U'$ by $\Phi = \varphi' \circ \varphi^{-1}$. Obviously, $\Phi(r, a) = (r', a')$. Now the proof of Theorem 3.11 reduces to the following proposition.

Proposition 3.13. Let $S = (\pi, E, V)$ and $S' = (\pi', E', V')$ be two splicings having the parameter sets $V = [0, \infty)^k \oplus Q$ and $V' = [0, \infty)^{k'} \oplus Q'$. Assume that $U$ and $U'$ are open subsets of the splicing cores $K^S$ and $K^{S'}$ containing the points $(r, a)$ and $(r', a')$ with $r \in [0, \infty)^k$ and $r' \in [0, \infty)^{k'}$ and assume that the map

$$\Phi : U \to U'$$

is an sc-diffeomorphism mapping $(r, a)$ to $(r', a')$. Then $r$ and $r'$ have the same number of vanishing coordinates.

Proof. We first prove the assertion under the additional assumption that the point $p_0 = (r, a)$ belongs to $U_{\infty}$. Then the image point $q_0 = (r', a') = \Phi(p_0)$ belongs to $U'_{\infty}$. Denote by $J$ the subset of $\{1, \ldots, k\}$ consisting of those indices $j$ for which $r_j = 0$. Similarly, $j' \in J' \subset \{1, \ldots, k'\}$ if $r'_{j'} = 0$. Denoting by $|r|$ and $|r'|$ the cardinalities of $J$ and $J'$ we claim that $|r| \geq |r'|$. Since $\Phi$ is an sc-diffeomorphism it suffices to prove the inequality $|r| \geq |r'|$ since the inequality has to also hold true for the sc-diffeomorphism $\Phi^{-1}$. Write $a = (q, e)$. If $\pi_{(r, q)}(e) = e$, then differentiating $\pi_{(r, q)} \circ \pi_{(r, q)}(e) = \pi_{(r, q)}(e)$
in \((r, q)\) one finds \(\pi_{(r, q)} \circ D_{(r, q)}(\pi_{(r, q)}(e)) = 0\) so that \(D_{(r, q)}(\pi_r(e))(\delta r, \delta q)\) is contained in the range of \(\text{id} - \pi_{(r, q)}\). Therefore, given \((r, a) \in U\) satisfying \(\pi_{(r, q)}(e) = e\) and given \(\delta r \in \mathbb{R}^k\) and \(\delta q \in Q_\infty\), there exists \(\delta e \in E_\infty\) solving

\[
\delta e = \pi_{(r, q)}(\delta e) + D_{(r, q)}(\pi_{(r, q)}(e))[(\delta r, \delta q)].
\]

In particular, taking \(\delta r \in \mathbb{R}^k\) with \(\delta r)_j = 0\) for \(j \in J\), and a smooth \(\delta q\), there exists \(\delta e \in E_\infty\) solving the equation \((14)\). This is equivalent to \(((\delta r, \delta q), \delta e) \in (T_{(r,a)}U)_\infty\). Introduce the path

\[
\tau \mapsto p_\tau = (r + \tau \delta r, q + \tau \delta q, \pi_{(r + \tau \delta r, q + \tau \delta q)}(e + \tau \delta e))
\]

for \(|\tau| < \rho\) and \(\rho\) small. From \((r, a) \in U\) and \(\delta e \in E_\infty\) one concludes \(p_\tau \in U\). Moreover, considering \(\tau \to p_\tau\) as a map into \(U_m\) for \(m \geq 0\), its derivative at \(\tau = 0\) is equal to \((\delta r, \delta q, \delta e)\). Fix a level \(m \geq 1\) and consider for \(\rho > 0\) sufficiently small the map

\[
(-\rho, \rho) \to \mathbb{R}^{k'} \oplus Q'_m \oplus E'_m : \tau \to \Phi(p_\tau).
\]

The map \(\Phi : U \to U'\) is \(C^1\) as a map from \(U_{m+1} \subset \mathbb{R}^k \oplus Q_{m+1} \oplus E_{m+1}\) into \(\mathbb{R}^{k'} \oplus Q'_m \oplus E'_m\). Its derivative \(d\Phi(r, q, e) : \mathbb{R}^k \oplus Q_{m+1} \oplus E_{m+1} \to \mathbb{R}^{k'} \oplus Q'_m \oplus E'_m\) has an extension to the continuous linear operator \(D\Phi(r, q, e) : \mathbb{R}^k \oplus Q_m \oplus E_m \to \mathbb{R}^{k'} \oplus Q'_m \oplus E'_m\). Since \(\Phi\) is a sc-diffeomorphism the extension \(D\Phi(r, q, e) : \mathbb{R}^k \oplus Q_m \oplus E_m \to \mathbb{R}^{k'} \oplus Q'_m \oplus E'_m\) is a bijection. Thus, since \(\delta q \in Q_\infty\) and \(\delta e \in E_\infty\),

\[
\Phi(p_\tau) = \Phi(p_0) + \tau \cdot d\Phi(p_0)[\delta r, \delta q, \delta e] + o_m(\tau)
\]

\[
= g_0 + \tau \cdot D\Phi(p_0)[\delta r, \delta q, \delta e] + o_m(\tau)
\]

\[(15)\]

where \(o_m(\tau)\) is a function taking values in \(\mathbb{R}^{k'} \oplus Q'_k \oplus E'_m\) and satisfying \(\frac{1}{\tau} o_m(\tau) \to 0\) as \(\tau \to 0\). Introduce the sc-continuous linear functionals \(\lambda_{j'} : \mathbb{R}^{k'} \oplus Q' \oplus E' \to \mathbb{R}\) by

\[
\lambda_{j'}(s', q', h') = s'_{j'}
\]

where \(j' \in \{1, \ldots, k'\}\). Then

\[
\lambda_{j'} \circ \Phi(p_\tau) \geq 0
\]

for \(|\tau| < \rho\) and for \(j' \in \{1, \ldots, k'\}\). Applying for \(j' \in J'\) the functional \(\lambda_{j'}\) to both sides of \((13)\) and using that for \(j' \in J'\) we have \(\lambda_{j'}(\Phi(p_0)) = \lambda_{j'}(g_0) = 0\)
we conclude for $\tau > 0$

$$0 \leq \frac{1}{\tau} \lambda_j [\Phi(p_\tau)] = \frac{1}{\tau} \lambda_j [\Phi(p_0) + \tau \cdot D\Phi(p_0)[\delta r, \delta q, \delta e] + o_m(\tau)]$$

$$= \lambda_j [D\Phi(p_0)[\delta r, \delta q, \delta e]] + \lambda_j (\frac{o_m(\tau)}{\tau}).$$

Passing to the limit $\tau \rightarrow 0^+$ we find

$$0 \leq \lambda_j (D\Phi(p_0)[\delta r, \delta q, \delta e])$$

and replacing $(\delta r, \delta q, \delta e)$ by $(-\delta r, -\delta a, -\delta e)$ we obtain the equality sign. Consequently,

$$\lambda_j (D\Phi(p_0)[\delta r, \delta q, \delta e]) = 0, \quad j' \in J' \quad (16)$$

for all $[\delta r, \delta q, \delta e] \in \mathbb{R}^k + Q_\infty + E_\infty$ satisfying

$$\pi_{(r,q)}(\delta e) + D_{(r,q)}(\pi_{(r,q)}(e))(\delta r, \delta q) = \delta e$$

and $(\delta r)_j = 0$ for all $j \in J$. Introduce the codimension $\#r$ subspace $L$ of the tangent space $T_{(r,q,e)} U \subset K^TS$ which we may view as a subset of $\mathbb{R}^k + Q_\infty + E_\infty$ by

$$L = \{(\delta r, \delta q, \delta e) \in \mathbb{R}^k + Q_\infty + E_\infty | \pi_{(r,q)}(\delta e) + D_{(r,q)}(\pi_{(r,q)}(e))(\delta r, \delta q) = \delta e$$

and $(\delta r)_j = 0$ for all $j \in J \}$. Then, in view of $(16)$,

$$D\Phi(r, q, e)L \subset \{(\delta r', \delta q', \delta e')|\pi_{(r', q', e')}(\delta e') + D_{(r', q', e')}(\pi_{(r', q', e')}(e'))(\delta r', \delta q') = \delta e'$$

and $(\delta r')_j = 0$ for all $j' \in J' \}$. Because the subspace on the right hand side has codimension $\#r'$ in $T_{(r', q', e')}'U'$ and since $D\Phi(r, q, e)$, being a bijection, maps $L$ onto a codimension $\#r$ subspace of $T_{(r', q', e')}'U'$, it follows that $\#r' \leq \#r$, as claimed.

Next we shall prove the general case. For this we take $p_0 = (r, q, e)$ in $U_0$, so that the image point $(r', q', e') = \Phi(r, q, e)$ belongs to $U_0'$. Arguing by contradiction we may assume without loss of generality that $\#r > \#r'$, otherwise we replace $\Phi$ by $\Phi^{-1}$. Since $U_\infty$ is dense in $U_0$ we find a sequence $(r, q_n, e_n) \in U_\infty$ satisfying $\pi_{(r, q_n)}(e_n) = e_n$ and $(r, q_n, e_n) \rightarrow (r, q, e)$ in $U_0$. By the previous discussion $\#r = \#r_n'$ where $(r_n', q_n', e_n') = \Phi(r, q_n, e_n)$. Since $\Phi$ is sc-smooth, we have $(r_n', q_n', e_n') \rightarrow (r', q', e')$ in $U_0'$ and $\pi_{(r', q', e')} (e') = e'$. From this convergence we deduce $\#r' \geq \#r_n'$ so that $\#r' \geq \#r$ contradicting our assumption. The proof of Proposition 3.13 is complete. ■
To finish the proof of Theorem 3.11 it remains to show that the function $d$ is lower semicontinuous. Assume for the moment that there exists a sequence of points $x_k$ converging to $x$ so that $d(x_k) > d(x)$. Since $\varphi$ is continuous, we have the convergence $\varphi_1(x_k) = (r_1^k, \ldots, r_n^k, q^k) \to \varphi_1(x) = (r_1, \ldots, r_n, q)$. If for a given coordinate index $j$ the coordinate $r_j^k$ vanishes for all but finitely many $k$, then $r_j = 0$, and if $r_j^k > 0$ for all but finitely many $k$, then $r_j \geq 0$. Hence $d(x_k) \leq d(x)$ contradicting our assumption. The proof of Theorem 3.11 is complete.

**Definition 3.14.** The closure of a connected component of the set $X(1) = \{x \in X | d(x) = 1\}$ is called a **face** of the $M$-polyfold $X$.

Around every point $x_0 \in X$ there exists an open neighborhood $U = U(x_0)$ so that every $x \in U$ belongs to precisely $d(x)$ many faces of $U$. This is easily verified. Globally it is always true that $x \in X$ belongs to at most $d(x)$ many faces and the strict inequality is possible.

**Definition 3.15.** The $M$-polyfold $X$ is called **face structured**, if every point $x \in X$ belongs to precisely $d(x)$ many faces.

The concept is related to some notion occurring in [17].

If $X \times Y$ is a product of two $M$-polyfolds, then one concludes from the definition of the product structure the following relation between the degeneracy indices

$$d_{X \times Y}(x, y) = d_X(x) + d_Y(y).$$

### 3.5 Submanifolds

There are many different types of distinguished subsets of a $M$-polyfold which qualify as some kind of sub-polyfold. We refer the reader to [8] for a comprehensive discussion, where we introduced three different notions of a sub-polyfold. Among those one can find sub-polyfolds of locally constant finite dimensions. These occur as solution sets of nonlinear Fredholm operators. In this paper we only consider the latter and introduce the notion of a submanifold of a $M$-polyfold.

We consider two sc-smooth splicings

$$S = (\pi, E, V) \quad \text{and} \quad T = (\rho, F, V)$$
having projections \( \pi_v \) and \( \rho_v \) parametrized by the same open subset \( V \) of a partial quadrant. We define their **Whitney sum** to be the sc-smooth splicing

\[
S \oplus T = (\pi \oplus \rho, E \oplus F, V)
\]
defined by the family of projections

\[
(\pi \oplus \rho)_v(h \oplus k) = (\pi_v(h), \rho_v(k)), \quad v \in V.
\]  

One verifies readily that the splicing core \( K_{S \oplus T} \) is the fibered sum over \( V \) of the splicing cores \( K_S \) and \( K_T \),

\[
K_{S \oplus T} = K_S \oplus_V K_T = \{(v, h, k) \in V \oplus E \oplus F | \pi_v(h) = h \text{ and } \rho_v(k) = k\}.
\]  

**Definition 3.16.** The sc-smooth map \( f : X \to Y \) between two M-polyfolds is called a **fred-submersion** if at every point \( x_0 \in X \) resp. \( f(x_0) \in Y \) there exists a chart \( (U, \varphi, T \oplus \hat{T}) \) resp. \( (W, \psi, \mathcal{T}) \) satisfying \( f(U) \subset W \) and

\[
\psi \circ f \circ \varphi^{-1}(v, e, e') = (v, e')
\]
and, moreover, the splicing \( \hat{T} = (\hat{\rho}, E, V) \) has the special property that the projections \( \hat{\rho}_v \) do not depend on \( v \) and project onto a finite dimensional subspace of \( E \).

Instead of \( \hat{T} = (\hat{\rho}, E, V) \) we just may take the splicing \( (\text{Id}, \mathbb{R}^n, V) \) where \( n \) is the dimension of the image of the projection \( \pi \) and \( \text{Id} \) stands for the constant family \( v \to \text{Id} \). Hence we may assume that in the Whitney sum \( \mathcal{T} \oplus \hat{T} \) the latter summand has the special form and we will indicate that by writing

\[
\mathcal{T} \oplus \mathbb{R}^n.
\]

The following result will be used quite often.

**Proposition 3.17.** If \( f : X \to Y \) and \( g : Y \to Z \) are fred-submersions, then the composition \( g \circ f : X \to Z \) is again a fred-submersion.

**Proof.** Let \( y_0 = f(x_0) \) and \( z_0 = g(y_0) \). We find special charts \( \phi \) and \( \psi \) around \( x_0 \) and \( y_0 \), respectively, so that

\[
\psi \circ f \circ \phi^{-1}(v, e, e') = (v, e).
\]
Similarly, we find special charts $\alpha$ and $\beta$ so that
\[ \alpha \circ g \circ \beta^{-1}(w, h, h') = (w, h). \]

Define the inverse of a chart $\gamma$ around $x_0$ by
\[ \gamma^{-1}(w, h, h', e') = \phi^{-1}(\psi \circ \beta^{-1}(w, h, h'), e'). \]

Then we compute
\[
\begin{align*}
&\alpha \circ (g \circ f) \circ \gamma^{-1}(w, h, h', e') \\
&= \alpha \circ g \circ f \circ \phi^{-1}(\psi \circ \beta^{-1}(w, h, h'), e') \\
&= \alpha \circ g \circ \psi^{-1} \circ (\psi \circ f \circ \phi^{-1})(\psi \circ \beta^{-1}(w, h, h'), e') \\
&= \alpha \circ g \circ \psi^{-1} \circ (\psi \circ \beta^{-1}(w, h, h')) \\
&= \alpha \circ g \circ \beta^{-1}(w, h, h') \\
&= (w, h).
\end{align*}
\]

The splicings used for the charts involved are of the form $S$ and $S \oplus (\mathbb{R}^n \oplus \mathbb{R}^k)$. This completes the proof.

The preimages of smooth points under a fred-submersion carry in a natural way the structure of smooth manifolds.

**Proposition 3.18.** If $f : X \to Y$ is a fred-submersion between two M-polyfolds, then the preimage of a smooth point $y \in Y$,
\[ f^{-1}(y) \subset X, \]
carries in a natural way the structure of a finite dimensional smooth manifold.

**Proof.** We can define local charts induced from the charts of $X$ (exhibiting $f$ as a fred-submersion). They are defined on open subsets in $\mathbb{R}^n$. Here $n$ is locally constant, i.e. only depends on the connected components of $X$. The transition maps are sc-smooth and consequently smooth in the classical sense. In other words, there is a natural system of charts which define the structure of a smooth manifold on $f^{-1}(y)$. 

The above discussion prompts the following useful concept.

**Definition 3.19.** A subset $N \subset X$ of an $M$-polyfold $X$ is called a **finite-dimensional submanifold** of $X$ if the following statements hold true.
(i) \( N \subset X_\infty \).

(ii) For every point \( m \in N \) there exists an open neighborhood \( U \subset X \) of \( m \), and an \( M \)-polyfold \( Y \), and a surjective Fred-submersion \( f : U \to Y \) satisfying

\[
 f^{-1}(f(m)) = N \cap U.
\]

4 M-Polyfold Bundles

In this section we continue with the conceptual framework. First we describe the local models for strong \( M \)-polyfold bundles and smooth maps between them. Then we introduce the notion of a strong \( M \)-polyfold bundle.

4.1 Local Strong M-Polyfold Bundles

In this subsection we shall introduce the local models for strong bundles over \( M \)-polyfolds. For this we need a generalization of the notion of splicing where the splicing projection is parameterized by an open subset of a splicing core. We begin by introducing these more general splicing definitions.

**Definition 4.1.** A **general sc-smooth splicing** is a triple

\[
 R = (\rho, F, (O, S)),
\]

where \((O, S)\) is a local \( M \)-polyfold model associated with the sc-smooth splicing \( S = (\pi, E, V) \) and \( O \) is an open subset of the splicing core \( K^S = \{(v, e) \in V \oplus E | \pi_v(e) = e\} \). The space \( F \) is an sc-smooth Banach space and the mapping

\[
 \rho : O \oplus F \to F
\]

\[
 ((v, e), u) \mapsto \rho(v, e, u)
\]

is sc-smooth. Finally, for fixed \((v, e) \in O\), the mapping

\[
 \rho_{(v,e)} = \rho(v, e, \cdot) : F \to F
\]

is a projection. Sc-smoothness of \( \rho \), of course, means that the map

\[
 (v, e, u) \to \rho(v, \pi_v(e), u),
\]

which is defined on an open subset \( \hat{O} \) of a partial quadrant in a sc-Banach space, is sc-smooth.
The novelty of this definition consists in the requirement, that the family of projections is parameterized by elements of an open subset of a splicing core. The definition of the tangent of a general splicing \( R = (\rho, F, (O, S)) \) is defined, quite similarly as in the case of a splicing, by

\[
T R = (T \rho, TF, (TO, TS)),
\]

which is again a general sc-smooth splicing. The map \( T \rho : TO \oplus TF \to TF \) is a family of projections acting on \( TF \) and parameterized by the tangent \( TO \) of \( O \). It is defined by

\[
T \rho(w, \delta w, u, \delta u) = (\rho(w, u), D \rho(w, u)(\delta w, \delta u)).
\]

Here \( w = (v, e) \in O_1 \subset V_1 \oplus E_1 \) and \( \delta w \in W \oplus E \) so that \( (w, \delta w) \in TO \) and \( (u, \delta u) \in F^1 \oplus F = TF \). Keeping \( (w, \delta w) \in TO \) fixed, the map

\[
T \rho_{(w, \delta w)} : TF \to TF
\]

is a projection in \( L(F_1 \oplus F) \).

Next we introduce the notion of a strong bundle splicing.

**Definition 4.2.** A **strong bundle splicing** is a general sc-smooth splicing

\[
R = (\rho, F, (O, S))
\]

having the following additional property. If \( (v, e) \in O_m \) and \( u \in F_{m+1} \), then \( \rho((v, e), u) \in F_{m+1} \) and the newly defined triple

\[
R^1 = (\rho, F^1, (O, S))
\]

is also a general sc-smooth splicing. If we view the strong bundle splicing \( R \) only as a general smooth splicing we denote it by \( R^0 \).

Let us note that the complementary splicing \( R^c \) is a strong bundle splicing as well. From the above definition we conclude, in particular, that a strong bundle splicing \( R \) gives rise to two general sc-smooth splicings, namely \( R^0 \) and \( R^1 \).

There is a non-symmetric product \( E \triangleright F \) of two sc-Banach spaces \( E \) and \( F \). This product is the Banach space \( E \oplus F \) equipped, however, with the bi-filtration defined by

\[
(E \triangleright F)_{m,k} = E_m \oplus F_k
\]
for pairs \((m, k)\) satisfying \(m \geq 0\) and \(0 \leq k \leq m + 1\). For a subset \(U \subset E\) we can define \(U \triangleleft F\) in the obvious way.

The splicing core \(K^\mathcal{R}\) of the strong bundle splicing \(\mathcal{R} = (\rho, F, (O, \mathcal{S}))\) is the set

\[
K^\mathcal{R} = \{(w, u) \in O \oplus F \mid \rho(w, u) = u\}.
\]

Since \(\mathcal{R}\) gives us two general splicings \(\mathcal{R}^0\) and \(\mathcal{R}^1\) we have a well-defined bi-filtration on \(K^\mathcal{R}\) by pairs \((m, k)\) satisfying \(0 \leq k \leq m + 1\) so that \(K^\mathcal{R}\) can be viewed as a subset of \((V \oplus E) \triangleleft F\) equipped with the induced bi-filtration. More precisely,

\[
K^\mathcal{R}_{m,k} = \{(w, u) \in K^\mathcal{R} \mid w \in O_m, u \in F_k\}
\]

where \(m \geq 0\) and \(0 \leq k \leq m + 1\). The bundle

\[
K^\mathcal{R} \to O
\]

defined by means of the strong bundle splicing \(\mathcal{R}\) is called a local strong bundle. It will serve as our local model of the strong M-polyfold bundles introduced in the next subsection.

**Remark 4.3.** There is a special case which we already shortly mentioned before. Assume the strong bundle splicing \(\mathcal{R}\) has the special form

\[
\mathcal{R} = (\text{Id}, F, (O, \mathcal{S})),
\]

where \(\mathcal{S} = (\text{Id}, E, V)\) and \(O\) is a relatively open subset of \(V \oplus E\). In that case

\[
K^\mathcal{R} = O \triangleleft F
\]

and we can view \(O\) as a local model for an sc-manifold and \(O \triangleleft F\) as a local model for a strong sc-bundle with base \(O\).

Associated with the strong bundle splicing \(\mathcal{R}\) we have the splicing cores \(K^\mathcal{R}_0\) and \(K^\mathcal{R}_1\), which we denote by \(K^\mathcal{R}(0)\) and \(K^\mathcal{R}(1)\), respectively. They are equipped with the filtrations

\[
K^\mathcal{R}(0)_m = K^\mathcal{R}_{m,m} \quad \text{and} \quad K^\mathcal{R}(1)_m = K^\mathcal{R}_{m,m+1}.
\]

The natural projection \(K^\mathcal{R} \to O : (w, u) \to u\) is sc-smooth in the sense that the two projections

\[
K^\mathcal{R}(i) \to O
\]
are sc-smooth for $i = 0, 1$.

We can define the tangent $T\mathcal{R}$ of the strong bundle splicing

$$\mathcal{R} = (\rho, F, (O, S))$$

as follows. First we consider the underlying strong bundle splicing $\mathcal{R}^0$ and take the associated tangent splicing $T\mathcal{R}^0$,

$$T\mathcal{R}^0 = (T\rho, TF, (TO, TS)).$$

Since we also have the splicing $\mathcal{R}^1$, we also can take its tangent $T\mathcal{R}^1$ given by

$$T\mathcal{R}^1 = (T\rho, T(F^1), (TO, TS)).$$

From $T(F^1) = (TF)^1$ we conclude that

$$T\mathcal{R} = (T\rho, TF, (TO, TS))$$

is again a strong bundle splicing in the sense of Definition 4. Its splicing core $K^{T\mathcal{R}}$ is, as usual, defined by

$$K^{T\mathcal{R}} = \{(w, \delta w, u, \delta u) \in TO \oplus TF \mid T\rho(w, \delta w, u, \delta u) = (u, \delta u)\}.$$

More explicitly, the elements of $K^{T\mathcal{R}}$ are restricted by the following equations for $w = (v, e) \in O_1 \oplus E_1$ and $\delta w = (\delta v, \delta e) \in W \oplus E$ so that $(w, \delta w) \in TO$ and for $(u, \delta u) \in TF$,

$$\pi(v, e) = e$$

$$\rho(w, u) = u$$

$$\delta e = \pi(v, \delta e) + D_v\pi(v, e)\delta v$$

$$\delta u = \rho(w, \delta u) + D_w\rho(w, u)\delta w.$$ 

Let us observe that for $i = 0, 1$ the following relationships hold for the underlying general sc-smooth splicings

$$(TK^{\mathcal{R}})(i) = K^{T\mathcal{R}}(i) = K^{T(\mathcal{R}^i)} = T(K^\mathcal{R}(i)).$$

Next we shall define the concept of an sc$^k$-map between splicing cores of strong bundle splicings. Recall the Definition 3.4 for the sc$^1$-class of mappings between open subsets of splicing cores.
**Definition 4.4.** If $\mathcal{R} = (\rho, F, (O, S))$ and $\mathcal{R}' = (\rho', F', (O', S'))$ are two strong bundle splicings we denote the associated splicing cores by $K = K^{\mathcal{R}} \subset O \oplus F$ and $K' = K'^{\mathcal{R}'} \subset O' \oplus F'$. Consider a map

$$f : K \to K'$$

of the form

$$f(w, u) = (\varphi(w), \Phi(w, u)),$$

where $\varphi : O \to O'$ and where $\Phi : O \oplus F \to F'$. Then

- The map $f$ is an $\text{sc}_0$-map if it induces $\text{sc}_0$-maps $K(i) \to K'(i)$ for $i = 0$ and $i = 1$.
- The map $f$ is called of class $\text{sc}_1$ if it is $\text{sc}_0$ and if it induces $\text{sc}_1$-maps $K(i) \to K'(i)$ for $i = 0$ and $i = 1$.

In many cases we require $\Phi$ to be linear in $u$. In particular, this is the case when $\Phi$ occurs as an isomorphism between local strong $M$-polyfold bundles.

Next we consider maps $f : K \to K'$ between splicing cores of strong bundle splicings of the form as in Definition 4.4. In order to define maps $f : K \to K'$ of class $\text{sc}_3$ we proceed as in the sc-case. Assuming that $f$ is of class $\text{sc}_1$ we consider it first as an $\text{sc}_1$-map

$$f : K(0) \to K'(0)$$

between splicing cores. Its tangent map $Tf$ is described by the formula

$$Tf(w, \delta w, u, \delta u) = (\phi(w), D\phi(w)\delta w, \Phi(w, u), D\Phi(u, w)(\delta w, \delta u))$$

Since $f$ is also an $\text{sc}_1$-map

$$f : K(1) \to K'(1)$$

the tangent formula above defines two maps

$$Tf : TK^{\mathcal{R}}(i) = K'^{\mathcal{R}'i} \to TK'^{\mathcal{R}'}(i) = K'^{\mathcal{R}'i}$$

for $i = 0, 1$ which are $\text{sc}_0$-continuous. Therefore they define a map

$$Tf : TK^{\mathcal{R}} \to TK'^{\mathcal{R}'}$$

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between splicing cores of strong bundle splicings which is of class $sc^0_\omega$. It is called the \textbf{tangent map} of the $sc^1_\omega$-map $f$.

If this tangent map $Tf$ is of class $sc^1_\omega$ as defined above, then the map $f : K \rightarrow K'$ is called of class $sc^2_\omega$. Proceeding inductively as in the $sc$-case one defines the mappings $f : K \rightarrow K'$ of class $sc^k_\omega$ for $k \geq 1$ and also the $sc_\omega$-smooth mappings. Let us finally note that the chain rule also holds for strong bundle maps.

**Theorem 4.5.** Let $f : K|O \rightarrow K'$ and $g : K'|O' \rightarrow K''$ be two $sc^1_\omega$-maps between local strong bundles so that the image of $f$ is contained in the domain of $g$. Then the composition $g \circ f$ is of class $sc^1_\omega$ and the tangent maps satisfy

$$T(g \circ f) = Tg \circ Tf.$$ 

A note of caution! As before the order of terms in the tangent map $Tf$ of a $sc^1_\omega$-map is different from their order in the classical theory.

Associated with the strong bundle splicing $\mathcal{R}$ we have the local strong bundle $p : K \rightarrow O$. A $sc$-smooth section of the bundle $p$ is just an $sc$-smooth section of the underlying bundle $K(0) \rightarrow O$. The vector space of $sc$-smooth sections is denoted by $\Gamma(p)$. In addition, there is a different class of sections called $sc^+$-sections. An $sc$-smooth section $f$ is called a $sc^+$-section if it defines an $sc$-smooth section of the bundle $K(1) \rightarrow O$. We denote the collection of $sc^+$-sections by $\Gamma^+(p)$.

### 4.2 Fillability and Fillers

Considering the local strong bundle $p : K^\mathcal{R} \rightarrow O$ associated with a strong bundle splicing $\mathcal{R}$, we investigate the coherence in the jumps of the space dimensions in the base and the fibers.

We start with a strong bundle splicing $\mathcal{R} = (\rho, F, (O, \mathcal{S}))$. The splicing $\mathcal{S}$ is the triple $(\pi, E, V)$ in which $V$ is an open subset of a partial quadrant $C$ contained in the $sc$-Banach space $W$. The set $O$ is an open neighborhood of the origin in the splicing core $K^\mathcal{S} = \{(v, e) \in V \oplus E | \pi_v(e) = e\}$. If

$$s : O \rightarrow V$$

is the $sc$-smooth map defined by $s(v, e) = v$, we shall abbreviate by $s^* \pi : O \times E \rightarrow E$ the composition $s^* \pi(v, e, u) = \pi(s(v, e), u) = \pi(v, u)$ and introduce the general $sc$-smooth splicing $s^* \mathcal{S}^c$, having the splicing parameter set $O$, by

$$s^* \mathcal{S}^c = (1 - s^* \pi, E, O).$$
Its splicing core is the set
\[ K^{s^*S^c} = \{(v, e, u) \in O \oplus E | \pi_{s(v,e)}(u) = 0\} \]
\[ = \{(v, e, u) \in V \oplus E \oplus E | (v, e) \in O, \pi_v(e) = e and (1 - \pi_v)(u) = u\}. \]

In view of the splitting \( E = \pi_v(E) \oplus (1 - \pi_v)(E) \), the splicing core \( K^{s^*S^c} \) can be naturally identified with the following open subset \( \hat{O} \) of \( V \oplus E \),
\[ \hat{O} = \{(v, e) \in V \oplus E | (v, \pi_v(e)) \in O\}. \]

We have the natural projection
\[ a : K^{s^*S^c} \rightarrow O, \quad (v, w) \rightarrow (v, \pi_v(w)) \]
and we can view \( a : K^{s^*S^c} \rightarrow O \) as a bundle (of course, not as a strong bundle). The fiber \( a^{-1}(v, e) \) over the point \((v, e) \in O\) is the Banach space
\[ a^{-1}(v, e) = \{(v, e + w) | w \in E, \pi_v(w) = 0\} \]
\[ = \{(v, e)\} \times \ker(\pi_v). \]

The strong bundle splicing \( \mathcal{R} \) comes together with its complementary strong bundle splicing \( \mathcal{R}^c = (1 - \rho, F, (O, S)) \) giving rise to the local strong bundle \( b : K^{\mathcal{R}^c} \rightarrow O \). We are interested only in the underlying bundle
\[ b : K^{\mathcal{R}^c}(0) \rightarrow O \]
associated with the general sc-smooth splicing \( (\mathcal{R}^c)^0 \).

The following concept of a filler turns out to be very useful in the applications.

**Definition 4.6.** Let \( \mathcal{R} \) be a strong bundle splicing and \( \mathcal{R}^c \) the associated complementary strong bundle splicing. Consider the two bundles over \( O \)
\[ a : K^{s^*S^c} \rightarrow O \quad \text{and} \quad b : K^{\mathcal{R}^c}(0) \rightarrow O. \]

Then a **filler** for \( \mathcal{R} \) is an sc-diffeomorphism
\[ f^c : K^{s^*S^c} \rightarrow K^{\mathcal{R}^c}(0) \]
between the complementary bundle pairs, which is linear in the fibers and covers the identity map \( O \rightarrow O \). (It is, in particular, a bundle bundle isomorphism).
**Definition 4.7.** The strong bundle splicing \( \mathcal{R} \) is **fillable** if there exists a filler for \( \mathcal{R} \).

Being fillable is a property of the strong bundle splicing \( \mathcal{R} \).

A filler \( f^c : K^s \ast S^c \rightarrow K^{\mathcal{R}^c}(0) \) has the the form

\[
f^c : (v, e, u) \rightarrow (v, e, f^c(v, e, u))
\]

where \((v, e) \in O\) and where \(u \in E\) satisfies \(\pi_v(u) = 0\). The principal part \(f^c(v, e, u) \in F\) satisfies \(\rho_{(v,e)}(f^c(v, e, u)) = 0\). In view of the identity \(e = \pi_v(e) + (1 - \pi_v)(e)\) in \(E\), the principal part \(f^c\) can be viewed as an sc-smooth map

\[
\hat{O} \rightarrow F, \quad (v, e) \rightarrow f^c(v, e)
\]

satisfying \(\rho_{(v,\pi_v(e))}(f^c(v, e)) = 0\).

### 4.3 Strong M-Polyfold Bundles

In order to introduce strong M-polyfold bundles we consider a surjective sc-smooth map

\(p : Y \rightarrow X\)

between two M-polyfolds. We assume in addition that for every \(x \in X\), the preimage \(p^{-1}(x) = Y_x\), called the fiber over \(x\), carries the structure of a Banach space.

**Definition 4.8.** Let \(p : Y \rightarrow X\) be as just described. A **strong M-polyfold bundle chart** for the bundle \(p : Y \rightarrow X\) is a triple \((U, \Phi, (K^{\mathcal{R}}, \mathcal{R}))\).

Here \(U \subset X\) is an open set and \(\mathcal{R} = (\rho, F, (O, S))\) a strong bundle splicing with the local model \((O, S)\) of the polyfold \(X\). The map \(\Phi\) is an sc-diffeomorphism

\[
\Phi : p^{-1}(U) \rightarrow K^{\mathcal{R}}
\]

which is linear on the fibers and covers the sc-diffeomorphism

\[
\varphi : U \rightarrow O
\]

so that \(\text{pr}_1 \circ \Phi = \varphi \circ p\). Moreover, the map \(\Phi\) resp. \(\varphi\) are smoothly compatible with the M-polyfold structures on \(Y\) and \(X\), respectively.
Recall that \( S = (\pi,E,V) \) is an sc-smooth splicing where \( V \) is an open subset of a partial quadrant in an sc-smooth Banach space \( W \). The set \( O \) is an open subset of the splicing core \( K^S = \{w = (v,e) \in V \oplus E | \pi(v,e) = e\} \) while the splicing core \( K^R \) over the base \( O \) is defined by \( K^R = \{(w,u) \in O \oplus F | \rho(w,u) = u\} \) where \( F \) is an sc-smooth Banach space.

**Definition 4.9.** Two M-polybundle charts \((\Phi,\varphi)\) and \((\Psi,\psi)\) are called **sc\textsubscript{c}\textsuperscript{-}compatible**, if the transition map

\[
\Psi \circ \Phi^{-1} : K^R|\varphi(U \cap U') \to K^{R'}|\psi(U \cap U')
\]

between their splicing cores \( K^R \) and \( K^{R'} \) are sc\textsubscript{c}\textsuperscript{-}smooth.

An **M-polybundle atlas** consists of a family of M-polybundle charts \((U,\Phi,(K^R,R))\) so that the underlying open sets \( U \) cover \( X \) and so that the transition maps are sc\textsubscript{c}\textsuperscript{-}smooth. A maximal smooth atlas of M-polybundle charts is called an **M-polybundle structure** and the bundle

\[
p : Y \to X
\]

is called a **strong M-polyfold bundle**.

**Definition 4.10.** A strong M-polyfold bundle \( p : Y \to X \) is called **fillable** if around every point \( q \in X \), there exists a compatible strong M-polyfold bundle chart \((U,\Phi,(K^R,R))\) whose strong bundle splicing \( R \) is fillable.

As it turns out all strong bundles occurring in the applications we have in mind have this property.

Note that the tangent bundle \( TX \to X^1 \) in general is not a strong M-polyfold bundle.

Given the strong polyfold bundle \( p : Z \to X \) having the base \( X \) and the sc-smooth map \( f : Y \to X \) between M-polyfolds one defines the (algebraic)
pullback (or induced) bundle

\[ p': f^*Z \to Y \]

having the base \( Y \) as follows. One takes the set \( f^*Z = \{(y, z) \in Y \times Z \mid p(z) = f(y)\} \) and the two projection maps \( p'(y, z) = y \) and \( f'(y, z) = z \), so that the diagram

\[ \begin{array}{ccc}
  f^*Z & \xrightarrow{f'} & Z \\
  \downarrow{p'} & & \downarrow{p} \\
  Y & \xrightarrow{f} & X
\end{array} \]

commutes.

**Proposition 4.11.** If \( p: Z \to X \) is a strong M-polyfold bundle and \( f: Y \to X \) is an sc-smooth map between M-polyfolds, then the pullback bundle \( p': f^*Z \to Y \) carries a natural induced structure of a strong M-polyfold bundle whose base is the M-polyfold \( Y \).

*Proof.* Choose a point \((y_0, z_0) \in f^*Z\) so that \( f(y_0) = p(z_0) = x_0 \in X\). Take a strong M-polyfold bundle chart for \( p: Z \to X \) denoted by \((U, \Phi, (K^R, R))\),

\[ \begin{array}{ccc}
  p^{-1}(U) & \xrightarrow{\Phi} & K^R \\
  \downarrow{p} & & \downarrow{pr_1} \\
  U & \xrightarrow{\varphi} & O,
\end{array} \]

so that the open set \( U \subset X \) contains the point \( x_0 \). The strong bundle splicing \( R = (\rho, F, (O, S)) \) is associated with the local model \((O, S)\) of the polyfold \( X \), where \( O \) is an open subset of the splicing core \( K^S \) of the splicing \( S = (\pi, E, V) \). Take now an M-polyfold chart \( \psi: U' \to O' \) around the given point \( y_0 \in U' \in Y \), associated with the local model \((O', S')\) of the M-polyfold \( Y \), where \( O' \subset K^S' \) is an open subset of the splicing core of the sc-smooth splicing \( S' = (\pi', E', V') \). Choose \( U' \subset Y \) so small that \( f(U') \subset U \). Define the strong bundle splicing \( R' = (\rho', F, (O', S')) \) by means of the sc-smooth map \( \rho': O' \oplus F \to F \) given as

\[ \rho'(v', u) := \rho(\varphi \circ f \circ \psi^{-1}(v'), u). \]
The strong M-polyfold bundle chart for the bundle $p' : f^*Z \to Y$ is now the triple $(U', \Psi, (K^{R'}, R'))$ with the homeomorphism
\[ \Psi : f^*Z|U' \to K^{R'}|O' \]
defined as
\[ \Psi(p'^{-1}(y)) = \Phi(p^{-1}(f(y))), \]
for all $y \in U' \subset Y$. We have the diagram
\[
\begin{array}{ccc}
p'^{-1}(U') & \xrightarrow{\Psi} & K^{R'} \\
\downarrow p' & & \downarrow \text{pr}_1 \\
U' & \xrightarrow{\varphi} & O'.
\end{array}
\]

One can verify that the transition maps between two such strong M-polyfold bundle charts are $\text{sc}_\omega$-smooth. This finishes the proof of Proposition 4.11.

### 4.4 Sections and Linearizations

Assume that $p : Y \to X$ is a strong M-polyfold bundle over the M-polyfold $X$. We denote the space of $\text{sc}$-smooth sections by $\Gamma(p)$. In addition there is the distinguished space of $\text{sc}^+$-sections which we denote by $\Gamma^+(p)$.

The section $f$ is an $\text{sc}^+$-section if its local representations in the strong $M$-polyfold bundle charts are $\text{sc}^+$-sections as defined at the end of section 4.4 above. If $(U, \Phi, (K^R, R))$ is such a strong $M$-polyfold bundle chart, the local representation of the section $f$ of the bundle $p : Y \to X$ is the section $g$ of the strong local bundle $K^R \to O$ defined as the push-forward of $f$ by
\[ g(w) = \Phi \circ f \circ \varphi^{-1}(w), \]
where $w \in O$. By definition, the map $\Phi : p^{-1}(U) \to K^R$ is an $\text{sc}$-diffeomorphism which is linear in the fibers and which covers the $\text{sc}$-diffeomorphism $\varphi : U \to O$ where $O$ is an open subset of the splicing core $K^S = \{(v, e)| \pi_v(e) = e\}$ belonging to the splicing $S = (\pi, E, V)$. Associated with the strong bundle splicing $R = (\rho, F, (O, S))$ we have the splicing core $K^R = \{(w, u) \in O \oplus F| \rho(w, u) = u\}$.

Next we choose a smooth point $q \in X$. Generalizing a trivial classical fact for vector bundles we can identify naturally the tangent space $T_{0q}Y$ at the
zero element \(0_q = \Phi^{-1}(\varphi(q), 0_F)\) with the sc-Banach space \(T_qX \oplus Y_q\) where \(Y_q = p^{-1}(q)\) is the fiber. Since \(q\) is a smooth point we may assume in the following that \(\varphi(q) \in O\) is equal to 0, so that \(\Phi(0_q) = (0, 0) \in K^R \subset O \oplus F\). The identification \(T_{0_q}Y \hookrightarrow T_qX \oplus Y_q\) corresponds in the local coordinates to the identification

\[
(0, \delta w, 0, \delta u) \leftrightarrow ((0, \delta w), (0, \delta u))
\]

of the elements in the tangent space \(T_{(0,0)}K^R \subset TO \oplus TF\). We shall denote by \(P_q : T_qY \simeq T_qX \oplus Y_q \to Y_q\) the projection.

Given a section \(f \in \Gamma(p)\) which vanishes at the smooth point \(q \in X\) we define, following the classical recipe, the linearization \(f'(q)\) by

\[
f'(q) : T_qX \to Y_q : h \to P_q \circ T(f(q))h.
\]

As in the case of vector bundles there is generally not an intrinsic notion of a linearization of a section at an arbitrary point \(q\) for which \(f(q)\) does not vanish. In our case with \(Y \to X\) being a strong bundle we have, however, some additional structure. This will allow us to define a linearization at an arbitrary smooth point which is unique up to a linear sc\(^+\)-operator.

In order to see this, we consider the sc-smooth section \(f \in \Gamma(p)\) and look at the smooth point \(q \in X\). Its image \(y = f(q)\) is a smooth point in \(Y\) and we claim that there exists an sc\(^+\)-section \(s\) defined near \(q\) and satisfying \(s(q) = f(q)\).

Indeed, if the coordinate representation of the section \(f\) is given by \(g(w) = (w, g(w))\) and if \(q\) corresponds to \(w_0\), then \(g(w_0)\) is a smooth point in the sc-Banach space \(F\) satisfying \(\rho(w_0, g(w_0)) = g(w_0)\). Now define in the local coordinates the section \(s\) by \(s(w) = (w, \rho(w, g(w_0)))\). It satisfies \(s(w_0) = g(w_0)\) and is indeed an sc\(^+\)-section because the projections \(\rho\) belong to a strong bundle splicing as defined in Definition 4.2.

Now take any sc\(^+\)-section \(s\) of the bundle \(Y \to X\) defined near \(q\) and satisfying \(s(q) = f(q)\). Then the section \(f - s\) is defined near \(q\) and vanishes at \(q\). We define the linearization \(f'_s(q)\) by

\[
f'_s(q) : T_qX \to Y_q : h \to P_q \circ T(f - s)(q)h.
\]

Next we investigate to what extend \(f'_s(q)\) depends on the choice of \(s\). Assume therefore that \(s\) and \(t\) are sc\(^+\)-sections defined near \(q\) and satisfying \(s(q) =
\( t(q) = f(q) \). Then, by definition,

\[
  f'_s(q) = P_q \circ T(f - s)(q) \\
  = P_q \circ T(f - t + (t - s))(q) \\
  = P_q \circ T(f - t)(q) + P_q \circ T(t - s)(q) \\
  = f'_i(q) + P_q \circ T(t - s)(q).
\]

It remains to understand the perturbation term \( P_q \circ T(t - s)(q) \). For this we observe that it suffices to understand \( P_q \circ Ts(q) \) for an \( \text{sc}^+ \)-section \( s \) defined in a neighborhood \( U \subset X \) of \( q \) and vanishing at \( q \). Since \( s \) is an \( \text{sc}^+ \)-section of the bundle \( p : Y|U \to U \) its tangent \( Ts \) is an \( \text{sc}^+ \)-section of \( Tp : T(Y|U) \to TU \). Hence the composition

\[
P_q \circ Ts(q) : T_q X \to Y_q
\]

which in local coordinates is given by

\[
(0, \delta w) \to (0, \delta w, 0, Ds(0)\delta w) \to (0, Ds(0)\delta w)
\]

is an \( \text{sc}^+ \)-operator.

**Definition 4.12.** Let \([f, q]\) be the germ of a section \( f \) of the strong bundle \( p : Y \to X \) around the smooth point \( q \). Let \([s]\) be a germ of a \( \text{sc}^+ \)-section around \( q \) which satisfies \( s(q) = f(q) \). Then the linearization of \([f, q]\) with respect to \([s]\) is defined by

\[
f'_{[s]}(q) = P_q \circ T(f - s)(q).
\]

The above discussion is now summarized in the following proposition.

**Proposition 4.13.** Let \([f, q]\) be an \( \text{sc-smooth} \) section germ of the bundle \( p : Y \to X \) near a smooth point \( q \). Then two linearizations \( f'_{[s]}(q) \) and \( f'_{[t]}(q) \) differ by a \( \text{sc}^+ \)-operator. In particular, if one linearization is \( \text{sc-Fredholm} \) so are all others.

The last statement follows from Proposition 2.11. This allows us to introduce the following definition.

**Definition 4.14.** An \( \text{sc-smooth} \) section of the strong \( M\)-polyfold bundle \( p : Y \to X \) is linearized Fredholm at the smooth point \( q \) provided a linearization at the point \( q \) is \( \text{sc-Fredholm} \). We say \( f \) is linearized Fredholm if this holds at all smooth points \( q \).
If \( f \) is linearized Fredholm and \( q \) a smooth point, we define the index
\[
\text{Ind}(f, q) \in \mathbb{Z}
\]
by
\[
\text{Ind}(f, q) := i(f'_s(q)).
\]
In view of Proposition 4.13 this is well-defined. Here \( i \) denotes the Fredholm index.

Another consequence of the previous discussion is the following.

**Proposition 4.15.** Assume that \( p : Y \to X \) is a strong \( M \)-polyfold bundle and \( f \in \Gamma(p) \) an sc-smooth section which is linearized Fredholm. Then the section \( f + s \) for any sc\(^+\)-section in \( \Gamma^+(p) \) is linearized Fredholm.

If a strong \( M \)-polyfold bundle \( p : Y \to X \) is fillable one can construct for every sc-smooth section \( f \) near a smooth point \( q \in X \) a filled section. This will be important for the Fredholm theory developed in [10]. To carry out this construction we assume that \( f \) is an sc-smooth section of the bundle \( p : Y \to X \) and \( q \in X_\infty \). We pick a fillable strong bundle coordinate
\[
\Phi : Y|U \to K^R
\]
defined on an open neighborhood \( U \) of \( q \) and covering the sc-diffeomorphism \( \varphi : U \to O \). Let
\[
f^c : K^{s^*S^e} \to K^{R^e}(0)
\]
be a filler for the strong bundle splicing \( R = (\rho, F, (O, (\pi, E, V))) \). The principal part of \( f^c \) gives us a sc-smooth map
\[
f^c : \hat{O} \to F : (v, e) \to f^c(v, e)
\]
satisfying \( \rho_{(v, \pi_v(e))}(f^c(v, e)) = 0 \). Recall that \( \hat{O} \) stands for the open subset of \( V \oplus E \) defined by \( \hat{O} = \{(v, e) \in V \oplus E | (v, \pi_v(e)) \in O \} \). The push-forward of \( \Phi_*f \) is a section of the local strong bundle \( K^R \to O \). Its principal part has a natural extension to the open set \( \hat{O} \) which we denote by \( f \). It satisfies
\[
\rho_{(v, \pi_v(e))}(f(v, e)) = f(v, e).
\]
Finally, we introduce the sc-smooth map \( \overline{f} : \hat{O} \to F \) by
\[
\overline{f}(v, e) = f(v, e) + f^c(v, e).
\]
which can be viewed as the principal part of an sc-smooth section \( \overline{f} \) of the bundle \( \hat{O} \circ F \to \hat{O} \).
**Definition 4.16.** The section $\bar{f}$ is called a filled version of $f$ near $q$ and $\overline{f}$ is called its principal part, i.e.

$$\overline{f}(v,e) = ((v,e), \overline{f}(v,e)).$$

Let us observe that $\overline{f}(v,e) = 0$ if and only if $f(v,e) = 0$ and $f^c(v,e) = 0$. Since $f^c$ is a filler we deduce from $f^c(v,e) = 0$ that $\pi_v(e) = 0$ implying $\pi_v(e) = e$ so that $(v,e) \in O$ and $\Phi_f(v,e) = 0$. Hence $\varphi^{-1}(v,e)$ is a zero of the section $f$. Consequently, a filled version still describes in local coordinates precisely the solution set of $f$ over the set $U$.

Assume again that $p : Y \rightarrow X$ is a fillable strong M-polyfold bundle and $f$ an sc-smooth section. Suppose that $\overline{f}$ is a filled version representing the section $f|U$ as a section of the bundle $\hat{O} \triangleleft F \rightarrow \hat{O}$. We will prove the following result.

**Proposition 4.17.** For a smooth point $q \in U$ corresponding to the point $(v,e) \in O$ the linearization $f^l_q(q) : T_qX \rightarrow Y_q$ is sc-Fredholm if and only if the linearization of the filled version $\overline{f}^l_q(v,e) : T_{(v,e)}\hat{O} \rightarrow F$ is sc-Fredholm. In this case the Fredholm indices are the same.

**Proof.** Without loss of generality we may assume that $f(q) = 0$ and $s = 0$. Using fillable strong bundle coordinates $\Phi : Y|U \rightarrow K^R$ covering $\varphi : U \rightarrow O$ we may assume without loss of generality that $f$ is a sc-smooth section of the bundle

$$p : K^R \rightarrow O$$

satisfying $0 \in O$ and $f(0) = 0$. Then $f$ has the form

$$O \rightarrow K^R : (v,e) \rightarrow ((v,e), \bar{f}(v,e)).$$

Using its principal part $\bar{f}$ we can define an sc-smooth map

$$f : \hat{O} \rightarrow F : (v,e) \rightarrow \bar{f}(v, \pi_v(e)),$$

which satisfies $\rho_{(v,\pi_v(e))}(f(v,e)) = f(v,e)$. The open subset $\hat{O}$ of $V \oplus E$ can be naturally identified with the splicing core $K^sS^c$, as we have seen in section 4.2. Since the strong bundle splicing $\mathcal{R}$ is fillable, we have the existence of a bundle isomorphism (linear in the fibers)

$$K^sS^c \rightarrow K^R(e)(0)$$

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over the set $O$ which gives us the sc-smooth filler

$$f^c : \hat{O} \to F$$

satisfying $\rho(v,\pi_v(e))f^c(v,e) = 0$. In addition, for fixed $(v,e) \in O$ the map $r \to f^c(v,e + r)$ is a linear isomorphism between the Banach spaces $\ker(\pi_v)$ and $\ker(\rho(v,e,v))$. Finally, the principal part of the locally filled section is the

$$\hat{f} : \hat{O} \to F : (v,e) \to f(v,e) + f^c(v,e).$$

Since $f(0,0) = 0$, the linearisation of the section $f$ of the bundle $K^R \to O$ at the point $(0,0) \in O$,

$$f'(0,0) : T_{(0,0)}O \to \ker(\rho(0,0)) = p^{-1}(0,0)$$

is equal to $Df(0,0)|T_{(0,0)}O$. We have to compare it to the linearisation $D\hat{f}(0,0) : W \oplus E \to F$. Here $W$ is the sc-Banach space containing the relatively open neighborhood $V$ of 0 in a partial quadrant $C \subset W$. According to the splitting $E = \pi_0(E) \oplus (1 - \pi_0)(E)$ we shall split $\delta e \in E$ into $\delta e = (\delta a, \delta b)$ and compute,

$$D\hat{f}(0,0)(\delta w, \delta e)$$

$$= Df(0,0)(\delta w, \delta a) + Df^c(0,0)(\delta w, \delta a)$$

$$= Df(0,0)(\delta w, \delta a) + Df(0,0)(0, \delta b) + Df^c(0,0)(\delta w, \delta a) + Df^c(0,0)(0, \delta b)$$

$$= Df(0,0)(\delta w, \delta a) + Df^c(0,0)(\delta w, \delta a) + Df^c(0,0)(0, \delta b)$$

$$=: f'(0,0)(\delta w, \delta a) + B(\delta w, \delta a) + C(\delta b).$$

We have concluded from the identity $f(v,e) = f(v,\pi_v(e))$ that

$$Df(0,0)(0, \delta b) = 0.$$

In addition, since for fixed $v$ the map $f^c(v,\pi_v(e)) + (1 - \pi_v)(e)$ is linear in $(1 - \pi_v)(e)$, we conclude that $Df^c(0,0)(0, \delta b) = f^c(0, \delta b)$. Since $(0,0) \in O$ is a smooth point, the map

$$C : \ker(\pi_0) \to \ker(\rho(0,0)) : \delta b \to f^c(0, \delta b)$$

is a linear sc-isomorphism, by the definition of a filler. The sc-operator $Df^c(0,0)$ defines a map

$$B : W \oplus \ker(\pi_0) \to \ker(\rho(0,0)).$$
Hence our total linear sc-operator $D\bar{f}(0,0)$ has the matrix form

$$\begin{pmatrix} (\delta w, \delta a) \\ \delta b \end{pmatrix} \rightarrow \begin{pmatrix} f'(0,0) & 0 \\ B & C \end{pmatrix} \cdot \begin{pmatrix} (\delta w, \delta a) \\ \delta b \end{pmatrix},$$

where $C$ is a sc-isomorphism and $B$ an sc-operator. An sc-operator of this form is sc-Fredholm if and only if the linearization $f'(0,0)$ is sc-Fredholm. In that case the Fredholm indices are the same. This completes the proof. ■

What we discussed in this paper is a minimal set of concepts needed to develop a Fredholm theory. The next paper will contain a treatment of implicit function theorems in the splicing context.

We refer the reader to the upcoming volume [8] for a more exhaustive list of splicing constructions and constructs.

References


